

Datasheet

APM32F405xG

APM32F407xExG

Arm® Cortex® -M4 core-based 32-bit MCU

Version: V1.2

1 Product Characteristics

■ Core

- 32-bit Arm® Cortex®-M4 core with FPU
- Up to 168MHz working frequency

■ Memory and interface

- Flash: The capacity is up to 1MB
- SRAM: System (192KB) + backup (4KB)
- EMMC: Support CF card, SRAM, PSRAM, SDRAM, NOR and NAND memories

■ Clock

- HSECLK: 4~26MHz external crystal/ceramic oscillator supported
- LSECLK: 32.768KHz crystal/ceramic oscillator supported
- HSICLK: 16MHz RC oscillator calibrated by factory
- LSICLK: 28KHz RC oscillator supported
- PLL1: Phase locked loop; output frequency is configured by four parameters
- PLL2: Phase locked loop specially used to provide clock signals to I2S; output frequency is configured by three parameters

■ Reset and power management

- V_{DD} range: 1.8~3.6V
- V_{DDA} range: 1.8~3.6V
- V_{BAT} range of backup domain power supply: 1.65V~3.6V
- Power-on/power-down/brown-out reset (POR/PDR/BOR) supported
- Programmable power supply voltage detector (PWD) supported

■ Low-power mode

- Sleep, stop and standby modes supported

■ DMA

- Two DMA; each DMA has 8 data streams, 16 in total

■ Debugging interface

- JTAG
- SWD

■ I/O

- Up to 140 I/O
- All I/O can be mapped to external interrupt vector
- Up to 138 FT input I/O

■ Communication peripherals

- 4 USART, 2 UART, supporting ISO7816, LIN and IrDA functions
- 3 I2C, supporting SMBus/PMBus
- 3 SPI (2 reusable I2S)
- 2 CAN
- 3 USB_OTG controllers
- 1 SDIO interface

■ Analog peripherals

- 3 12-bit ADCs
- 2 12-bit DACs

■ Timer

- 2 16-bit advanced timers TMR1/8 that can provide 7-channel PWM output, support dead zone generation and braking input functions
- 2 32-bit general-purpose timers TMR2/5, each with up to 4 independent channels to support input capture, output comparison, PWM, pulse count and other functions
- 8 16-bit general-purpose timers TMR3/4/9/10/11/12/13/14, each with up to 2 independent channels to support input capture, output comparison, PWM, pulse count and other functions
- 2 16-bit basic timers TMR6/7
- 2 watchdog timers: one independent watchdog IWDT and one window watchdog WWDT
- 1 24-bit autodecrement SysTick Timer

■ RTC

- Support calendar function
- Alarm and regular wake-up from stop/standby mode

■ CRC computing unit

■ 96-bit unique device ID

Contents

1	Product Characteristics	1
2	Product Information	6
3	Pin Information	7
3.1	Pin distribution	7
3.2	Pin function description	10
3.3	GPIO Multiplexing Function Configuration	28
4	Function Description	51
4.1	System architecture	52
4.1.1	System block diagram	52
4.1.2	Address mapping	53
4.1.3	Startup configuration	54
4.2	Core	54
4.3	Interrupt controller	54
4.3.1	Nested Vector Interrupt Controller (NVIC)	54
4.3.2	External Interrupt/Event Controller (EINT)	54
4.4	On-chip memory	54
4.4.1	Configurable external memory controller (EMMC)	55
4.4.2	LCD parallel interface (LCD)	55
4.5	Clock	55
4.5.1	Clock tree	55
4.5.2	Clock source	56
4.5.3	System clock	57
4.5.4	Bus clock	57
4.5.5	Phase locked loop	57
4.6	Power and power management	57
4.6.1	Power supply scheme	57
4.6.2	Voltage regulator	57
4.6.3	Power supply voltage monitor	58

4.7	Low-power mode	58
4.8	DMA.....	58
4.9	GPIO.....	59
4.10	Communication peripherals	59
4.10.1	USART/UART.....	59
4.10.2	I2C	59
4.10.3	SPI/I2S	60
4.10.4	CAN	60
4.10.5	USB_OTG	60
4.10.6	Ethernet	60
4.10.7	SDIO	60
4.11	Analog peripherals	61
4.11.1	ADC	61
4.11.2	DAC	61
4.12	Timer.....	61
4.13	RTC	63
4.13.1	Backup domain.....	63
4.14	RNG.....	63
4.15	DCI.....	63
4.16	CRC	64
5	Electrical Characteristics	64
5.1	Test conditions of electrical characteristics	64
5.1.1	Maximum and minimum values.....	64
5.1.2	Typical value.....	64
5.1.3	Typical curve.....	64
5.1.4	Power supply scheme	65
5.1.5	Load capacitance	66
5.2	Test under general operating conditions	66
5.3	Absolute maximum ratings	67
5.3.1	Maximum temperature characteristics	67

5.3.2 Maximum rated voltage characteristics.....	67
5.3.3 Maximum rated current characteristics	67
5.3.4 Electro-static discharge (ESD).....	68
5.3.5 Static latch-up (LU).....	68
5.4 On-chip memory.....	68
5.4.1 Flash characteristics.....	68
5.5 Clock.....	69
5.5.1 Characteristics of external clock source	69
5.5.2 Characteristics of internal clock source	70
5.5.3 PLL Characteristics	71
5.6 Reset and power management.....	71
5.6.1 Test of Embedded Reset and Power Control Module Characteristics.....	71
5.7 Power consumption.....	73
5.7.1 Power consumption test environment.....	73
5.7.2 Power consumption in run mode.....	74
5.7.3 Power consumption in sleep mode	77
5.7.4 Power consumption in stop mode	78
5.7.5 Power consumption in standby mode	78
5.7.6 Peripheral power consumption.....	79
5.7.7 Backup Domain Power Consumption	81
5.8 Wake-up time in low-power mode.....	81
5.9 I/O port characteristics	82
5.10 NRST pin characteristics.....	84
5.11 Communication peripherals	85
5.11.1 I2C peripheral characteristics.....	85
5.11.2 SPI peripheral characteristics	86
5.12 Analog peripherals	88
5.12.1 ADC	88
5.12.2 DAC	89
6 Package Information.....	91

6.1	LQFP176 package information	91
6.2	LQFP144 package information	93
6.3	LQFP100 package information	96
6.4	LQFP64 package information	99
7	Packaging Information.....	102
7.1	Reel packaging.....	102
7.2	Tray packaging	103
8	Ordering Information	105
9	Commonly Used Function Module Denomination.....	106
10	Version History	107

2 Product Information

See the following table for APM32F405xG 407xExG product functions and peripheral configuration.

Table 1 Functions and Peripherals of APM32F405xG 407xExG Series Chips

Product		APM32F407								APM32F405																
Model		RET6	RGT6	VET6	VGT6	ZET6	ZGT6	IET6	IGT6	RGT6	VGT6	ZGT6														
Package		LQFP64		LQFP100		LQFP144		LQFP176		LQFP64	LQFP100	LQFP144														
Core and maximum working frequency		Arm® 32-bit Cortex®-M4@168MHz																								
Working voltage		1.8~3.6V																								
Flash(KB)		512	1024	512	1024	512	1024	512	1024	1024																
System + backup SRAM(KB)		192+4																								
SMC		0		1				0		1																
DMC		0				1		0																		
GPIOs		51		82		114		140		51	82	114														
Communication interface	USART/UART	4/2																								
	SPI/I2S	3/2																								
	I2C	3																								
	OTG_FS	1																								
	OTG_HS	2																								
	CAN	2																								
	Ethernet	0	1				0				0															
	SDIO	1																								
Timer	16-bit advanced	2																								
	32-bit general	2																								
	16-bit general	8																								
	16-bit basic	2																								
	System tick timer	1																								
	Watchdog	2																								
Real-time clock		1																								
DCI		0	1				0				0															
RNG		1																								
12-bit ADC	Unit	3																								
	External channel	13			21			13		21																
	Internal channel	3																								
12 位 DAC	Unit	2																								
	Channel	2																								
Operating temperature		Ambient temperature: -40°C to 85°C Junction temperature: -40°C to 105°C																								

3 Pin Information

3.1 Pin distribution

Figure 1 Distribution Diagram of APM32F407xExG Series LQFP176 Pins

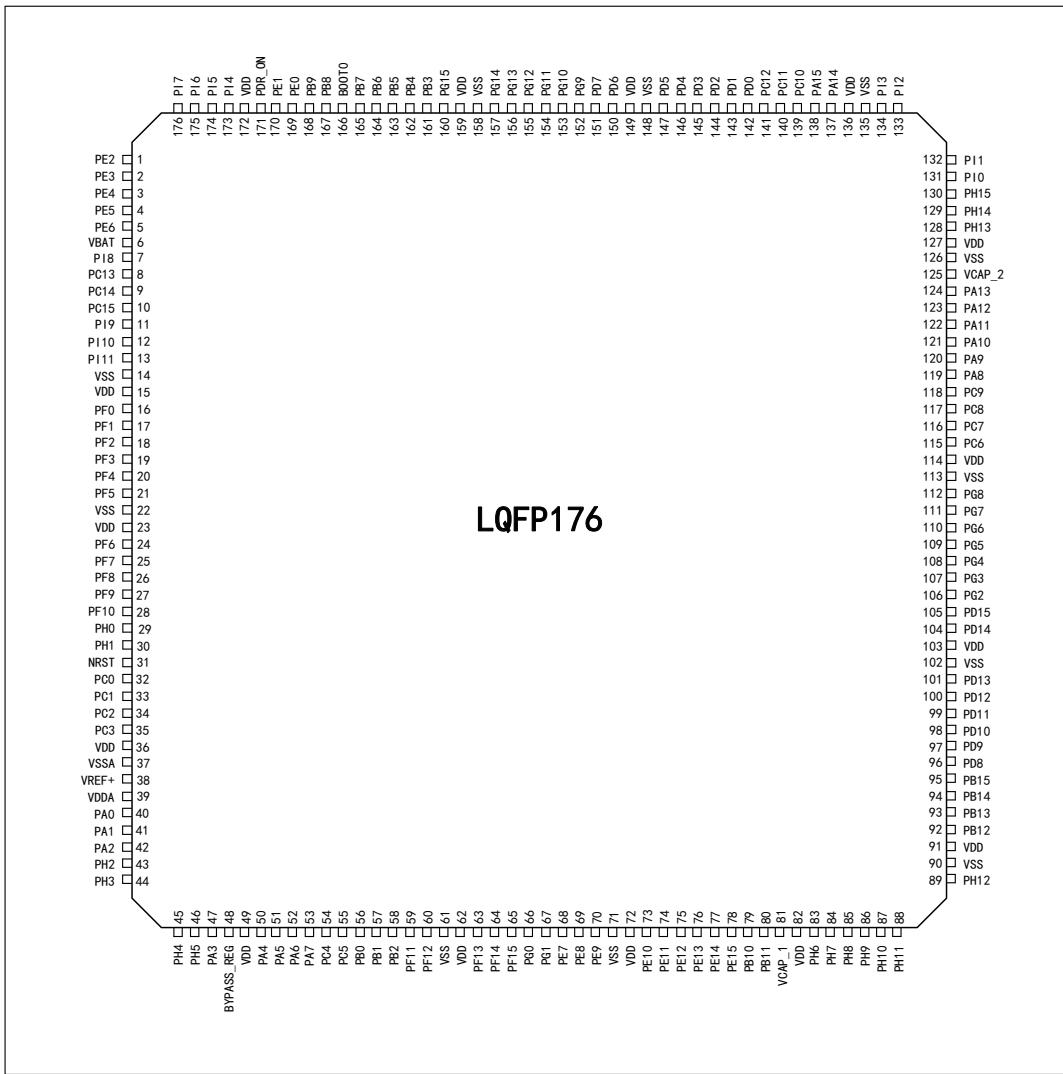


Figure 2 Distribution Diagram of APM32F405xG 407xExG Series LQFP144 Pins

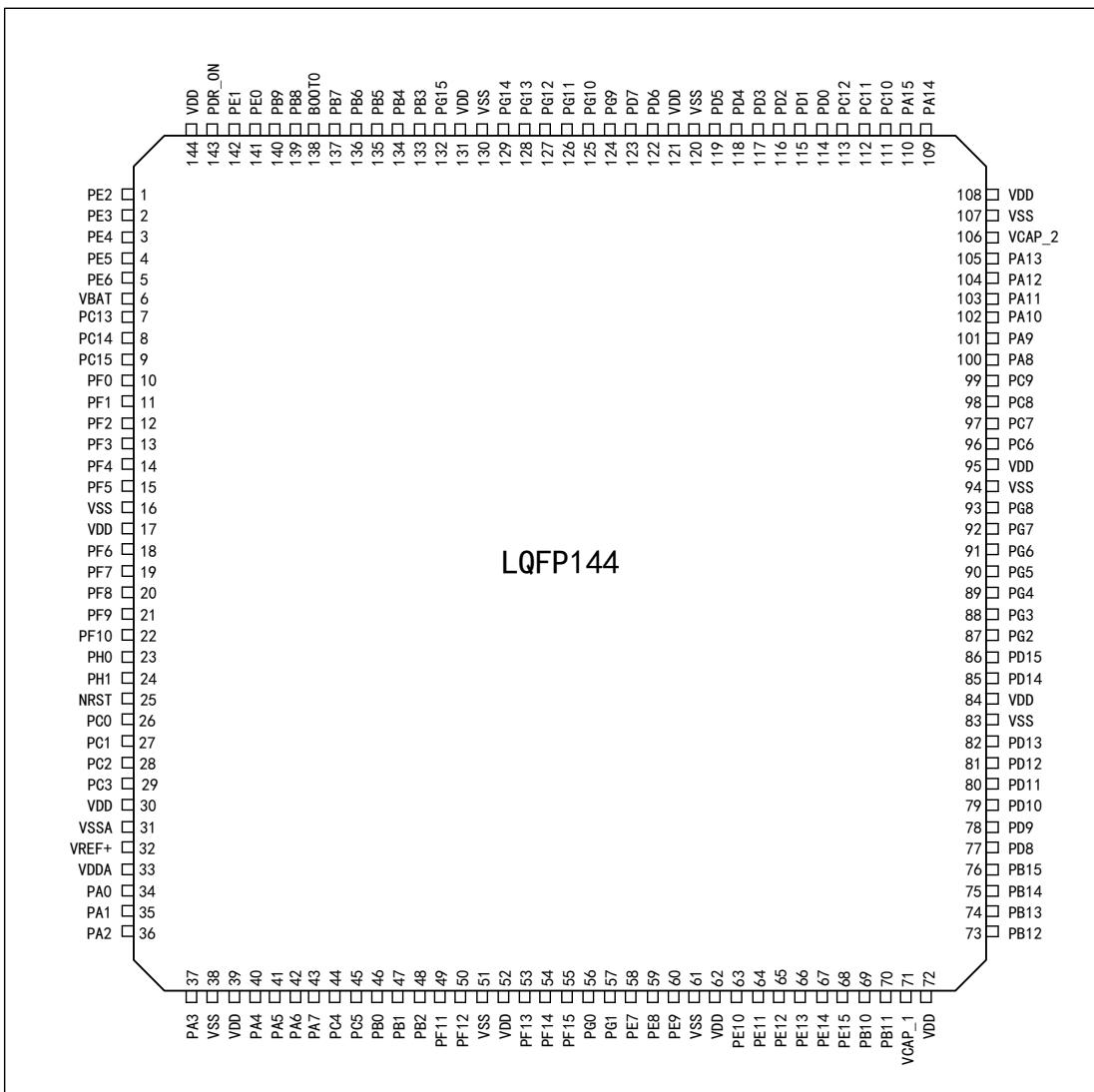


Figure 3 Distribution Diagram of APM32F405xG 407xExG Series LQFP100 Pins

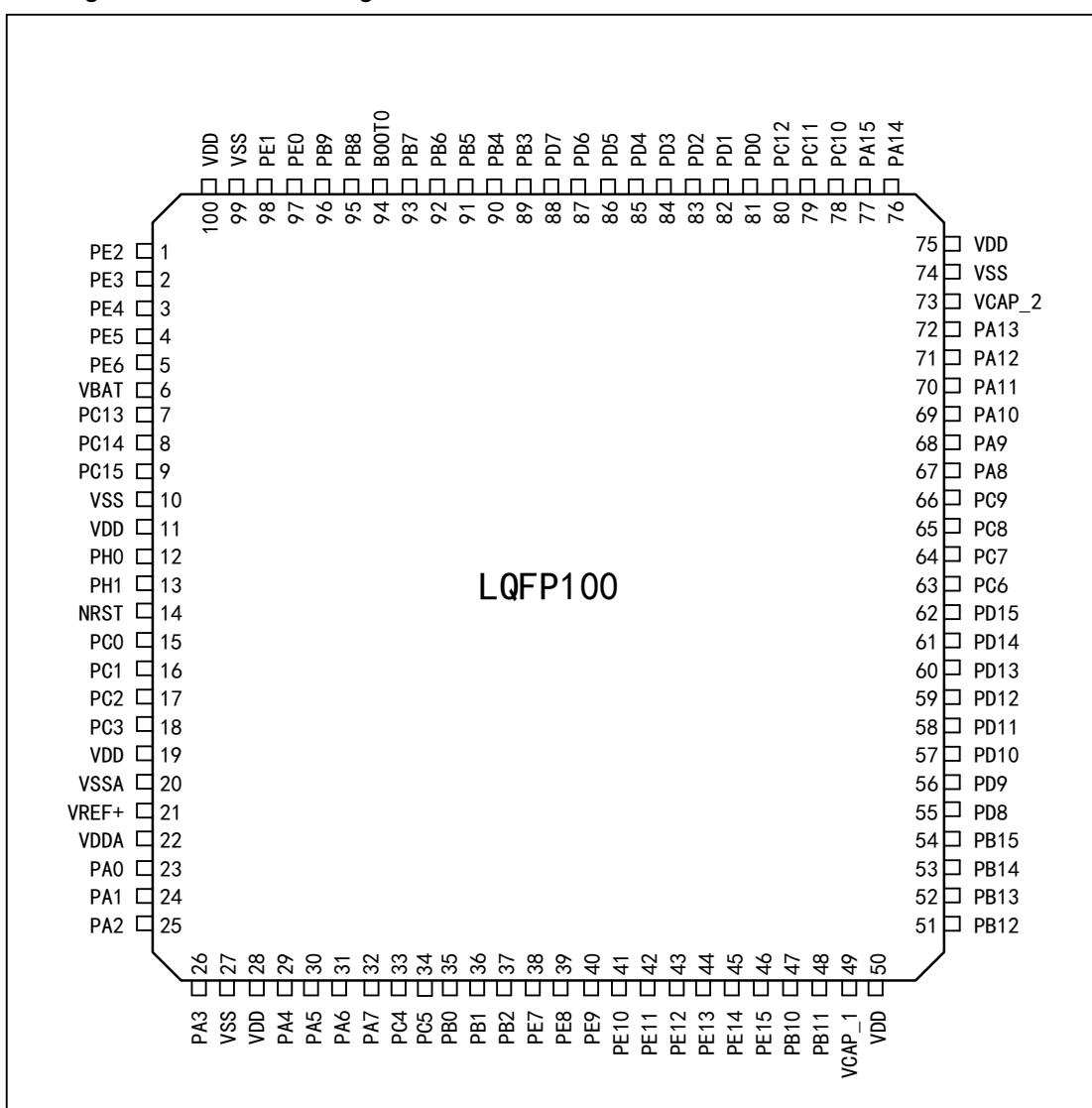
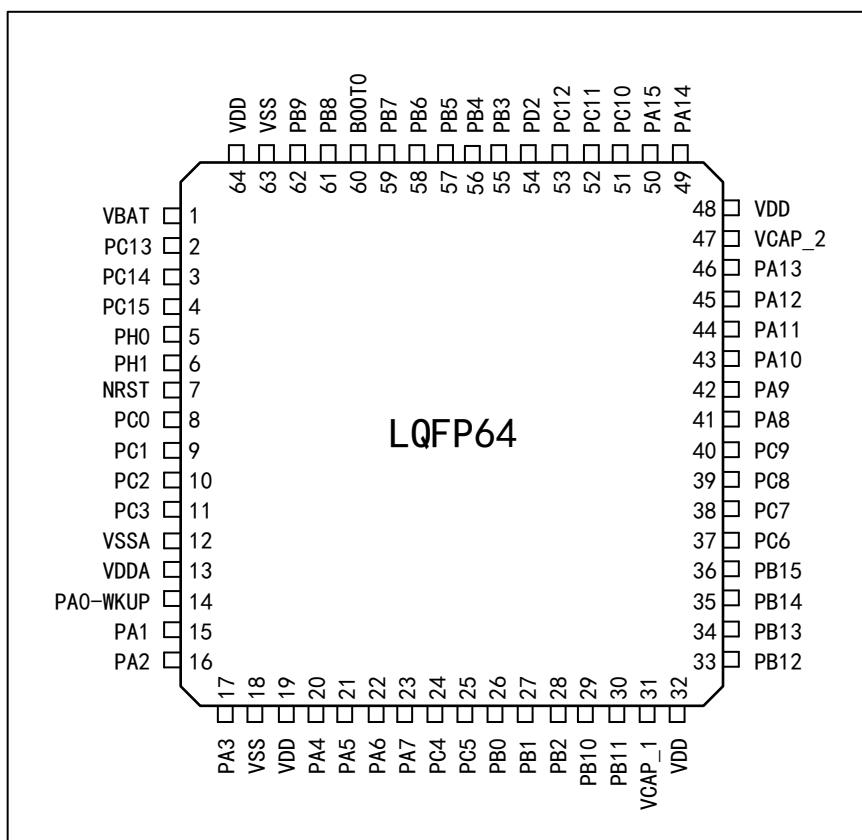


Figure 4 Distribution Diagram of APM32F405xG 407xExG Series LQFP64 Pins



3.2 Pin function description

Table 2 Legends/Abbreviations Used in Output Pin Table

Name	Abbreviation	Definition
Pin name	Unless otherwise specified in parentheses below the pin name, the pin functions during and after reset are the same as the actual pin name	
Pin type	P	Power pin
	I	Only input pin
	I/O	I/O pin
I/O structure	5T	FT I/O
	STDA	3.3V standard I/O, directly connected to ADC
	STD	3.3V standard I/O
	B	Dedicated Boot0 pin
	RST	Bidirectional reset pin with built-in pull-up resistor
Notes	Unless otherwise specified in the notes, all I/O is set as floating input during and after reset	
Pin function	Default multiplexing function	Function directly selected/enabled through peripheral register

Name		Abbreviation	Definition			
	Redefining function		Select this function through AFIO remapping register			

Table 3 Description of APM32F405xG 407xEExG by Pin Number

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
PE2	I/O	5T	TRACECK, SMC_A23, ETH_MII_TXD3, EVENTOUT	-	-	1	1	1
PE3	I/O	5T	TRACED0, SMC_A19, EVENTOUT	-	-	2	2	2
PE4	I/O	5T	TRACED1, SMC_A20, DCI_D4, EVENTOUT	-	-	3	3	3
PE5	I/O	5T	TRACED2, SMC_A21, TMR9_CH1, DCI_D6, EVENTOUT	-	-	4	4	4
PE6	I/O	5T	TRACED3, SMC_A22, TMR9_CH2, DCI_D7, EVENTOUT	-	-	5	5	5
VBAT	P	-	-	-	1	6	6	6
PI8	I/O	5T	EVENTOUT, DMC_CAS	RTC_TAMP1, RTC_TAMP2, RTC_TS	-	-	-	7
PC13	I/O	5T	EVENTOUT	RTC_OUT, RTC_TAMP1, RTC_TS	2	7	7	8
PC14- OSC32_IN (PC14)	I/O	5T	EVENTOUT	OSC32_IN	3	8	8	9
PC15- OSC32_OUT (PC15)	I/O	5T	EVENTOUT	OSC32_OUT	4	9	9	10
PI9	I/O	5T	CAN1_RX, EVENTOUT, DMC_RAS	-	-	-	-	11
PI10	I/O	5T	ETH_MII_RX_ER,	-	-	-	-	12

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			EVENTOUT, DMC_CS					
PI11	I/O	5T	OTG_HS_ULPI_DIR, EVENTOUT, DMC_BA	-	-	-	-	13
VSS	P	-	-	-	-	-	-	14
VDD	P	-	-	-	-	-	-	15
PF0	I/O	5T	SMC_A0, DMC_A10, I2C2_SDA, EVENTOUT	-	-	-	10	16
PF1	I/O	5T	SMC_A1, DMC_A0, I2C2_SCL, EVENTOUT	-	-	-	11	17
PF2	I/O	5T	SMC_A2, DMC_A1, I2C2_SMBAI, EVENTOUT	-	-	-	12	18
PF3	I/O	5T	SMC_A3, DMC_A2, EVENTOUT	ADC3_IN9	-	-	13	19
PF4	I/O	5T	SMC_A4, DMC_A3, EVENTOUT	ADC3_IN14	-	-	14	20
PF5	I/O	5T	SMC_A5, EVENTOUT	ADC3_IN15	-	-	15	21
VSS	P	-	-	-	-	10	16	22
VDD	P	-	-	-	-	11	17	23
PF6	I/O	5T	TMR10_CH1, SMC_NIORD, DMC_A4, EVENTOUT	ADC3_IN4	-	-	18	24
PF7	I/O	5T	TMR11_CH1, SMC_NREG, DMC_A5, EVENTOUT	ADC3_IN5	-	-	19	25
PF8	I/O	5T	TMR13_CH1, SMC_NIOWR,	ADC3_IN6	-	-	20	26

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			DMC_A6, EVENTOUT					
PF9	I/O	5T	TMR14_CH1, SMC_CD, DMC_A7 EVENTOUT	ADC3_IN7	-	-	21	27
PF10	I/O	5T	SMC_INTR, DMC_A8 EVENTOUT	ADC3_IN8	-	-	22	28
PH0-OSC_IN (PH0)	I/O	5T	EVENTOUT	OSC_IN	5	12	23	29
PH1-OSC_OUT (PH1)	I/O	5T	EVENTOUT	OSC_OUT	6	13	24	30
NRST	I/O	RST	-	-	7	14	25	31
PC0	I/O	5T	OTG_HS_ULPI_STP, EVENTOUT	ADC123_IN10	8	15	26	32
PC1	I/O	5T	ETH_MDC, EVENTOUT	ADC123_IN11	9	16	27	33
PC2	I/O	5T	SPI2_MISO, OTG_HS_ULPI_DIR, ETH_MII_TXD2, I2S2ext_SD, EVENTOUT	ADC123_IN12	10	17	28	34
PC3	I/O	5T	SPI2_MOSI, I2S2_SD, OTG_HS_ULPI_NXT, ETH_MII_TX_CLK, EVENTOUT	ADC123_IN13	11	18	29	35
VDD	P	-	-	-	-	19	30	36
VSSA	P	-	-	-	12	20	31	37
VREF+	P	-	-	-	-	21	32	38
VDDA	P	-	-	-	13	22	33	39
PA0-WKUP (PA0)	I/O	5T	USART2_CTS, UART4_TX, ETH_MII_CRS, TMR2_CH1_ETR, TMR5_CH1, TMR8_ETR, EVENTOUT	WKUP, ADC123_IN0	14	23	34	40

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
PA1	I/O	5T	USART2_RTS, UART4_RX, ETH_RMII_REF_CLK, ETH_MII_RX_CLK, TMR5_CH2, TMR2_CH2, EVENTOUT	ADC123_IN1	15	24	35	41
PA2	I/O	5T	USART2_TX, TMR5_CH3, TMR9_CH1, TMR2_CH3, ETH_MDIO, EVENTOUT	ADC123_IN2	16	25	36	42
PH2	I/O	5T	ETH_MII_CRS, EVENTOUT	-	-	-	-	43
PH3	I/O	5T	ETH_MII_COL, EVENTOUT, DMC_A9	-	-	-	-	44
PH4	I/O	5T	I2C2_SCL, OTG_HS_ULPI_NXT, EVENTOUT	-	-	-	-	45
PH5	I/O	5T	I2C2_SDA, EVENTOUT	-	-	-	-	46
PA3	I/O	5T	USART2_RX, TMR5_CH4, TMR9_CH2, TMR2_CH4, OTG_HS_ULPI_D0, ETH_MII_COL, EVENTOUT, DMC_CKE	ADC123_IN3	17	26	37	47
VSS	P	-	-	-	18	27	38	-
BYPASS_REG	I	5T	-	-	-	-	-	48
VDD	P	-	-	-	19	28	39	49
PA4	I/O	STDA	SPI1_NSS, SPI3_NSS, USART2_CK, DCI_HSYNC, OTG_HS_SOF, I2S3_WS,	DAC_OUT1, ADC12_IN4	20	29	40	50

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			EVENTOUT					
PA5	I/O	STDA	SPI1_SCK, OTG_HS_ULPI_CK, TMR2_CH1_ETR, TMR8_CH1N, EVENTOUT	DAC_OUT2, ADC12_IN5	21	30	41	51
PA6	I/O	5T	SPI1_MISO, TMR8_BKIN, TMR13_CH1, DCI_PIXCLK, TMR3_CH1, TMR1_BKIN, EVENTOUT	ADC12_IN6	22	31	42	52
PA7	I/O	5T	SPI1_MOSI, TMR8_CH1N, TMR14_CH1, TMR3_CH2, ETH_MII_RX_DV, TMR1_CH1N, ETH_RMII_CRS_DV, EVENTOUT	ADC12_IN7	23	32	43	53
PC4	I/O	5T	ETH_RMII_RX_D0, ETH_MII_RX_D0, EVENTOUT	ADC12_IN14	24	33	44	54
PC5	I/O	5T	ETH_RMII_RX_D1, ETH_MII_RX_D1, EVENTOUT	ADC12_IN15	25	34	45	55
PB0	I/O	5T	TMR3_CH3 TMR8_CH2N, OTG_HS_ULPI_D1, ETH_MII_RXD2, TMR1_CH2N, EVENTOUT	ADC12_IN8	26	35	46	56
PB1	I/O	5T	TMR3_CH4 TMR8_CH3N, OTG_HS_ULPI_D2, ETH_MII_RXD3, TMR1_CH3N, EVENTOUT	ADC12_IN9	27	36	47	57
PB2-BOOT	I/O	5T	EVENTOUT	-	28	37	48	58

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
(PB2)								
PF11	I/O	5T	DCI_D12, EVENTOUT, DMC_UDQM	-	-	-	49	59
PF12	I/O	5T	SMC_A6, EVENTOUT	-	-	-	50	60
VSS	P	-	-	-	-	-	51	61
VDD	P	-	-	-	-	-	52	62
PF13	I/O	5T	SMC_A7, EVENTOUT	-	-	-	53	63
PF14	I/O	5T	SMC_A8, EVENTOUT	-	-	-	54	64
PF15	I/O	5T	SMC_A9, EVENTOUT	-	-	-	55	65
PG0	I/O	5T	SMC_A10, EVENTOUT	-	-	-	56	66
PG1	I/O	5T	SMC_A11, DMC_CK, EVENTOUT	-	-	-	57	67
PE7	I/O	5T	SMC_D4, TMR1_ETR, EVENTOUT	-	-	38	58	68
PE8	I/O	5T	SMC_D5, TMR1_CH1N, EVENTOUT	-	-	39	59	69
PE9	I/O	5T	SMC_D6, TMR1_CH1, EVENTOUT	-	-	40	60	70
VSS	P	-	-	-	-	-	61	71
VDD	P	-	-	-	-	-	62	72
PE10	I/O	5T	SMC_D7, TMR1_CH2N, EVENTOUT	-	-	41	63	73
PE11	I/O	5T	SMC_D8, TMR1_CH2, EVENTOUT	-	-	42	64	74
PE12	I/O	5T	SMC_D9, TMR1_CH3N, EVENTOUT	-	-	43	65	75

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
PE13	I/O	5T	SMC_D10, TMR1_CH3, EVENTOUT	-	-	44	66	76
PE14	I/O	5T	SMC_D11, TMR1_CH4, EVENTOUT	-	-	45	67	77
PE15	I/O	5T	SMC_D12, TMR1_BKIN, EVENTOUT	-	-	46	68	78
PB10	I/O	5T	SPI2_SCK, I2S2_CK, I2C2_SCL, USART3_TX, OTG_HS_ULPI_D3, ETH_MII_RX_ER, TMR2_CH3, EVENTOUT	-	29	47	69	79
PB11	I/O	5T	I2C2_SDA, USART3_RX, OTG_HS_ULPI_D4, ETH_RMII_TX_EN, ETH_MII_TX_EN, TMR2_CH4, EVENTOUT	-	30	48	70	80
VCAP_1	P	-	-	-	31	49	71	81
VDD	P	-	-	-	32	50	72	82
PH6	I/O	5T	I2C2_SMBAI, TMR12_CH1, ETH_MII_RXD2, EVENTOUT	-	-	-	-	83
PH7	I/O	5T	I2C3_SCL, ETH_MII_RXD3, EVENTOUT	-	-	-	-	84
PH8	I/O	5T	I2C3_SDA, DCI_HSYNC, EVENTOUT, DMC_DQ8	-	-	-	-	85
PH9	I/O	5T	I2C3_SMBAI, TMR12_CH2, DCI_D0,	-	-	-	-	86

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			EVENTOUT					
PH10	I/O	5T	TMR5_CH1, DCI_D1, EVENTOUT, DMC_DQ9	-	-	-	-	87
PH11	I/O	5T	TMR5_CH2, DCI_D2, EVENTOUT	-	-	-	-	88
PH12	I/O	5T	TMR5_CH3, DCI_D3, EVENTOUT	-	-	-	-	89
VSS	P	-	-	-	-	-	-	90
VDD	P	-	-	-	-	-	-	91
PB12	I/O	5T	SPI2_NSS, I2S2_WS, I2C2_SMBAI, USART3_CK, TMR1_BKIN, CAN2_RX, OTG_HS_ULPI_D5, ETH_RMII_TXD0, ETH_MII_TXD0, OTG_HS_ID, EVENTOUT	-	33	51	73	92
PB13	I/O	5T	SPI2_SCK, I2S2_CK, USART3_CTS, TMR1_CH1N, CAN2_TX, OTG_HS_ULPI_D6, ETH_RMII_TXD1, ETH_MII_TXD1, EVENTOUT	OTG_HS_VBUS	34	52	74	93
PB14	I/O	5T	SPI2_MISO, TMR1_CH2N, TMR12_CH1, OTG_HS_DM, USART3_RTS, TMR8_CH2N, I2S2ext_SD,	-	35	53	75	94

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			EVENTOUT					
PB15	I/O	5T	SPI2_MOSI, I2S2_SD, TMR1_CH3N, TMR8_CH3N TMR12_CH2, OTG_HS_DP, EVENTOUT	RTC_REFIN	36	54	76	95
PD8	I/O	5T	SMC_D13, USART3_TX, EVENTOUT	-	-	55	77	96
PD9	I/O	5T	SMC_D14, USART3_RX, EVENTOUT	-	-	56	78	97
PD10	I/O	5T	SMC_D15, DMC_DQ10 USART3_CK, EVENTOUT	-	-	57	79	98
PD11	I/O	5T	SMC_CLE, SMC_A16, USART3_CTS, EVENTOUT	-	-	58	80	99
PD12	I/O	5T	SMC_ALE, SMC_A17, DMC_DQ11, TMR4_CH1, USART3_RTS, EVENTOUT	-	-	59	81	100
PD13	I/O	5T	SMC_A18, DMC_DQ12 TMR4_CH2, EVENTOUT	-	-	60	82	101
VSS	P	-	-	-	-	-	83	102
VDD	P	-	-	-	-	-	84	103
PD14	I/O	5T	SMC_D0, DMC_DQ13, TMR4_CH3, EVENTOUT	-	-	61	85	104
PD15	I/O	5T	SMC_D1,	-	-	62	86	105

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			DMC_DQ14, TMR4_CH4, EVENTOUT					
PG2	I/O	5T	SMC_A12, DMC_DQ15, EVENTOUT	-	-	-	87	106
PG3	I/O	5T	SMC_A13, DMC_DQ0, EVENTOUT	-	-	-	88	107
PG4	I/O	5T	SMC_A14, DMC_DQ1, EVENTOUT	-	-	-	89	108
PG5	I/O	5T	SMC_A15, DMC_DQ2, EVENTOUT	-	-	-	90	109
PG6	I/O	5T	SMC_INT2, DMC_DQ3 EVENTOUT	-	-	-	91	110
PG7	I/O	5T	SMC_INT3, USART6_CK, EVENTOUT	-	-	-	92	111
PG8	I/O	5T	DMC_DQ4 USART6_RTS, ETH_PPS_OUT, EVENTOUT	-	-	-	93	112
VSS	P	-	-	-	-	-	94	113
VDD	P	-	-	-	-	-	95	114
PC6	I/O	5T	I2S2_MCK, TMR8_CH1, SDIO_D6, USART6_TX, DCI_D0, TMR3_CH1, EVENTOUT	-	37	63	96	115
PC7	I/O	5T	I2S3_MCK, TMR8_CH2, SDIO_D7, USART6_RX, DCI_D1, TMR3_CH2,	-	38	64	97	116

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			EVENTOUT					
PC8	I/O	5T	TMR8_CH3, SDIO_D0, TMR3_CH3, USART6_CK, DCI_D2, EVENTOUT	-	39	65	98	117
PC9	I/O	5T	I2S_CKIN, MCO2, TMR8_CH4, SDIO_D1, I2C3_SDA, DCI_D3, TMR3_CH4, EVENTOUT	-	40	66	99	118
PA8	I/O	5T	USART1_CK, TMR1_CH1, MCO, I2C3_SCL, OTG_FS_SOF, EVENTOUT	-	41	67	100	119
PA9	I/O	5T	USART1_TX, TMR1_CH2, I2C3_SMBAI, DCI_D0, EVENTOUT	OTG_FS_VBUS	42	68	101	120
PA10	I/O	5T	USART1_RX, TMR1_CH3, OTG_FS_ID, DCI_D1, EVENTOUT	-	43	69	102	121
PA11	I/O	5T	USART1_CTS, CAN1_RX, TMR1_CH4, OTG_FS_DM, EVENTOUT	-	44	70	103	122
PA12	I/O	5T	USART1_RTS, CAN1_TX, TMR1_ETR, OTG_FS_DP,	-	45	71	104	123

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			EVENTOUT					
PA13 (JTMS-SWDIO)	I/O	5T	JTMS-SWDIO, EVENTOUT	PA13	46	72	105	124
VCAP_2	P	-	-	-	47	73	106	125
VSS	P	-	-	-	-	74	107	126
VDD	P	-	-	-	48	75	108	127
PH13	I/O	5T	TMR8_CH1N, CAN1_TX, EVENTOUT, DMC_DQ5	-	-	-	-	128
PH14	I/O	5T	TMR8_CH2N, DCI_D4, EVENTOUT	-	-	-	-	129
PH15	I/O	5T	TMR8_CH3N, DCI_D11, EVENTOUT, DMC_DQ6	-	-	-	-	130
PI0	I/O	5T	TMR5_CH4, SPI2 NSS, I2S2_WS, DCI_D13, EVENTOUT	-	-	-	-	131
PI1	I/O	5T	SPI2_SCK, I2S2_CK, DCI_D8, EVENTOUT	-	-	-	-	132
PI2	I/O	5T	TMR8_CH4, SPI2_MISO, DCI_D9, I2S2ext_SD, EVENTOUT	-	-	-	-	133
PI3	I/O	5T	TMR8_ETR, SPI2_MOSI, I2S2_SD, DCI_D10, EVENTOUT, DMC_DQ7	-	-	-	-	134
VSS	P	-	-	-	-	-	-	135
VDD	P	-	-	-	-	-	-	136

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
PA14 (JTCK/SWCLK)	I/O	5T	JTCK-SWCLK, EVENTOUT	-	49	76	109	137
PA15 (JTDI)	I/O	5T	JTDI, SPI3_NSS, I2S3_WS, TMR2_CH1_ETR, SPI1_NSS, EVENTOUT	-	50	77	110	138
PC10	I/O	5T	SPI3_SCK, I2S3_CK, UART4_TX, SDIO_D2, DCI_D8, USART3_TX, EVENTOUT	-	51	78	111	139
PC11	I/O	5T	UART4_RX, SPI3_MISO, SDIO_D3, DCI_D4, USART3_RX, I2S3ext_SD, EVENTOUT	-	52	79	112	140
PC12	I/O	5T	UART5_TX, SDIO_CK, DCI_D9, SPI3_MOSI, I2S3_SD, USART3_CK, EVENTOUT	-	53	80	113	141
PD0	I/O	5T	SMC_D2, CAN1_RX, EVENTOUT	-	-	81	114	142
PD1	I/O	5T	SMC_D3, CAN1_TX, EVENTOUT	-	-	82	115	143
PD2	I/O	5T	TMR3_ETR, UART5_RX, SDIO_CMD, DCI_D11, EVENTOUT	-	54	83	116	144

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
PD3	I/O	5T	SMC_CLK, USART2_CTS, EVENTOUT	-	-	84	117	145
PD4	I/O	5T	SMC_NOE, USART2_RTS, EVENTOUT	-	-	85	118	146
PD5	I/O	5T	SMC_NWE, USART2_TX, EVENTOUT	-	-	86	119	147
VSS	P	-	-	-	-	-	120	148
VDD	P	-	-	-	-	-	121	149
PD6	I/O	5T	SMC_NWAIT, USART2_RX, EVENTOUT	-	-	87	122	150
PD7	I/O	5T	SMC_NE1, SMC_NCE2, USART2_CK, EVENTOUT	-	-	88	123	151
PG9	I/O	5T	SMC_NE2, SMC_NCE3, USART6_RX, EVENTOUT	-	-	-	124	152
PG10	I/O	5T	SMC_NCE4_1, SMC_NE3, EVENTOUT	-	-	-	125	153
PG11	I/O	5T	SMC_NCE4_2, ETH_MII_TX_EN, ETH_RMII_TX_EN, EVENTOUT	-	-	-	126	154
PG12	I/O	5T	SMC_NE4, USART6_RTS, EVENTOUT	-	-	-	127	155
PG13	I/O	5T	SMC_A24, USART6_CTS, ETH_MII_TXD0, ETH_RMII_TXD0, EVENTOUT	-	-	-	128	156
PG14	I/O	5T	SMC_A25, USART6_TX, ETH_MII_TXD1,	-	-	-	129	157

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			ETH_RMII_TXD1, EVENTOUT					
VSS	P	-	-	-	-	-	130	158
VDD	P	-	-	-	-	-	131	159
PG15	I/O	5T	DMC_LDQM, USART6_CTS, DCI_D13, EVENTOUT	-	-	-	132	160
PB3 (JTDO/TRACESWO)	I/O	5T	JTDO, TRACESWO, SPI3_SCK, I2S3_CK, TMR2_CH2, SPI1_SCK, EVENTOUT	-	55	89	133	161
PB4 (NJTRST)	I/O	5T	NJTRST, SPI3_MISO, TMR3_CH1, SPI1_MISO, I2S3ext_SD, EVENTOUT	-	56	90	134	162
PB5	I/O	-	I2C1_SMBAI, CAN2_RX, OTG_HS_ULPI_D7, ETH_PPS_OUT, TMR3_CH2, SPI1_MOSI, SPI3_MOSI, DCI_D10, I2S3_SD, EVENTOUT	-	57	91	135	163
PB6	I/O	5T	I2C1_SCL, TMR4_CH1, CAN2_TX, DCI_D5, USART1_TX, EVENTOUT	-	58	92	136	164
PB7	I/O	5T	I2C1_SDA, SMC_NL, DCI_VSYNC,	-	59	93	137	165

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			USART1_RX, TMR4_CH2, EVENTOUT					
BOOT0	I	B	-	VPP	60	94	138	166
PB8	I/O	5T	TMR4_CH3, SDIO_D4, TMR10_CH1, DCI_D6, ETH_MII_TXD3, I2C1_SCL, CAN1_RX, EVENTOUT	-	61	95	139	167
PB9	I/O	5T	SPI2_NSS, I2S2_WS, TMR4_CH4, TMR11_CH1, SDIO_D5, DCI_D7, I2C1_SDA, CAN1_TX, EVENTOUT	-	62	96	140	168
PE0	I/O	5T	TMR4_ETR, SMC_NBL0, DCI_D2, EVENTOUT	-	-	97	141	169
PE1	I/O	5T	SMC_NBL1, DCI_D3, EVENTOUT	-	-	98	142	170
VSS	P	-	-	-	63	99	-	-
PDR_ON	I	5T	-	-	-	-	143	171
VDD	P	-	-	-	64	100	144	172
PI4	I/O	5T	TMR8_BKIN, DCI_D5, EVENTOUT	-	-	-	-	173
PI5	I/O	5T	TMR8_CH1, DCI_VSYNC, EVENTOUT	-	-	-	-	174
PI6	I/O	5T	TMR8_CH2, DCI_D6,	-	-	-	-	175

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			EVENTOUT					
PI7	I/O	5T	TMR8_CH3, DCI_D7, EVENTOUT, DMC_WE	-	-	-	-	176

Note:

(1) PC13, PC14 and PC15 are powered through the power switch. Since the switch only sinks limited current (3mA), the use of GPIO from PC13 to PC15 in output mode is limited:

- ① The speed shall not exceed 2MHz when the heavy load is 30pF;
- ② Not used for current source (e.g. driving LED).

3.3 GPIO Multiplexing Function Configuration

Table 4 GPIOA Multiplexing Function Configuration

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	A	F	AF1
		SYS	TMR1/2	TMR3/4/5	TMR8/9/10/11	I2C1/2/3	SPI1/SPI2/I2S2/I2S2 ext	SPI3/I2S3 ext	USART1/I2S3	UART4/5/USART T6	CAN1/2T MR12/13 /14	OTG_FS/OTG_HS	ETH	SMC/DMC/SDIO/OTG_FS	DCI	1	4	5
Port_A	P A 0	-	TMR2_CH1_E TR	TMR5_C H1	TMR8_ETR	-	-	-	USART2_CTS	UART4_TX	-	-	ETH_MII_CRS	-	-	-	EVE NTO UT	
	P A 1	-	TMR2_CH2	TMR5_C H2	-	-	-	-	USART2_RTS	UART4_RX	-	-	ETH_MII_RX_CLK	-	-	-	EVE NTO UT	
	P A 2	-	TMR2_CH3	TMR5_C H3	TMR9_CH1	-	-	-	USART2_TX	-	-	-	ETH_MDIO	-	-	-	EVE NTO UT	
	P A 3	-	TMR2_CH4	TMR5_C H4	TMR9_CH2	-	-	-	USART2_RX	-	-	OTG_HS_ULPI_D0	ETH_MII_COL	DMC_CKE	-	-	EVE NTO UT	
	P A 4	-	-	-	-	-	SPI1_NSS	SPI3_I2S3_WS	USART2_CK	-	-	-	OTG_HS_SOF	DCI_HSY_NC	-	-	EVE NTO UT	

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	A	
	SYS	TMR1/ 2	TMR 3/4/5	TMR8 /9/10/ 11	I2C1/ 2/3	SPI1/SPI2 ext	SPI3/I2 Sext/I2	USART1 ext	UART4/ 5/USAR	CAN1/2T MR12/13	OTG_F S/OTG_ HS	ETH	SMC/DMC/ SDIO/OTG _FS	DCI	F 1 4	AF1 5
P A 5	-	TMR2_ CH1_E TR		TMR8 _CH1 N	-	SPI1_SC K	-	-	-		OTG_H S_ULPI _CK	-	-	-	-	EVE NTO UT
P A 6	-	TMR1_ BKIN	TMR 3_C H1	TMR8 _BKI N	-	SPI1_MIS O	-	-	-	TMR13_ CH1	-	-	-	DCI_ PIXC K	-	EVE NTO UT
P A 7	-	TMR1_ CH1N	TMR 3_C H2	TMR8 _CH1 N	-	SPI1_MO SI	-	-	-	TMR14_ CH1	-	ETH_MII _RX_DV ETH_RM II CRS _DV	-	-	-	EVE NTO UT
P A 8	MCO1	TMR1_ CH1	-	-	I2C3 _SC L	-	-	USART1 _CK	-	-	OTG_F S_SOF	-	-	-	-	EVE NTO UT
P A 9	-	TMR1_ CH2	-	-	I2C3 _SM BA	-	-	USART1 _TX	-	-	-	-	-	DCL D0	-	EVE NTO UT
P A 10	-	TMR1_ CH3	-	-	-	-	-	USART1 _RX	-	-	OTG_F S_ID	-	-	DCI D1	-	EVE NTO UT
P A 11	-	TMR1_ CH4	-	-	-	-	-	USART1 _CTS	-	CAN1_R X	OTG_F S_DM	-	-	-	-	EVE NTO UT

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	A	
	SYS	TMR1/ 2	TMR 3/4/5	TMR8 /9/10/ 11	I2C1/ 2/3	SPI1/SPI2 ext	SPI3/I2 Sext/I2	USART1 ext	UART4/ 5/USAR ext	CAN1/2T MR12/13 T6	OTG_F S/OTG_ HS	ETH	SMC/DMC/ SDIO/OTG _FS	DCI	F 1 4	AF1 5
P A 1 2	-	TMR1_ ETR	-	-	-	-	-	USART1 _RTS	-	CAN1_T X	OTG_F S_DP	-	-	-	-	EVE NTO UT
P A 1 3	JTMS _SWD IO	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVE NTO UT
P A 1 4	JTCK _SWC LK	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVE NTO UT
P A 1 5	JTDI	TMR2_ CH1 TMR2_ ETR	-	-	-	SPI1_NS S	SPI3_ NSS I2C3_ WS	-	-	-	-	-	-	-	-	EVE NTO UT

Table 5 GPIOB Multiplexing Function Configuration

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF 13	A F 1 4	AF15
		SYS	TMR1 /2	TMR 3/4/5	TMR8 /9/10/ 11	I2C1/ 2/3	SPI1/SPI2 /I2S2/I2S2 ext	SPI3/I2 Sext/I2 S3	USART1/ 2/3/I2S3e xt	UART4/ 5/USAR T6	CAN1/2T MR12/13/ 14	OTG_F S/OTG_ HS	ETH	SMC/DMC/ SDIO/OTG _FS	DC I		
Port_B	P B 0	-	TMR1 _CH2 N	TMR 3_C H3	TMR8 _CH2 N	-	-	-	-	-	-	OTG_H S_ULPI _D1	ETH_M II_RXD 2	-	-	-	EVE NTO UT
	P B 1	-	TMR1 _CH3 N	TMR 3_C H4	TMR8 _CH3 N	-	-	-	-	-	-	OTG_HS _ULPI_D 2	ETH_MII _RXD3	-	-	-	EVE NTO UT
	P B 2	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVE NTO UT
	P B 3	JTDO/T RACES WO	TMR2 _CH2	-	-	-	SPI1_SCK	SPI3_S CK I2S3_C K	-	-	-	-	-	-	-	-	EVE NTO UT
	P B 4	NJTRST	-	TMR 3_C H1	-	SPI1 _MIS O	SPI3_MIS O	I2S3ext _SD	-	-	-	-	-	-	-	-	EVE NTO UT
	P B 5	-	-	TMR 3_C H2	I2C1_ SMBA	SPI1 _MO SI	SPI3_MO SII2S3_S D	-	CAN2_R X	OTG_H S_ULPI _D7	ETH_PP S_OUT	-	DCI_D 10	-	-	-	EVE NTO UT
	P B 6	-	-	TMR 4_C H1	I2C1_ SCL	-	-	USART 1_TX	-	CAN2_T X	-	-	-	DCI_D5	-	-	EVE NTO UT

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	A F 1 4	AF15
	SYS	TMR1 /2	TMR 3/4/5	TMR8 /9/10/ 11	I2C1/ 2/3	SPI1/SPI2 /I2S2/I2S2 ext	SPI3/I2 Sext/I2 S3	USART1/ 2/3/I2S3e xt	UART4/ 5/USAR T6	CAN1/2T MR12/13/ 14	OTG_F S/OTG_ HS	ETH	SMC/DMC/ SDIO/OTG _FS	DC I		
P B 7	-	-	TMR 4_C H2	I2C1_ SDA	-	-	USART 1_RX	-	-	-	-	SMC_N L	DCI_VSYN C	-	-	EVE NTO UT
P B 8	-	-	TMR 4_C H3	TMR1 0_CH 1	I2C1 _SC L	-	-	-	-	CAN1_R X	-	ETH_M II_TXD 3	SDIO_D4	DC I_D 6	-	EVE NTO UT
P B 9	-	-	TMR 4_C H4	TMR1 1_CH 1	I2C1 _SD A	SPI2_NSS I2S2_WS	-	-	-	CAN1_T X	-	-	SDIO_D5	DC I_D 7	-	EVE NTO UT
P B 10	-	TMR2 _CH3	-	-	I2C2 _SC L	SPI2_SCK I2S2_CK	-	USART3 _TX	-	-	OTG_H S_ULPI _D3	ETH_M II_RX_ ER	-	-	-	EVE NTO UT
P B 11	-	TMR2 _CH4	-	-	I2C2 _SD A	-	-	USART3 _RX	-	-	OTG_H S_ULPI _D4	ETH_M II_TX_ EN ETH _RMII_ TX_EN	-	-	-	EVE NTO UT
P B 12	-	TMR1 _BKIN	-	-	I2C2 _SM BA	SPI2_NSS I2S2_WS	-	USART3 _CK	-	CAN2_R X	OTG_H S_ULPI _D5	ETH_R MII_TX D0	OTG_HS_I D	-	-	EVE NTO UT

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	A F 1 4	AF15
	SYS	TMR1 /2	TMR 3/4/5	TMR8 /9/10/ 11	I2C1/ 2/3	SPI1/SPI2 /I2S2/I2S2 ext	SPI3/I2 Sext/I2	USART1/ 2/3/I2S3e	UART4/ 5/USAR	CAN1/2T MR12/13/	OTG_F S/OTG_	ETH	SMC/DMC/ SDIO/OTG _FS	DC I		
													ETH_M II_TXD 0			
P B 1 3	-	TMR1 _CH1 N	-	-	-	SPI2_SCK I2S2_CK	-	USART3 _CTS	-	CAN2_T X	OTG_H S_ULPI _D6	ETH_R MII_TX D1 ETH_M II_TXD 1	-	-	-	EVE NTO UT
P B 1 4	-	TMR1 _CH2 N	-	TMR8 _CH2 N	-	SPI2_MIS O	I2S2ext _SD	USART3 _RTS	-	TMR12_ CH1	-	-	OTG_HS_ DM	-	-	EVE NTO UT
P B 1 5	RTC_R EFIN	TMR1 _CH3 N	-	TMR8 _CH3 N	-	SPI2_MO SII2S2_S D	-	-	-	TMR12_ CH2	-	-	OTG_HS_ DP	-	-	EVE NTO UT

Table 6 GPIOC Multiplexing Function Configuration

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	A	
		SY S	TM R1/ 2	TMR 3/4/5	TMR8/ 9/10/1	I2C1 /2/3	SPI1/SPI2/I 2S2/I2S2ex t	SPI3/I2 Sext/I2 S3	USART1/ 2/3/I2S3e xt	UART4/ 5/USAR T6	CAN1/2T MR12/13/ 14	OTG_FS /OTG_H S	ETH	SMC/DMC/S DIO/OTG_F S	DCI	F1 4	AF15
Port_C	P C 0	-	-	-	-	-	-	-	-	-	-	OTG_HS _ULPI_ STP	-	-	-	-	EVE NTO UT
	P C 1	-	-	-	-	-	-	-	-	-	-	ETH_M DC	-	-	-	-	EVE NTO UT
	P C 2	-	-	-	-	-	SPI2_MIS O	I2S2ext _SD	-	-	-	OTG_HS _ULPI_ DIR	ETH_MI _TXD2	-	-	-	EVE NTO UT
	P C 3	-	-	-	-	-	SPI2_MOS I I2S2_SD	-	-	-	-	OTG_HS _ULPI_ NXT	ETH _MII_TX _CLK	-	-	-	EVE NTO UT
	P C 4	-	-	-	-	-	-	-	-	-	-	ETH_MI _RXD0	ETH_R _MII_RX D0	-	-	-	EVE NTO UT
	P C 5	-	-	-	-	-	-	-	-	-	-	ETH_MI _RXD1	ETH_R _MII_RX D1	-	-	-	EVE NTO UT

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	A	
	SY S	TM R1/2	TMR 3/4/5	TMR8/9/10/1	I2C1 /2/3	SPI1/SPI2/I 2S2/I2S2ext	SPI3/I2 Sext/I2 S3	USART1/ 2/3/I2S3e xt	UART4/ 5/USART T6	CAN1/2T MR12/13/ 14	OTG_FS /OTG_H S	ETH	SMC/DMC/S DIO/OTG_F S	DCI	F1 4	AF15
P C 6	-	-	TMR3_CH1	TMR8_CH1	-	I2S2_MCK	-	-	USART6_TX	-	-	-	SDIO_D6	DCI_D0	-	EVE NTO UT
P C 7	-	-	TMR3_CH2	TMR8_CH2	-	-	I2S3_M CK	-	USART6_RX	-	-	-	SDIO_D7	DCI_D1	-	EVE NTO UT
P C 8	-	-	TMR3_CH3	TMR8_CH3	-	-	-	-	USART6_CK	-	-	-	SDIO_D0	DCI_D2	-	EVE NTO UT
P C 9 O2	M C	-	TMR3_CH4	TMR8_SD_A	I2C3	I2S_CKIN	-	-	-	-	-	-	SDIO_D1	DCI_D3	-	EVE NTO UT
P C 10	-	-	-	-	-	-	SPI3_S CK/I2S3_C K	USART3_TX/	UART4_TX	-	-	-	SDIO_D2	DCI_D8	-	EVE NTO UT
P C 11	-	-	-	-	-	I2S3ext_S D	SPI3_M ISO/	USART3_RX	UART4_RX	-	-	-	SDIO_D3	DCI_D4	-	EVE NTO UT
P C 12	-	-	-	-	-	-	SPI3_M OSI I2S3_S D	USART3_CK	UART5_TX	-	-	-	SDIO_CK	DCI_D9	-	EVE NTO UT

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	A	
	SY S	TM R1/2	TMR 3/4/5	TMR8/9/10/1	I2C1 /2/3	SPI1/SPI2/I 2S2/I2S2ext	SPI3/I2 Sext/I2 S3	USART1/2/3/I2S3ext	UART4/5/USART6	CAN1/2T MR12/13/14	OTG_FS /OTG_HS	ETH S	SMC/DMC/S DIO/OTG_F S	DCI	F1 4	AF15
P C 13	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVE NTO UT
P C 14	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVE NTO UT
P C 15	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVE NTO UT

Table 7 GPIOD Multiplexing Function Configuration

Port	A F 0	AF 1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	A F1 1	AF12	AF1 3	A	
	S Y S	TM R1/2	TMR3 /4/5	TMR8/ 9/10/11	I2C 1/2/3	SPI1/SPI2/I 2S2/I2S2ext	SPI3/I2S ext/I2S3	USART1/2 /3/I2S3ext	UART4/5 /USART6	CAN1/2TM R12/13/14	OTG_FS /OTG_HS	E T H	SMC/DMC/S DIO/OTG_FS	DCI	F1 4	AF15
Por t_D	P D0	-	-	-	-	-	-	-	-	CAN1_RX	-	-	SMC_D2	-	-	EVEN TOUT
	P D1	-	-	-	-	-	-	-	-	CAN1_TX	-	-	SMC_D3	-	-	EVEN TOUT

Port	A F 0	AF 1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	A F1 1	AF12	AF1 3	A F1 4	AF15
	S Y S	T M R1/ 2	TMR3	TMR8/ 9/10/11	I2C 1/2/ 3	SPI1/SPI2/I 2S2/I2S2ext	SPI3/I2S ext/I2S3	USART1/2 /3/I2S3ext	USART4/5 /USART6	CAN1/2TM R12/13/14	OTG_FS/ OTG_HS	E T H	SMC/DMC/S DIO/OTG_FS	DCI		
P D2	-	-	TMR3 _ETR	-	-	-	-	-	UART5_ RX	-	-	-	SDIO_CMD	DCI _D1 1	-	EVEN TOUT
P D3	-	-	-	-	-	-	-	USART2_ CTS	-	-	-	-	SMC_CLK	-	-	EVEN TOUT
P D4	-	-	-	-	-	-	-	USART2_ RTS	-	-	-	-	SMC_NOE	-	-	EVEN TOUT
P D5	-	-	-	-	-	-	-	USART2_ TX	-	-	-	-	SMC_NWE	-	-	EVEN TOUT
P D6	-	-	-	-	-	-	-	USART2_ RX	-	-	-	-	SMC_NWAIT	-	-	EVEN TOUT
P D7	-	-	-	-	-	-	-	USART2_ CK	-	-	-	-	SMC_NE1/S MC_NCE2	-	-	EVEN TOUT
P D8	-	-	-	-	-	-	-	USART3_ TX	-	-	-	-	SMC_D13	-	-	EVEN TOUT
P D9	-	-	-	-	-	-	-	USART3_ RX	-	-	-	-	SMC_D14	-	-	EVEN TOUT

Port	A F 0	AF 1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	A F1 1	AF12	AF1 3	A F1 4	AF15
	S Y S	T M R1/ I4/5	TMR3	TMR8/ 9/10/11	I2C 1/2/ 3	SPI1/SPI2/I 2S2/I2S2ext	SPI3/I2S ext/I2S3	USART1/2 /3/I2S3ext	UART4/5 /USART6	CAN1/2TM R12/13/14	OTG_FS/ OTG_HS	E T H	SMC/DMC/S DIO/OTG_FS	DCI		
P D1 0	-	-	-	-	-	-	-	USART3_ CK	-	-	-	-	SMC_D15 DMC_DQ10	-	-	EVEN TOUT
P D1 1	-	-	-	-	-	-	-	USART3_ CTS	-	-	-	-	SMC_A16	-	-	EVEN TOUT
P D1 2	-	-	TMR4 _CH1	-	-	-	-	USART3_ RTS	-	-	-	-	SMC_A17 DMC_DQ11	-	-	EVEN TOUT
P D1 3	-	-	TMR4 _CH2	-	-	-	-	-	-	-	-	-	SMC_A18 DMC_DQ12	-	-	EVEN TOUT
P D1 4	-	-	TMR4 _CH3	-	-	-	-	-	-	-	-	-	SMC_D0 DMC_DQ13	-	-	EVEN TOUT
P D1 5	-	-	TMR4 _CH4	-	-	-	-	-	-	-	-	-	SMC_D1 DMC_DQ14	-	-	EVEN TO

Table 8 GPIOE Multiplexing Function Configuration

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	A	
		SYS	TMR1/2	TMR3/4/5	TMR9/10/11	I2C3	SPI1/SPI2/I2S2/I2S2e	SPI3/I2Sxt	USART1/2/3/I2S3e	UART4/T6	CAN1/2T/14	OTG_FS/OTG_HS	ETH	SMC/DMC/SDIO/OTG_FS	DCI	F14	AF15
Port_E	P_E_0	-	-	TMR4_ETR	-	-	-	-	-	-	-	-	-	SMC_NBL0	DC_I_D_2	-	EVE_NTO_UT
	P_E_1	-	-	-	-	-	-	-	-	-	-	-	-	SMC_NBL1	DC_I_D_3	-	EVE_NTO_UT
	P_E_2	TRA_CEC_LK	-	-	-	-	-	-	-	-	-	-	ETH_MII_TX_D3	SMC_A23	-	-	EVE_NTO_UT
	P_E_3	TRA_CED_0	-	-	-	-	-	-	-	-	-	-	-	SMC_A19	-	-	EVE_NTO_UT
	P_E_4	TRA_CED_1	-	-	-	-	-	-	-	-	-	-	-	SMC_A20	DC_I_D_4	-	EVE_NTO_UT
	P_E_5	TRA_CED_2	-	-	TMR9_CH1	-	-	-	-	-	-	-	-	SMC_A21	DC_I_D_6	-	EVE_NTO_UT
	P_E_6	TRA_CED_3	-	-	TMR9_CH2	-	-	-	-	-	-	-	-	SMC_A22	DC_I_D_7	-	EVE_NTO_UT

Port	AF0	AF1	AF2	AF3	AF 4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF 13	A	
	SYS	TMR1 /2	TMR 3/4/5	TMR8/ 9/10/1	I2C 1/2/ 1	SPI1/SPI2/ I2S2/I2S2e	SPI3/I2 Sext/I2	USART1/ 2/3/I2S3e	UART4/ 5/USAR	CAN1/2T MR12/13/	OTG_FS /OTG_H	ETH	SMC/DMC/ SDIO/OTG_	FS	DC I	F1 4
P E 7	-	TMR1 _ETR	-	-	-	-	-	-	-	-	-	-	SMC_D4	-	-	EVE NTO UT
P E 8	-	TMR1 _CH1 N	-	-	-	-	-	-	-	-	-	-	SMC_D5	-	-	EVE NTO UT
P E 9	-	TMR1 _CH1	-	-	-	-	-	-	-	-	-	-	SMC_D6	-	-	EVE NTO UT
P E 10	-	TMR1 _CH2 N	-	-	-	-	-	-	-	-	-	-	SMC_D7	-	-	EVE NTO UT
P E 11	-	TMR1 _CH2	-	-	-	-	-	-	-	-	-	-	SMC_D8	-	-	EVE NTO UT
P E 12	-	TMR1 _CH3 N	-	-	-	-	-	-	-	-	-	-	SMC_D9	-	-	EVE NTO UT
P E 13	-	TMR1 _CH3	-	-	-	-	-	-	-	-	-	-	SMC_D10	-	-	EVE NTO UT
P E 14	-	TMR1 _CH4	-	-	-	-	-	-	-	-	-	-	SMC_D11	-	-	EVE NTO UT

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	A	
	SYS	TMR1 /2	TMR 3/4/5	TMR8/ 9/10/1	I2C 1/2/1	SPI1/SPI2/ I2S2/I2S2e	SPI3/I2 Sext/I2	USART1/ 2/3/I2S3e	UART4/ 5/USART	CAN1/2T MR12/13/1	OTG_FS /OTG_H S	ETH	SMC/DMC/ SDIO/OTG_ FS	DCI	F14	AF15
P E 15	-	TMR1 _BKI N	-	-	-	-	-	-	-	-	-	-	SMC_D12	-	-	EVE NTO

Table 9 GPIOF Multiplexing Function Configuration

Port	A F 0	AF 1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	A F1 1	AF12	AF1 3	A F1 4	
	S Y S	TM R1/ 2	TMR 3/4/5	TMR8/ 9/10/1	I2C1/ 2/3	SPI1/SPI2/I 2S2/I2S2ext	SPI3/I2S ext/I2S3	USART1/2 /3/I2S3ext	UART4/5 /USART6	CAN1/2T MR12/13/1	OTG_FS/ OTG_HS	E T H	SMC/DMC/S DIO/OTG_FS	DCI	F14	AF15
Port_F	P F0	-	-	-	-	I2C2_ SDA	-	-	-	-	-	-	SMC_A0	-	-	EVEN TOUT
	P F1	-	-	-	-	I2C2_ SCL	-	-	-	-	-	-	SMC_A1	-	-	EVEN TOUT
	P F2	-	-	-	-	I2C2_ SMBA	-	-	-	-	-	-	SMC_A2	-	-	EVEN TOUT
	P F3	-	-	-	-	-	-	-	-	-	-	-	SMC_A3	-	-	EVEN TOUT
	P F4	-	-	-	-	-	-	-	-	-	-	-	SMC_A4	-	-	EVEN TOUT
	P F5	-	-	-	-	-	-	-	-	-	-	-	SMC_A5	-	-	EVEN TOUT

Port	A F 0	AF 1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	A F1 1	AF12	AF1 3	A F1 4	AF15
	S Y S	TM R1/ 2	TMR 3/4/5	TMR8/ 9/10/1 1	I2C1/ 2/3	SPI1/SPI2/I 2S2/I2S2ext	SPI3/I2S ext/I2S3	USART1/2 /3/I2S3ext	UART4/5 /USART6	CAN1/2T MR12/13/1 4	OTG_FS/ OTG_HS	E T H	SMC/DMC/S DIO/OTG_FS	DCI		
P F6	-	-	-	TMR1 0_CH1	-	-	-	-	-	-	-	-	SMC_NIORD DMC_A4	-	-	EVEN TOUT
P F7	-	-	-	TMR11 _CH1	-	-	-	-	-	-	-	-	SMC_NREG DMC_A5	-	-	EVEN TOUT
P F8	-	-	-	-	-	-	-	-	-	TMR13_C H1	-	-	SMC_NIOW R DMC_A6	-	-	EVEN TOUT
P F9	-	-	-	-	-	-	-	-	-	TMR14_C H1	-	-	SMC_CD DMC_A7	-	-	EVEN TOUT
P F1 0	-	-	-	-	-	-	-	-	-	-	-	-	SMC_INTR DMC_A8	-	-	EVEN TOUT
P F1 1	-	-	-	-	-	-	-	-	-	-	-	-	DMC_UDQM	DCI _D1 2	-	EVEN TOUT
P F1 2	-	-	-	-	-	-	-	-	-	-	-	-	SMC_A6	-	-	EVEN TOUT
P F1 3	-	-	-	-	-	-	-	-	-	-	-	-	SMC_A7	-	-	EVEN TOUT

Port	A F 0	AF 1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	A F1 1	AF12	AF1 3	A F1 4	AF15
	S Y S	TM R1/ 2	TMR 3/4/5	TMR8/ 9/10/1	I2C1/ 2/3	SPI1/SPI2/I 2S2/I2S2ext	SPI3/I2S ext/I2S3	USART1/2 /3/I2S3ext	UART4/5 /USART6	CAN1/2T MR12/13/1 4	OTG_FS/ OTG_HS	E T H	SMC/DMC/S DIO/OTG_FS	DCI		
P F1 4	-	-	-	-	-	-	-	-	-	-	-	-	SMC_A8	-	-	EVEN TOUT
P F1 5	-	-	-	-	-	-	-	-	-	-	-	-	SMC_A9	-	-	EVEN TOUT

Table 10 GPIOG Multiplexing Function Configuration

Port	A F 0	AF 1	AF2	AF3	AF 4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF1 3	A F1 4	AF15
	S Y S	TM R1/ 2	TMR 3/4/ 5	TMR8/ 9/10/1	I2C 1/2/ 3	SPI1/SPI2/I 2S2/I2S2ex	SPI3/I2 Sext/I2	USART1/ 2/3/I2S3e	USART xt	UART4/5 /USART	CAN1/2T MR12/13/ 6	OTG_FS /OTG_H	ETH	SMC/DMC/S DIO/OTG_F	DCI	
Port_G_0	P G 0	-	-	-	-	-	-	-	-	-	-	-	SMC_A10	-	-	EVE NTO UT
Port_G_1	P G 1	-	-	-	-	-	-	-	-	-	-	-	SMC_A11 DMC_CK	-	-	EVE NTO UT

Port	A F 0	AF 1	AF2	AF3	AF 4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF1 3	A F1 4	AF15
	S Y S	TM R1/ 2	TMR 3/4/ 5	TMR8/ 9/10/1 1	I2C 1/2/ 3	SPI1/SPI2/I 2S2/I2S2ex t	SPI3/I2 Sext/I2 S3	USART1/ 2/3/I2S3e xt	UART4/5 /USART 6	CAN1/2T MR12/13/ 14	OTG_FS /OTG_H S	ETH	SMC/DMC/S DIO/OTG_F S	DCI		
P G 2	-	-	-	-	-	-	-	-	-	-	-	-	SMC_A12 DMC_DQ15	-	-	EVE NTO UT
P G 3	-	-	-	-	-	-	-	-	-	-	-	-	SMC_A13 DMC_DQ0	-	-	EVE NTO UT
P G 4	-	-	-	-	-	-	-	-	-	-	-	-	SMC_A14 DMC_DQ1	-	-	EVE NTO UT
P G 5	-	-	-	-	-	-	-	-	-	-	-	-	SMC_A15 DMC_DQ2	-	-	EVE NTO UT
P G 6	-	-	-	-	-	-	-	-	-	-	-	-	SMC_INT2 DMC_DQ3	-	-	EVE NTO UT
P G 7	-	-	-	-	-	-	-	-	USART6 _CK	-	-	-	SMC_INT3	-	-	EVE NTO UT
P G 8	-	-	-	-	-	-	-	-	USART6 _RTS	-	-	ETH_PP S_OUT	DMC_DQ4	-	-	EVE NTO UT

Port	A F 0	AF 1	AF2	AF3	AF 4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF1 3	A F1 4	AF15
	S Y S	TM R1/ 2	TMR 3/4/ 5	TMR8/ 9/10/1 1	I2C 1/2/ 3	SPI1/SPI2/I 2S2/I2S2ex t	SPI3/I2 Sext/I2 S3	USART1/ 2/3/I2S3e xt	UART4/5 /USART 6	CAN1/2T MR12/13/ 14	OTG_FS /OTG_H S	ETH	SMC/DMC/S DIO/OTG_F S	DCI		
P G 9	-	-	-	-	-	-	-	-	USART6 _RX	-	-	-	SMC_NE2/S MC_NCE3	-	-	EVE NTO UT
P G 10	-	-	-	-	-	-	-	-	-	-	-	-	SMC_NCE4 _1/SMC_NE 3	-	-	EVE NTO UT
P G 11	-	-	-	-	-	-	-	-	-	-	-	-	ETH_MII _TX_EN ETH_RM II_TX_E N	SMC_NCE4 _2	-	EVE NTO UT
P G 12	-	-	-	-	-	-	-	-	USART6 _RTS	-	-	-	SMC_NE4	-	-	EVE NTO UT
P G 13	-	-	-	-	-	-	-	-	USART6 _CTS	-	-	-	ETH_MII _TXD0 ETH_RM II_TXD0	SMC_A24	-	EVE NTO UT
P G 14	-	-	-	-	-	-	-	-	USART6 _TX	-	-	-	ETH_MII _TXD1 ETH_RM II_TXD1	SMC_A25	-	EVE NTO UT

Port		A F 0	AF 1	AF2	AF3	AF 4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF1 3	A F1 4	AF15
		S Y S	TM R1/ 2	TMR 3/4	TMR8/ 9/10/1	I2C 1/2/ 3	SPI1/SPI2/I 2S2/I2S2ex t	SPI3/I2 Sext/I2 S3	USART1/ 2/3/I2S3e xt	UART4/5 /USART 6	CAN1/2T MR12/13/ 14	OTG_FS /OTG_H S	ETH	SMC/DMC/S DIO/OTG_F S	DCI		
P G 15	-	-	-	-	-	-	-	-	-	USART6 _CTS	-	-	-	DMC_LDQM	DCI _D1 3	-	EVE NTO UT

Table 11 GPIOH Multiplexing Function Configuration

Port		A F 0	AF 1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	A F1 4	AF15
		S Y S	TM R1/ 2	TMR 3/4/5	TMR8/ 9/10/1	I2C1/ 2/3	SPI1/SPI2/ I2S2/I2S2e xt	SPI3/I2 Sext/I2 S3	USART1/ 2/3/I2S3e xt	UART4/ 5/USAR T6	CAN1/2T MR12/13/ 14	OTG_FS/ OTG_HS	ETH	SMC/DMC/ SDIO/OTG_ FS	DCI		
Po rt_H	P H 0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVE NTO UT	
	P H 1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVE NTO UT	
	P H 2	-	-	-	-	-	-	-	-	-	-	-	ETH_M II_CRS	-	-	EVE NTO UT	

Port	A F 0	AF 1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	A F1 4	AF15
	S Y S	TM R1/ 2	TMR 3/4/5	TMR8/ 9/10/1	I2C1/ 2/3	SPI1/SPI2/ I2S2/I2S2e	SPI3/I2 Sext/I2	USART1/ 2/3/I2S3e	UART4/ 5/USAR	CAN1/2T MR12/13/ 14	OTG_FS/ OTG_HS	ETH	SMC/DMC/ SDIO/OTG_	FS	DCI	
P H 3	-	-	-	-	-	-	-	-	-	-	-	ETH_M II_COL	DMC_A9	-	-	EVE NTO UT
P H 4	-	-	-	-	I2C2 _SCL	-	-	-	-	-	OTG_HS _ULPI_N XT	-	-	-	-	EVE NTO UT
P H 5	-	-	-	-	I2C2 _SDA	-	-	-	-	-	-	-	-	-	-	EVE NTO UT
P H 6	-	-	-	-	I2C2 _SM BA	-	-	-	-	TMR12_C H1	-	ETH_M II_RXD 2	-	-	-	EVE NTO UT
P H 7	-	-	-	-	I2C3 _SCL	-	-	-	-	-	-	ETH_M II_RXD 3	-	-	-	EVE NTO UT
P H 8	-	-	-	-	I2C3 _SDA	-	-	-	-	-	-	-	DMC_DQ8	DCI_ HSY NC	-	EVE NTO UT
P H 9	-	-	-	-	I2C3 _SM BA	-	-	-	-	TMR12_C H2	-	-	-	DCI_ D0	-	EVE NTO UT

Port	A F 0	AF 1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	A F1 4	AF15	
	S Y S	TM R1/ 2	TMR 3/4/5	TMR8/ 9/10/1	I2C1/ 2/3	SPI1/SPI2/ I2S2/I2S2e	SPI3/I2 Sext/I2	USART1/ 2/3/I2S3e	UART4/ 5/USAR	CAN1/2T MR12/13/ 14	OTG_FS/ OTG_HS	ETH	SMC/DMC/ SDIO/OTG_	FS	DCI		
P H 10	-	-	TMR 5_C H1	-	-	-	-	-	-	-	-	-	-	DMC_DQ9	DCI_D1	-	EVE NTO UT
P H 11	-	-	TMR 5_C H2	-	-	-	-	-	-	-	-	-	-	-	DCI_D2	-	EVE NTO UT
P H 12	-	-	TMR 5_C H3	-	-	-	-	-	-	-	-	-	-	-	DCI_D3	-	EVE NTO UT
P H 13	-	-	-	TMR8 _CH1 N	-	-	-	-	-	CAN1_TX	-	-	DMC_DQ5	-	-	-	EVE NTO UT
P H 14	-	-	-	TMR8 _CH2 N	-	-	-	-	-	-	-	-	-	-	DCI_D4	-	EVE NTO UT
P H 15	-	-	-	TMR8 _CH3 N	-	-	-	-	-	-	-	-	DMC_DQ6	DCI_D11	-	EVE NTO UT	

Table 12 GPIOI Multiplexing Function Configuration

Port		A F 0	AF 1	AF2	AF3	AF 4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	A F1 4	AF15
		S Y S	TMR R1/ 2	TMR 3/4/5	TMR8/ 9/10/1	I2C 1	SPI1/SPI2/I 2S2/I2S2ex	SPI3/I2 Sext/I2	USART1/ 2/3/I2S3e	UART4/ 5/USAR	CAN1/2T MR12/13/ 14	OTG_FS/ OTG_HS	ETH	SMC/DMC/S DIO/OTG_F S	DCI		
Port_I	PI_0	-	-	TMR5_CH4	-	-	SPI2_NSS I2S2_WS	-	-	-	-	-	-	-	DCI_D13	-	EVE_NTO_UT
	PI_1	-	-	-	-	-	SPI2_SCK I2S2_CK	-	-	-	-	-	-	-	DCI_D8	-	EVE_NTO_UT
	PI_2	-	-	-	TMR8_CH4	-	SPI2_MISO	I2S2ext_SD	-	-	-	-	-	-	DCI_D9	-	EVE_NTO_UT
	PI_3	-	-	-	TMR8_ETR	-	SPI2_MOSI I2S2_SD	-	-	-	-	-	-	DMC_DQ7	DCI_D10	-	EVE_NTO_UT
	PI_4	-	-	-	TMR8_BKIN	-	-	-	-	-	-	-	-	-	DCI_D5	-	EVE_NTO_UT
	PI_5	-	-	-	TMR8_CH1	-	-	-	-	-	-	-	-	-	DCI_VSYNC	-	EVE_NTO_UT
	PI_6	-	-	-	TMR8_CH2	-	-	-	-	-	-	-	-	-	DCI_D6	-	EVE_NTO_UT

Port	A F 0	AF 1	AF2	AF3	AF 4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	A F1 4	AF15
	S Y S	TM R1/ 2	TMR 3/4/5	TMR8/ 9/10/1 1	I2C 1/2/ 3	SPI1/SPI2/I 2S2/I2S2ex t	SPI3/I2 Sext/I2 S3	USART1/ 2/3/I2S3e xt	UART4/ 5/USAR T6	CAN1/2T MR12/13/ 14	OTG_FS/ OTG_HS	ETH	SMC/DMC/S DIO/OTG_F S	DCI		
PI 7	-	-	-	TMR8 _CH3	-	-	-	-	-	-	-	-	DMC_WE	DCI_ D7	-	EVE NTO UT
PI 8	-	-	-	-	-	-	-	-	-	-	-	-	DMC_CAS	-	-	EVE NTO UT
PI 9	-	-	-	-	-	-	-	-	-	CAN1_RX	-	-	DMC_RAS	-	-	EVE NTO UT
PI 10	-	-	-	-	-	-	-	-	-	-	-	ETH_MI I_RX_E R	DMC_CS	-	-	EVE NTO UT
PI 11	-	-	-	-	-	-	-	-	-	-	OTG_HS _ULPI_DI R	-	DMC_BA	-	-	EVE NTO UT

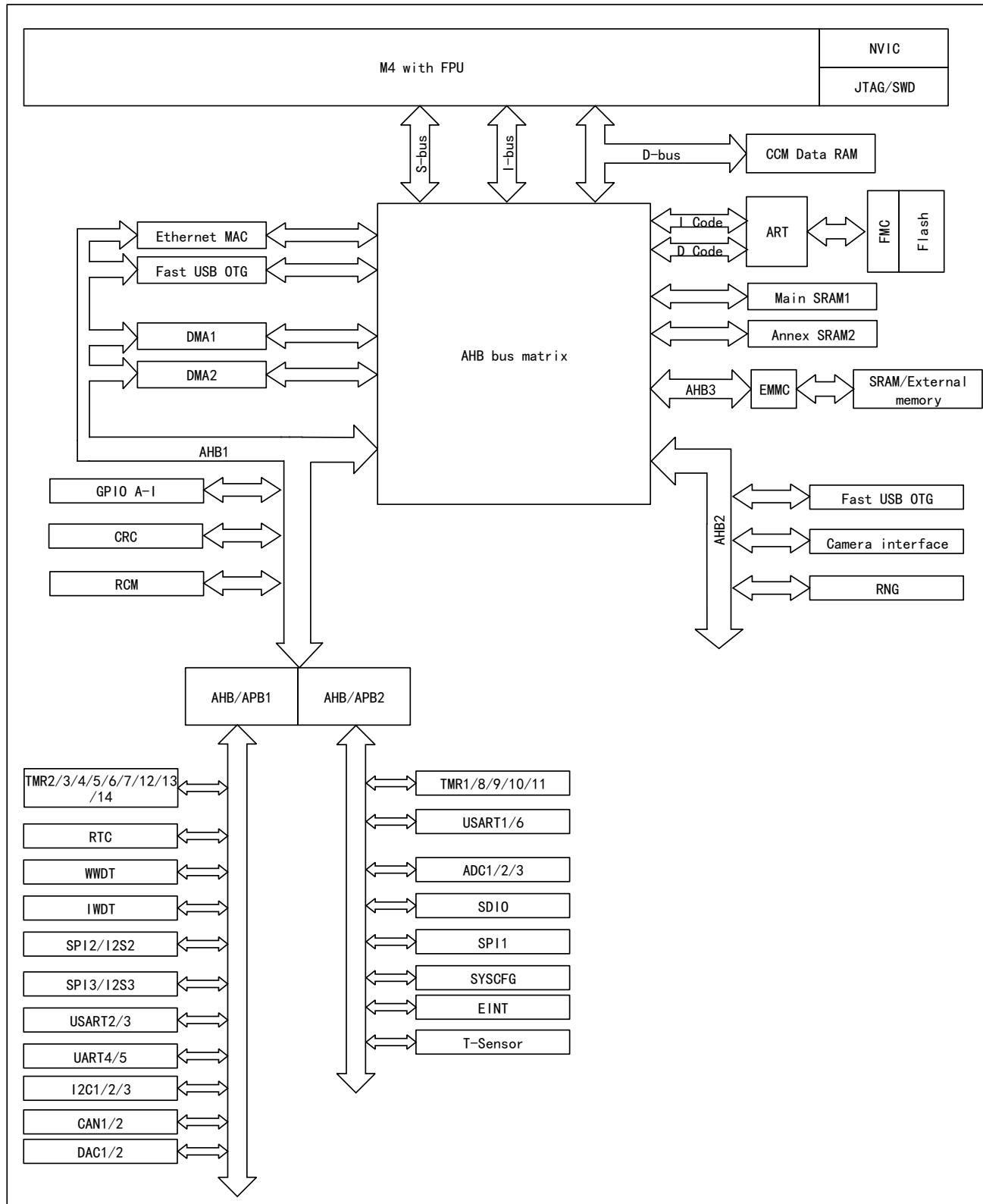
4 Function Description

This chapter mainly introduces the system architecture, interrupt, on-chip memory, clock, power supply and peripheral features of APM32F405xG 407xExG series products; for information about the Arm® Cortex®-M4 core, please refer to the *Arm® Cortex®-M4 Technical Reference Manual*, which can be downloaded from Arm's website.

4.1 System architecture

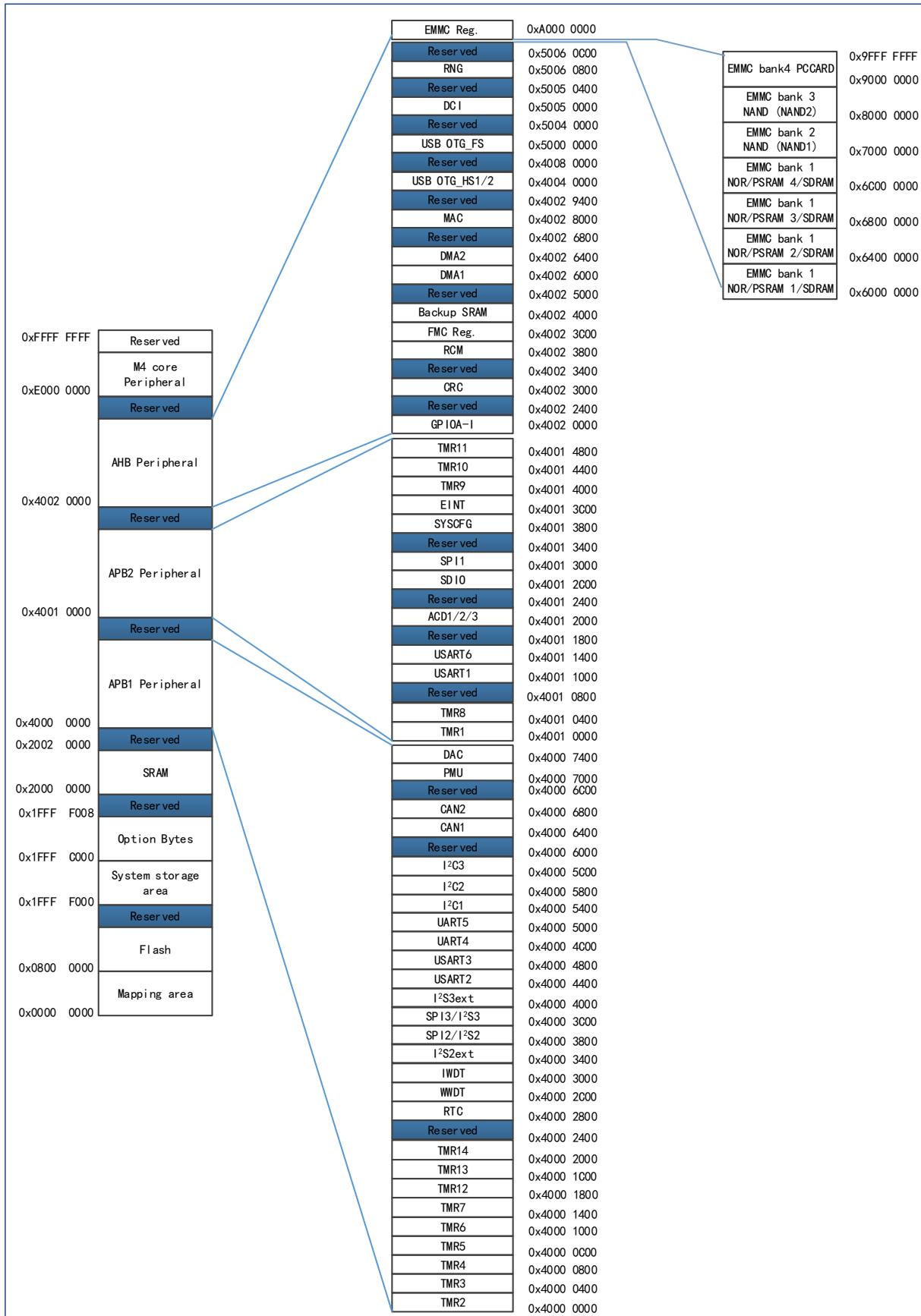
4.1.1 System block diagram

Figure 5 APM32F405xG 407xExG System Block Diagram



4.1.2 Address mapping

Figure 6 APM32F405xG 407xExG Series Address Mapping Diagram



4.1.3 Startup configuration

At startup, the user can select one of the following three startup modes by setting the high and low levels of the Boot pin:

- Startup from main memory
- Startup from BootLoader
- Startup from built-in SRAM

The user can use serial interface to reprogram the user Flash if starting up from BootLoader.

4.2 Core

The core of APM32F405xG 407xExG is Arm® Cortex®-M4 with FPU computing unit. Based on this platform, the development cost is low and the power consumption is low. It can provide excellent computing performance and advanced system interrupt response, and is compatible with all Arm tools and software.

4.3 Interrupt controller

4.3.1 Nested Vector Interrupt Controller (NVIC)

It embeds a nested vectored interrupt controller (NVIC) that can handle up to 79 maskable interrupt channels (not including 16 interrupt lines of Cortex®-M4) and 8 priority levels. The interrupt vector entry address can be directly transmitted to the core, so that the interrupt response processing with low delay can give priority to the late higher priority interrupt.

4.3.2 External Interrupt/Event Controller (EINT)

The external interrupt/event controller consists of 23 edge detectors, and each detector includes edge detection circuit and interrupt/event request generation circuit; each detector can be configured as rising edge trigger, falling edge trigger or both and can be masked independently. Up to 140 GPIOs can be connected to 16 external interrupt lines.

4.4 On-chip memory

On-chip memory includes main memory area, SRAM and information block; the information block includes system memory area and option byte; the system memory area stores BootLoader, 96-bit unique device ID and capacity information of main memory area; the system memory area has been written into the program when leaving the factory and cannot be erased.

Table 13 On-chip Memory Area

Memory	Maximum capacity	Function
Main memory area	1MB	Store user programs and data
SRAM	192 KB	CPU can access at 0 wait cycle (read/write)
System memory area	30KB	Store BootLoader, 96-bit unique device ID, and main memory area capacity information

Memory	Maximum capacity	Function
Option byte	16Bytes	Configure main memory area read-write protection and MCU working mode

4.4.1 Configurable external memory controller (EMMC)

APM32F405xG 407xExG series integrates EMMC module, consists of SMC (static memory controller), DMC (dynamic memory controller), and supports PC card, SRAM, SDRAM, PSRAM, NorFlash and NandFlash.

Function introduction:

- Three EMMC interrupt sources, connected to NVIC unit through logic or
- Write FIFO
- The code can run in off-chip memories except NAND flash and PC card
- Connect to LCD

4.4.2 LCD parallel interface (LCD)

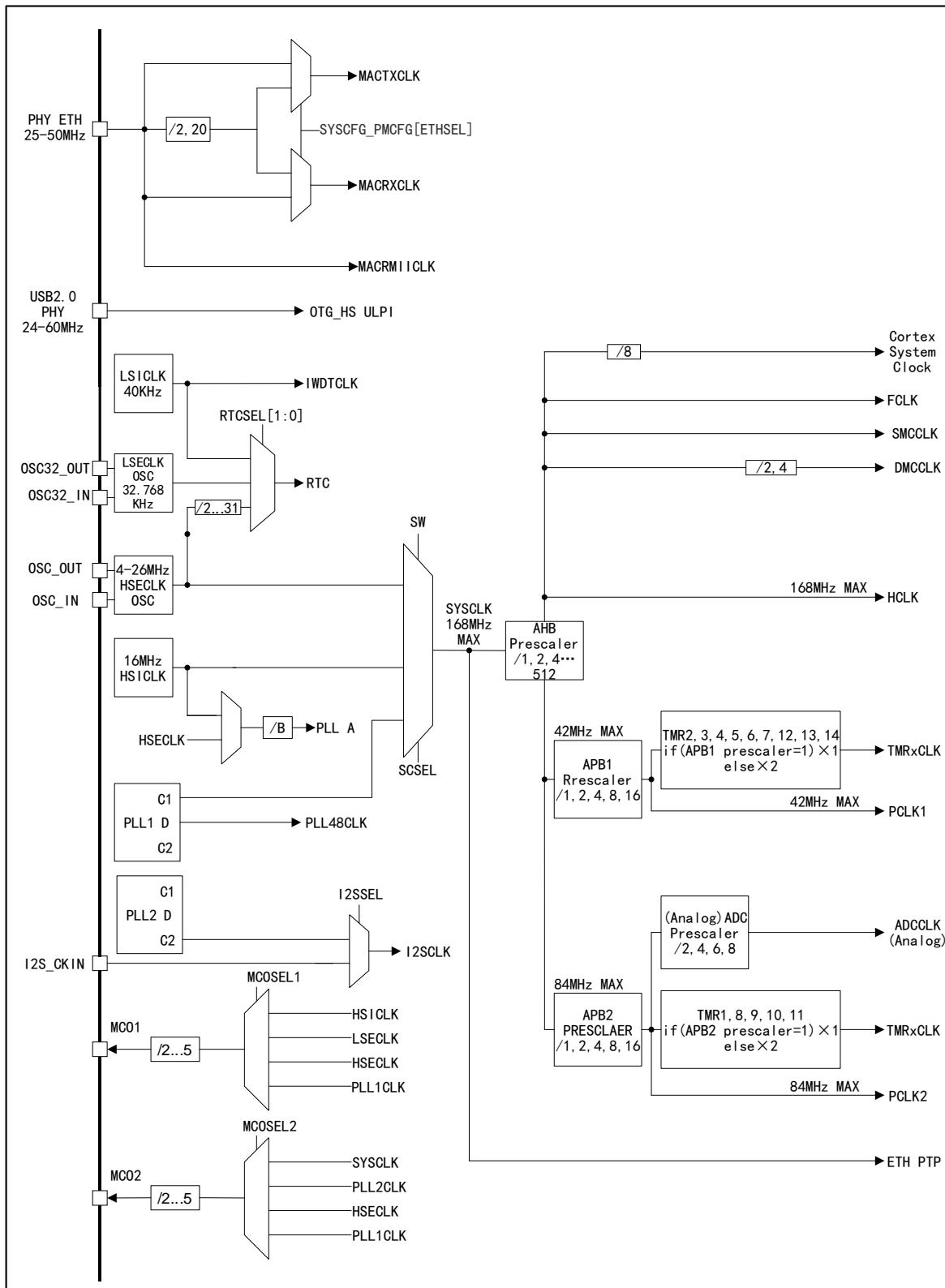
EMMC can be configured to seamlessly connect with most graphic LCD controllers, and supports the modes of Intel 8080 and Motorola 6800, and can flexibly connect with specific LCD interface. This LCD parallel interface can be used to easily build a simple graphics application environment or the high-performance scheme of the special acceleration controller can be used.

4.5 Clock

4.5.1 Clock tree

Clock tree of APM32F405xG 407xExG is shown in the figure below:

Figure 7 APM32F405xG 407xEExG Clock Tree



4.5.2 Clock source

Clock source is divided into high-speed clock and low-speed clock according to the speed; the high-speed clock includes HSIECLK and HSECLK, and the low-speed clock includes LSECLK

and LSICLK; besides, some modules may have additional clock source pins to obtain the required clock frequency through external circuits.

4.5.3 System clock

HSICLK, PLLCLK and HSECLK can be selected as system clock; the clock source of PLLCLK can be HSICLK or HSECLK; the required system clock can be obtained by configuring PLL clock multiplier factor and frequency division factor.

When the product is reset and started, HSICLK is selected as the system clock by default, and then the user can choose one of the above clock sources as the system clock. When HSECLK failure is detected, the system will automatically switch to the HSICLK, and if an interrupt is enabled, the software can receive the related interrupt.

4.5.4 Bus clock

AHB, APB1 and APB2 buses are built in. The clock source of AHB is SYSCLK, and the clock source of APB1 and APB2 is HCLK; the required clock can be obtained by configuring the frequency division factor. The maximum frequency of AHB is 168MHz, the maximum frequency of APB2 is 84MHz, and the maximum frequency of APB1 is 42MHz.

4.5.5 Phase locked loop

APM32F405xG 407xExG series product has two PLL, one is PLL (PLL1), and the other is PLL (PLL2) specially used to provide specific clock frequency for I2S. They all need to generate different clock frequencies by configuring parameters. Please refer to the *User Manual* for specific parameters and configuration registers.

4.6 Power and power management

4.6.1 Power supply scheme

Table 14 Power Supply Scheme

Name	Voltage range	Description
V _{DD}	1.8~3.6V	I/O (see pin distribution diagram for specific IO) and internal voltage regulator are powered through V _{DD} pin.
V _{DDA} /V _{SSA}	1.8~3.6V	Supply power for ADC, DAC, reset module, RC oscillator and PLL analog part; when ADC or DAC is used, V _{DDA} and V _{SSA} must be connected to V _{DD} and V _{SS} .
V _{BAT}	1.8~3.6V	When V _{DD} is disabled, RTC, external 32KHz oscillator and backup register are powered through internal power switch.

4.6.2 Voltage regulator

Table 15 Regulator Operating Mode

Name	Description
Master mode (MR)	Used in run mode
Low-power mode (LPR)	Used in stop mode

Name	Description
Power-down mode	Used in standby mode; when the voltage regulator has high-impedance output, the core circuit is powered down, the power consumption of the voltage regulator is zero, and all data of registers and SRAM will be lost.

Note: The voltage regulator is always in working state after reset, and outputs with high impedance in power-down mode.

4.6.3 Power supply voltage monitor

Power-on reset (POR), power-down reset (PDR) and brown-out reset circuits are integrated inside the product. These three circuits are always in working condition. When the power-down reset circuit monitors that the power supply voltage is lower than the specified threshold value ($V_{POR/PDR}$), even if the external reset circuit is used, the system will remain reset.

The product has a built-in programmable power supply voltage monitor (PWD) that can monitor V_{DD} and compare it with V_{PWD} threshold. When V_{DD} is outside the V_{PWD} threshold range and the interrupt is enabled, the MCU can be set to a safe state through the interrupt service program.

4.7 Low-power mode

APM32F405xG 407xExG supports three low-power modes, namely, sleep mode, stop mode and standby mode, and there are differences in power, wake-up time and wake-up mode among these three modes. The low-power mode can be selected according to the actual application requirements.

Table 16 Low-power Mode

Mode	Description
Sleep mode	The core stops working, all peripherals are working, and it can be woken up through interrupts/events
Stop mode	Under the condition that SRAM and register data are not lost, the lowest power consumption can be achieved in stop mode; The clock of the internal 1.3V power supply module will stop, HSECLK crystal resonator, HSICLK and PLL will be disabled, and the voltage regulator can be configured in normal mode or low-power mode; Any external interrupt line can wake up MCU, and the external interrupt lines include one of the 16 external interrupt lines, PVD output, RTC and USB_OTG.
Standby mode	The power consumption in this mode is the lowest; Internal voltage regulator is turned off, all 1.3V power supply modules are powered down, HSECLK crystal resonator, and HSICLK clocks are disabled, SRAM and register data disappear, RTC area and backup register contents remain, and the standby circuit still works; The external reset signal on NRST, IWDT reset, rising edge on WKUP pin or RTC event will wake MCU out of standby mode.

4.8 DMA

2 built-in DMA, 16 data streams in total. Each data stream corresponds to 8 channels, but each

data stream can only use 1 channel at the same time. The peripherals supporting DMA requests are ADC, SPI, USART, I2C, and TMRx. Four levels of DMA channel priority can be configured. Support "memory→memory, memory→peripheral, peripheral→memory" data transmission (the memory includes Flash、SRAM、SDRAM).

4.9 GPIO

GPIO can be configured as general input, general output, multiplexing function and analog input and output. The general input can be configured as floating input, pull-up input and pull-down input; the general output can be configured as push-pull output and open-drain output; the multiplexing function can be used for digital peripherals; and the analog input and output can be used for analog peripherals and low-power mode; the enable and disable pull-up/pull-down resistor can be configured; the speed of 2MHz, 10MHz and 50MHz can be configured; the higher the speed is, the greater the power and the noise will be.

4.10 Communication peripherals

4.10.1 USART/UART

Up to 6 universal synchronous/asynchronous transmitter receivers are built in the chip. The USART1/6 interfaces can communicate at a rate of 10.5Mbit/s, while other USART/UART interfaces can communicate at a rate of 5.25Mbit/s. All USART/UART interfaces can configure baud rate, parity check bit, stop bit, and data bit length; they all can support DMA.

USART/UART function differences are shown in the table below:

Table 17 USART/UART Function Differences

USART mode/function	USART1	USART2	USART3	UART4	UART5	USART6
Hardware flow control of modem	√	√	√	—	—	√
Smart card mode	√	√	√	—	—	√
IrDA SIR coder-encoder functions	√	√	√	√	√	√
LIN mode	√	√	√	√	√	√
Standard characteristics	√	√	√	√	√	√
SPI host	√	√	√	—	—	√
Maximum baud rate under 16-time oversampling (Mbit/s)	5.25	2.62	2.62	2.62	2.62	5.25
Maximum baud rate under 8-time oversampling (Mbit/s)	10.50	5.25	5.25	5.25	5.25	10.5
APB mapping	APB2	APB1	APB1	APB1	APB1	APB2

Note: √ = support.

4.10.2 I2C

I2C1/2/3 bus interfaces are built-in and they all can work in multiple-master or slave modes,

support 7-bit or 10-bit addressing, and support dual-slave addressing in 7-bit slave mode; the communication rate supports standard mode (up to 100kbit/s) and fast mode (up to 400kbit/s); hardware CRC generator/checker are built in; they can operate with DMA and support SMBus 2.0 version/PMBus.

4.10.3 SPI/I2S

3 built-in SPI, support full-duplex and half-duplex communication in master mode and slave mode, can use DMA controller, and can configure 4~16 bits per frame, and 3 SPI can communicate at a rate of up to 42Mbit/s, 21MBit/s and 21MBit/s respectively.

2 built-in I2S (multiplexed with SPI2 and SPI3 respectively), support half-duplex communication in master mode and slave mode, support synchronous transmission, and can be configured with 16-bit, 24-bit and 32-bit data transfer with 16-bit or 32-bit resolution. The configurable range of audio sampling rate is 8kHz~192kHz; when one or two I2S interfaces are configured as the master mode, the master clock can be output to external DAC or decoder (CODEC) at 256-time sampling frequency.

4.10.4 CAN

2 built-in CAN, compatible with 2.0A and 2.0B (active) specification, and can communicate at a rate of up to 1Mbit/s. It can receive and transmit standard frame of 11-bit identifier and extended frame of 29-bit identifier. It has 3 sending mailboxes and 2 receiving FIFO, and 14 3-level adjustable filters.

4.10.5 USB_OTG

Three USB controllers, namely, one OTG_FS and two OTG_HS, are embedded in the product. They all can support both host and slave functions to comply with the On-The-Go supplementary standard of USB 2.0 specification, and can also be configured as "Host only" or "Slave only" mode, to fully comply with USB 2.0 specification. OTG_FS clock (48MHz) is output by specific PLL, and OTG_HS clock (60MHz) is provided by external PHY.

4.10.6 Ethernet

Provides an IEEE-802.3-2002 compatible MAC for Ethernet LAN communication over MII or RMII. This MCU requires a PHY connection to a physical LAN bus. The PHY connects to the MII port, uses 17 signals for MII or 9 signals for RMII, and can use a 25MHz clock (MII) from the kernel.

4.10.7 SDIO

The secure digital input/output interface can connect SD card, SD I/O card, multi-media card (MMC) and CE-ATA card master interfaces, and provide data transmission between APB2 system bus and SD memory card, SD I/O card, MMC and CE-ATA device.

4.11 Analog peripherals

4.11.1 ADC

3 built-in ADC with 12-bit accuracy, up to 21 external channels and 3 internal channels for each ADC. The internal channels measure the temperature sensor voltage, reference voltage and backup voltage respectively. A/D conversion mode of each channel has single, continuous, scan or intermittent modes, ADC conversion results can be left aligned or right aligned and stored in 16-bit data register; they support analog watchdog, and DMA.

4.11.1.1 Temperature sensor

1 temperature sensor (TSensor) is built in, which is internally connected with ADC_IN16 channel. The voltage generated by the sensor changes linearly with temperature and the converted voltage value can be obtained by ADC and converted into temperature.

4.11.1.2 Internal reference voltage

Built-in reference voltage V_{REFINT} , internally connected to ADC_IN17 channel; V_{REFINT} can be obtained through ADC; V_{REFINT} provides stable voltage output for ADC.

4.11.2 DAC

2 built-in 12-bit DAC, each corresponding to an output channel, which can be configured as 8-bit and 12-bit modes, and the DMA function is supported. The waveform generation supports noise wave and triangle wave. The conversion mode supports independent or simultaneous conversion and the trigger mode supports external signal trigger and internal timer update trigger.

4.12 Timer

2 built-in 16-bit advanced timers (TMR1/8), 8 16-bit general-purpose timers (TMR3/4/9/10/11/12/13/14), 2 32-bit general timers (TMR2/5), 2 16-bit basic timers (TMR6/7), 1 independent watchdog timer, 1 window watchdog timer and 1 system tick timer.

Watchdog timer can be used to detect whether the program is running normally.

The system tick timer is the peripheral of the core with automatic reloading function. When the counter is 0, it can generate a maskable system interrupt, which can be used for real-time operating system and general delay.

Table 18 Function Comparison between Advanced/General-purpose/Basic and System Tick Timers

Timer type	System tick timer	Basic timer	General-purpose timer		Advanced timer
Timer name	Sys Tick Timer	TMR6/7	TMR2/5	TMR3/4/9/10/11/12/13/14	TMR1/8
Counter resolution	24 bits	16 bits	32 bits	16 bits	16 bits

Timer type	System tick timer	Basic timer	General-purpose timer	Advanced timer
Counter type	Down	Up	Up, down, up/down	Up, down, up/down
Prescaler factor	-	Any integer between 1 and 65536	Any integer between 1 and 65536	Any integer between 1 and 65536
Generate DMA request	-	OK	OK	OK
Capture/comp are register	-	-	4	4
Complementary output	-	None	None	Yes
Pin characteristics	-	-	1-way external trigger signal input pin; 1-way braking input signal pin; 4-way non-complementary channel pin.	1-way external trigger signal input pin; 1-way braking input signal pin; 3-pair complementary channel pins; 1-way non-complementary channel pin.
Function Description	Special for real-time operating system. Automatic reloading function supported. When the counter is 0, it can generate a maskable system interrupt. Can program the clock source.	Used to generate DAC trigger signals. Can be used as a 16-bit general-purpose timebase counter.	Synchronization or event chaining function provided. Timers in debug mode can be frozen. Can be used to generate PWM output. Each timer has independent DMA request mechanism. It can handle incremental encoder signals.	It has complementary PWM output with dead band insertion. When configured as a 16-bit standard timer, it has the same function as the TMRx timer. When configured as a 16-bit PWM generator, it has full modulation capability (0~100%). In debug mode, the timer can be frozen, and PWM output is disabled. Synchronization or event chaining function provided.

Table 19 Function Comparison between IWDT and WWDT

Name	Counter resolution	Counter type	Prescaler factor	Function description
Independent watchdog	12 bits	Down	Any integer between 1 and 256	The clock is provided by an internally independent RC oscillator of 28KHz, which is independent of the master clock, so it can run in stop and standby modes.

Name	Counter resolution	Counter type	Prescaler factor	Function description
				<p>The whole system can be reset in case of problems.</p> <p>It can provide timeout management for applications as a free-running timer.</p> <p>It can be configured as a software or hardware startup watchdog through option bytes.</p> <p>Timers in debug mode can be frozen.</p>
Window watchdog	7 bits	Down	-	<p>Can be set for free running.</p> <p>The whole system can be reset in case of problems.</p> <p>Driven by the master clock, it has early interrupt warning function;</p> <p>Timers in debug mode can be frozen.</p>

4.13 RTC

1 RTC is built in, and there are LSECLK signal input pins (OS32_IN and OS32_OUT) and 2 TAMP input signal detection pins (RTC_TAMP1/2); the clock source can select external 32.768kHz crystal oscillator, resonator or oscillator, LSICLK and HSECLK/128; it is powered by V_{DD} by default; when V_{DD} is powered off, it can be automatically switched to V_{BAT} power supply, and RTC configuration and time data will not be lost; RTC configuration and time data will not be lost in case of system reset, software reset and power-on reset; it supports clock and calendar functions.

4.13.1 Backup domain

4KB backup SRAM and 20 backup registers are built in, and are powered by V_{DD} by default; when V_{DD} is powered off, it can be automatically switched to V_{BAT} power supply, and the data in backup register will not be lost; the data in backup register will not be lost in case of system reset, software reset and power-on reset.

4.14 RNG

A RNG is embedded, and it provides 32-bit random number generated by the integrated simulation.

4.15 DCI

DCI is used to receive high-speed data streams from CMOS camera. It supports different data formats and is applicable to black-and-white cameras, X24 cameras and so on.

4.16 CRC

1 CRC (cyclic redundancy check) computing unit is built in, which can generate CRC codes and operate 8-bit, 16-bit and 32-bit data.

5 Electrical Characteristics

5.1 Test conditions of electrical characteristics

5.1.1 Maximum and minimum values

Unless otherwise specified, all products are tested on the production line at $T_A=25^{\circ}\text{C}$. Its maximum and minimum values can support the worst environmental temperature, power supply voltage and clock frequency.

In the notes at the bottom of each table, it is stated that the data are obtained through comprehensive evaluation, design simulation or process characteristics and are not tested on the production line; on the basis of comprehensive evaluation, after passing the sample test, take the average value and add and subtract three times the standard deviation (average $\pm 3\sum$) to get the maximum and minimum values.

5.1.2 Typical value

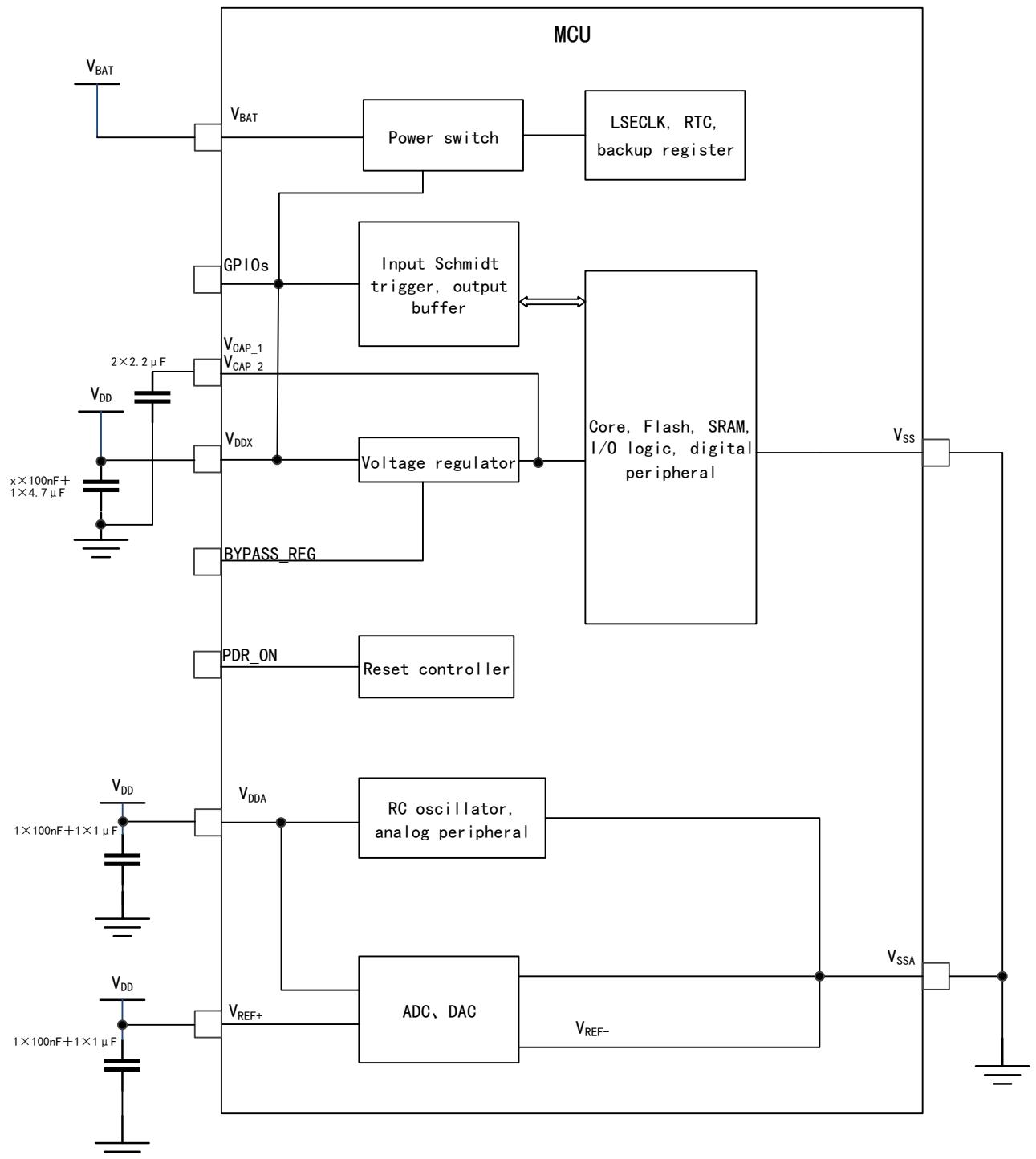
Unless otherwise specified, typical data are measured based on $T_A=25^{\circ}\text{C}$, $V_{DD}=V_{DDA}=3.3\text{V}$. These data are only used for design guidance.

5.1.3 Typical curve

Unless otherwise specified, typical curves will only be used for design guidance and will not be tested.

5.1.4 Power supply scheme

Figure 8 Power Supply Scheme



Notes: V_{DDX} in the figure means the number of V_{DD} is x

5.1.5 Load capacitance

Figure 9 Load conditions when measuring pin parameters

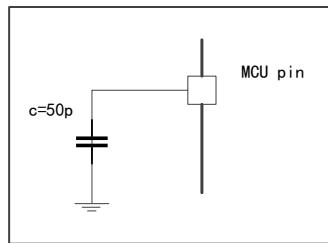


Figure 10 Pin Input Voltage Measurement Scheme

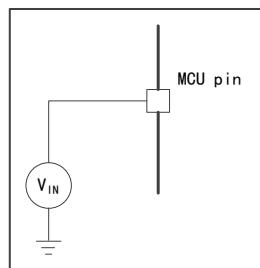
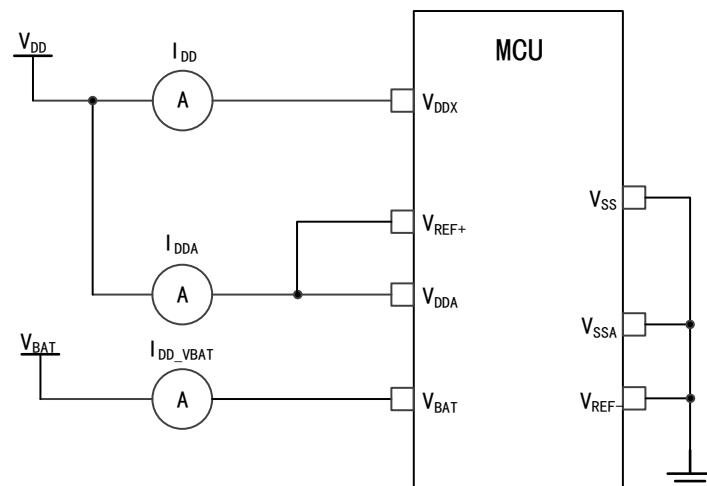


Figure 11 Power Consumption Measurement Scheme



5.2 Test under general operating conditions

Table 20 General Operating Conditions

Symbol	Parameter	Conditions	Minimum value	Maximum value	Unit
f_{HCLK}	Internal AHB clock frequency	-	-	168	MHz
f_{PCLK1}	Internal APB1 clock frequency	-	-	42	
f_{PCLK2}	Internal APB2 clock frequency	-	-	84	
V_{DD}	Main power supply voltage	-	1.8	3.6	V
V_{DDA}	Analog power supply voltage	Must be the same	1.8	2.4	V

Symbol	Parameter	Conditions	Minimum value	Maximum value	Unit
	(When neither ADC nor DAC is used)	as V _{DD}			
	Analog power supply voltage (When ADC and DAC are used)		2.4	3.6	
V _{BAT}	Power supply voltage of backup domain	-	1.65	3.60	V
T _A	Ambient temperature (temperature number 6)	Maximum power dissipation	-40	85	°C

5.3 Absolute maximum ratings

If the load on the device exceeds the absolute maximum rating, it may cause permanent damage to the device. Here, only the maximum load that can be borne is given, and there is no guarantee that the device functions normally under this condition.

5.3.1 Maximum temperature characteristics

Table 21 Temperature Characteristics

Symbol	Description	Value	Unit
T _{STG}	Storage temperature range	-65 ~ +150	°C
T _J	Maximum junction temperature	125	°C

5.3.2 Maximum rated voltage characteristics

All power supply (V_{DD}, V_{DDA}) and ground (V_{SS}, V_{SSA}) pins must always be connected to the power supply within the external limited range.

Table 22 Maximum Rated Voltage Characteristics

Symbol	Description	Minimum value	Maximum value	Unit
V _{DD} - V _{SS}	External main power supply voltage	-0.3	4.0	
V _{IN}	Input voltage on FT pins	V _{SS} -0.3	V _{DD} +4	V
	Input voltage on other pins	V _{SS} -0.3	4.0	
ΔV _{DDX}	Voltage difference between different power supply pins	-	50	mV
V _{SSx} -V _{SS}	Voltage difference between different grounding pins	-	50	

5.3.3 Maximum rated current characteristics

Table 23 Current Characteristics

Symbol	Description	Maximum value	Unit
I _{VDD}	Total current through V _{DD} /V _{DDA} power line (supply current) ⁽¹⁾	240	mA
I _{VSS}	Total current through V _{SS} ground line (outflow current) ⁽¹⁾	240	

Symbol	Description	Maximum value	Unit
I_{IO}	Sink current on any I/O and control pin	25	
	Source current on any I/O and control pin	25	
$I_{INJ(PIN)}^{(2)}$	Injection current of 5T pin	-5/+0	
	Injection current of other pins	±5	
$\Sigma I_{INJ(PIN)}^{(2)}$	Total injection current on all I/O and control pins ⁽⁴⁾	±25	

1. All power supply (V_{DD} , V_{DDA}) and ground (V_{SS} , V_{SSA}) must always be within the allowed range.
2. The outflow current will interfere with the analog performance of the device.
3. I/O cannot be injected positively: when $V_{IN} < V_{SS}$, $I_{INJ(PIN)}$ cannot exceed the maximum allowable input voltage value.
4. If V_{IN} exceeds the maximum value, $I_{INJ(PIN)}$ must be externally limited not to exceed the maximum value. When $V_{IN} > V_{DD}$, the current flows into the pins; when $V_{IN} < V_{SS}$, the current flows out of the pins.
5. When the current is injected into several I/O ports at the same time, the maximum value of $\Sigma I_{INJ(PIN)}$ is the sum of instantaneous absolute value of inflow current and outflow current.

5.3.4 Electro-static discharge (ESD)

Table 24 ESD Absolute Maximum Ratings

Symbol	Parameter	Conditions	Range	Unit
$V_{ESD(HBM)}$	Electrostatic discharge voltage (human body model)	$T_A = +25^\circ C$, conforming to JESD22-A114	±4500	V

Note: The samples are measured by a third-party testing organization and are not tested in production.

5.3.5 Static latch-up (LU)

Table 25 Static Latch-up

Symbol	Parameter	Conditions	Type
LU	Class of static latch-up	$T_A = +105^\circ C$, conforming to JESD78A	Class II A

Note: The samples are measured by a third-party testing organization and are not tested in production.

5.4 On-chip memory

5.4.1 Flash characteristics

Table 26 Flash Memory Characteristics

Symbol	Parameter	Conditions	Minimum value	Typical value	Maximum value	Unit
t_{prog}	8/16/32-bit programming time	$T_A = -40\text{--}105^\circ C$ $V_{DD}=2.4\text{--}3.6V$	-	43	60	μs
t_{ERASE1}	Page (16KBytes) erase time	8 bits	-	60	120	ms
		16 bits	-	60	120	
		32 bits	-	60	120	

Symbol	Parameter		Conditions	Minimum value	Typical value	Maximum value	Unit	
t_{ERASE2}	Page (64KBytes) erase time	8 bits		-	250	500		
		16 bits		-	250	500		
		32 bits		-	250	500		
t_{ERASE3}	Page (128KBytes) erase time	8 bits		-	500	1000		
		16 bits		-	500	1000		
		32 bits		-	500	1000		
t_{ME}	Mass erase time	8 bits	$T_A = -40\sim105^\circ C$ $V_{DD}=2.4\sim3.6V$	-	10	20	ms	
		16 bits		-	10	20		
		32 bits		-	10	20		
V_{prog}	Voltage of 8-bit programming		$T_A = -40\sim105^\circ C$	1.8	-	3.6	V	
	Voltage of 16-bit programming			2.1	-	3.6		
	Voltage of 32-bit programming			2.7	-	3.6		

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.5 Clock

5.5.1 Characteristics of external clock source

5.5.1.1 High-speed external clock generated by crystal resonator

For detailed parameters (frequency, package, precision, etc.) of crystal resonator, please consult the corresponding manufacturer.

Table 27 HSECLK4~26MHz Oscillator Characteristics

Symbol	Parameter	Conditions	Minimum value	Typical value	Maximum value	Unit
f_{osc_IN}	Oscillator frequency	-	4	8	26	MHz
R_F	Feedback resistance	-	-	200	-	kΩ
$I_{DD(HSECLK)}$	HSECLK current consumption	$V_{DD}=3.3V$, $C_L=10pF@8MHz$	-	-	0.5	mA
$t_{SU(HSECLK)}$	Start-up Time	V_{DD} is stable	-	2	-	ms

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.5.1.2 Low-speed external clock generated by crystal resonator

For detailed parameters (frequency, package, precision, etc.) of crystal resonator, please consult the corresponding manufacturer.

Table 28 LSECLK Oscillator Characteristics ($f_{LSECLK} = 32.768\text{KHz}$)

Symbol	Parameter	Conditions	Minimum value	Typical value	Maximum value	Unit
f_{OSC_IN}	Oscillator frequency	-	-	32.768	-	KHz
$I_{DD(LSECLK)}$	LSECLK current consumption	-	-	-	1	μA
$t_{SU(LSECLK)}^{(1)}$	Start-up Time	V_{DD} is stable	-	2	-	s

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

(1) $t_{SU(LSECLK)}$ is the startup time, which is measured from the time when LSECLK is enabled by software to the time when stable oscillation at 32.768KHz is obtained. This value is measured by using a standard crystal resonator, which may vary greatly due to different crystal manufacturers.

5.5.2 Characteristics of internal clock source

5.5.2.1 High-speed internal (HSICLK) RC oscillator

Table 29 HSICLK Oscillator Characteristics

Symbol	Parameter	Conditions		Minimum value	Typical value	Maximum value	Unit
f_{HSICLK}	Frequency	-		-	16	-	MHz
$A_{CC(HSICLK)}$	Accuracy of HSICLK oscillator	Factory calibration	$V_{DD}=3.3\text{V}, T_A=25^\circ\text{C}^{(1)}$	-1	-	1	%
			$V_{DD}=2-3.6\text{V}, T_A=-40\text{--}105^\circ\text{C}$	-2	-	4	%
$I_{DDA(HSICLK)}$	Power consumption of HSICLK oscillator	-		-	100	120	μA
$t_{SU(HSICLK)}$	Startup time of HSICLK oscillator	$V_{DD}=3.3\text{V}, T_A=-40\text{--}105^\circ\text{C}$		-	3.7	5	μs

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.5.2.2 Low-speed internal (LSICLK) RC oscillator

Table 30 LSICLK Oscillator Characteristics

Symbol	Parameter	Minimum value	Typical value	Maximum value	Unit
f_{LSICLK}	Frequency ($V_{DD}=2-3.6\text{V}, T_A=-40\text{--}105^\circ\text{C}$)	20	28	35	KHz
$I_{DD(LSICLK)}$	Power consumption of LSICLK oscillator	-	0.4	0.6	μA
$t_{SU(LSICLK)}$	Startup time of LSICLK oscillator, ($V_{DD}=3.3\text{V}, T_A=-40\text{--}105^\circ\text{C}$)	-	16	40	μs

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.5.3 PLL Characteristics

Table 31 PLL1 Characteristics

Symbol	Parameter	Value			Unit
		Minimum value	Typical value	Maximum value	
f_{PLL1_IN}	PLL1 input clock	0.92	1	2.1	MHz
	PLL1 input clock duty cycle	40	-	60	%
f_{PLL1_OUT}	PLL1 frequency multiplier output clock ($V_{DD}=3.3V$, $T_A=-40\sim105^\circ C$)	24	-	168	MHz
$f_{PLL1_48_OUT}$	PLL1 frequency multiplier output 48MHz clock ($V_{DD}=3.3V$, $T_A=-40\sim105^\circ C$)	-	48	75	MHz
t_{LOCK1}	PLL1 phase locking time	60	-	120	μs

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

Table 32 PLL2 Characteristics

Symbol	Parameter	Value			Unit
		Minimum value	Typical value	Maximum value	
f_{PLL2_IN}	PLL2 input clock	0.92	1	2.1	MHz
	PLL2 input clock duty cycle	40	-	60	%
f_{PLL2_OUT}	PLL2 frequency multiplier output clock ($V_{DD}=3.3V$, $T_A=-40\sim105^\circ C$)	20	-	144	MHz
t_{LOCK1}	PLL phase locking time	82	-	150	μs

5.6 Reset and power management

5.6.1 Test of Embedded Reset and Power Control Module Characteristics

Table 33 Embedded Reset and Power Control Module Characteristics

Symbol	Parameter	Conditions	Minimum value	Typical value	Maximum value	Unit
$V_{POR/PDR}$	Power-on/power-down reset threshold	Falling edge	1.68	1.70	1.70	V
		Rising edge	1.71	1.72	1.73	V
V_{BOR1}	Under-voltage threshold level 1	Falling edge	2.19	2.21	2.24	V
		Rising edge	2.27	2.29	2.30	V
V_{BOR2}	Under-voltage threshold level 2	Falling edge	2.49	2.51	2.55	V
		Rising edge	2.56	2.58	2.59	V
V_{BOR3}	Under-voltage threshold level 3	Falling edge	2.81	2.84	2.87	V
		Rising edge	2.89	2.91	2.92	V
$V_{BORhyst}$	BOR hysteresis	-	-	100	-	mV

Symbol	Parameter	Conditions	Minimum value	Typical value	Maximum value	Unit
$V_{PDRhyst}$	PDR hysteresis	-	-	40.00	50.00	mV
$T_{RSTTEMPO}$	Reset duration	-	0.70	0.95	1.48	ms

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

Table 34 Programmable Power Supply Voltage Detector Characteristics

Symbol	Parameter	Conditions	Minimum value	Typical value	Maximum value	Unit
V_{PVD}	Programmable power supply voltage detector voltage level selection	PLS[2:0]=000 (rising edge)	2.14	-	2.18	V
		PLS[2:0]=000 (falling edge)	2.03	-	2.10	V
		PLS[2:0]=000 (PVD hysteresis)	80.00	-	120.00	mV
		PLS[2:0]=001 (rising edge)	2.30	-	2.34	V
		PLS[2:0]=001 (falling edge)	2.18	-	2.23	V
		PLS[2:0]=001 (PVD hysteresis)	90.00	-	120.00	mV
		PLS[2:0]=010 (rising edge)	2.44	-	2.48	V
		PLS[2:0]=010 (falling edge)	2.32	-	2.37	V
		PLS[2:0]=010 (PVD hysteresis)	110.00	-	120.00	mV
		PLS[2:0]=011 (rising edge)	2.58	-	2.63	V
		PLS[2:0]=011 (falling edge)	2.49	-	2.53	V
		PLS[2:0]=011 (PVD hysteresis)	90.00	-	100.00	mV
		PLS[2:0]=100 (rising edge)	2.75	-	2.80	V
		PLS[2:0]=100 (falling edge)	2.64	-	2.68	V
		PLS[2:0]=100 (PVD hysteresis)	110.00	-	120.00	mV
		PLS[2:0]=101 (rising edge)	2.91	-	2.97	V
		PLS[2:0]=101 (falling edge)	2.81	-	2.86	V
		PLS[2:0]=101 (PVD hysteresis)	100.00	-	110.00	mV
		PLS[2:0]=110 (rising edge)	3.02	-	3.08	V
		PLS[2:0]=110 (falling edge)	2.90	-	2.96	V
		PLS[2:0]=110 (PVD hysteresis)	110.00	-	120.00	mV
		PLS[2:0]=111 (rising edge)	3.12	-	3.19	V
		PLS[2:0]=111 (falling edge)	3.00	-	3.07	V
		PLS[2:0]=111 (PVD hysteresis)	110.00	-	120.00	mV

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.7 Power consumption

5.7.1 Power consumption test environment

- (1) The values are measured by executing Dhrystone 2.1, with the Keil.V5 compilation environment and the L0 compilation optimization level.
- (2) All I/O pins are in analog input mode and are connected to a static level at V_{DD} or V_{SS} (no load)
- (3) Unless otherwise specified, all peripherals are disabled
- (4) The relationship between Flash wait cycle setting and f_{HCLK}:
 - 0~30MHz: 0 wait cycle
 - 30~60MHz: 1 wait cycle
 - 60~90MHz: 2 wait cycles
 - 90~120MHz: 3 wait cycles
 - 120~150MHz: 4 wait cycles
 - 150~168MHz: 5 wait cycles
- (5) When the peripherals are enabled: f_{PCLK1}=f_{HCLK}/4, f_{PCLK2}=f_{HCLK}/2

5.7.2 Power consumption in run mode

Table 35 Power Consumption in Run Mode when the Program is Executed in Flash (ART is turned on)

Parameter	Conditions	f _{HCLK}	Typical value ⁽¹⁾		Maximum value ⁽¹⁾	
			T _A =25°C, V _{DD} =3.3V		T _A =105°C, V _{DD} =3.6V	
			I _{DDA} (μA)	I _{DD} (mA)	I _{DDA} (μA)	I _{DD} (mA)
Power consumption in run mode	HSECLK bypass ⁽²⁾ , enabling all peripherals ⁽³⁾	168MHz	751.56	67.70	802.20	74.02
		144MHz	693.94	52.75	745.20	57.66
		120MHz	637.4	44.49	691.10	49.39
		90MHz	780.88	34.37	831.70	39.375
		60MHz	636.86	23.86	689.60	28.7
		30MHz	636.62	13.29	689.40	18.099
		25MHz	115.372	10.83	127.76	15.627
		16MHz	115.42	7.21	127.93	11.905
		8MHz	115.36	3.93	127.77	8.587
		4MHz	115.33	2.31	127.78	6.967
		2MHz	115.36	1.49	127.82	6.17
Power consumption in run mode	HSECLK bypass ⁽²⁾ , disabling all peripherals	168MHz	750.88	28.35	801.40	34.352
		144MHz	692.84	22.02	744.70	26.958
		120MHz	636.82	18.54	691.10	23.48
		90MHz	779.80	14.45	831.90	19.302
		60MHz	636.52	10.04	689.80	14.924
		30MHz	636.40	5.75	690.20	10.563
		25MHz	115.32	4.38	128.66	9.115
		16MHz	115.34	3.01	128.44	7.673
		8MHz	115.36	1.86	127.80	6.481
		4MHz	115.35	1.27	127.84	5.93
		2MHz	115.36	0.99	127.86	5.65

Note:

(1) The data are obtained from a comprehensive evaluation and are not tested in production.

(2) The external clock is 4MHz; when f_{HCLK}>25MHz, turn on PLL; otherwise, turn off PLL.

(3) When the analog peripherals such as ADC, DAC, HSECLK, LSECLK, HSICLK and LSICLK are turned on, extra power consideration needs to be considered.

Table 36 Power Consumption in Run Mode when the Program is Executed in Flash (ART is turned off)

Parameter	Conditions	f _{HCLK}	Typical value ⁽¹⁾		Maximum value ⁽¹⁾	
			T _A =25°C, V _{DD} =3.3V		T _A =105°C, V _{DD} =3.6V	
			I _{DDA} (μA)	I _{DD} (mA)	I _{DDA} (μA)	I _{DD} (mA)
Power consumption in run mode	HSECLK bypass ⁽²⁾ , enabling all peripherals ⁽³⁾	168MHz	751.66	64.25	802.00	70.52
		144MHz	693.58	51.09	745.30	56.05
		120MHz	637.26	43.99	690.20	48.92
		90MHz	780.86	34.91	831.40	39.97
		60MHz	636.78	25.02	689.40	29.90
		30MHz	636.66	14.33	689.00	19.32
		25MHz	115.36	11.80	127.72	16.725
		16MHz	115.36	7.83	127.75	12.53
		8MHz	115.35	4.27	127.80	8.99
		4MHz	115.35	2.45	127.88	7.13
		2MHz	115.362	1.57	127.76	6.28
	HSECLK bypass ⁽²⁾ , disabling all peripherals	168MHz	750.94	24.71	801.40	30.85
		144MHz	692.82	20.21	744.70	25.18
		120MHz	636.76	17.96	689.80	22.91
		90MHz	780.46	15.03	831.60	20.01
		60MHz	636.46	11.19	689.80	16.13
		30MHz	636.38	6.79	689.90	11.68
		25MHz	115.33	5.26	128.50	10.15
		16MHz	115.32	3.65	127.96	8.46
		8MHz	115.36	2.14	127.82	6.80
		4MHz	115.35	1.43	127.68	6.11
		2MHz	115.53	1.07	127.90	5.82

Note:

(1) The data are obtained from a comprehensive evaluation and are not tested in production.

(2) The external clock is 4MHz; when f_{HCLK}>25MHz, turn on PLL; otherwise, turn off PLL.

(3) When the analog peripherals such as ADC, DAC, HSECLK, LSECLK, HSICLK and LSICLK are turned on, extra power consideration needs to be considered.

Table 37 Power Consumption in Run Mode when the Program is Executed in RAM

Parameter	Conditions	f _{HCLK}	Typical value ⁽¹⁾		Maximum value ⁽¹⁾	
			T _A =25°C, V _{DD} =3.3V		T _A =105°C, V _{DD} =3.6V	
			I _{DDA} (μA)	I _{DD} (mA)	I _{DDA} (μA)	I _{DD} (mA)
Power consumption in run mode	HSECLK bypass ⁽²⁾ , enabling all peripherals ⁽³⁾	168MHz	752.14	70.29	803.80	76.51
		144MHz	693.74	54.73	745.50	59.73
		120MHz	637.60	46.22	690.40	51.16
		90MHz	781.00	35.67	832.00	40.53
		60MHz	637.02	24.70	689.8	29.65
		30MHz	636.74	13.74	689.2	18.596
		25MHz	115.42	11.23	127.85	16.02
		16MHz	115.374	7.42	127.88	12.21
		8MHz	115.37	4.05	127.81	8.836
		4MHz	115.376	2.38	127.72	7.12
		2MHz	115.347	1.53	127.76	6.28
	HSECLK bypass ⁽²⁾ , disabling all peripherals	168MHz	751.38	31.03	802.4	37.29
		144MHz	693.00	24.11	744.7	29.11
		120MHz	636.88	20.30	689.80	25.23
		90MHz	780.56	15.81	931.60	20.74
		60MHz	636.68	10.92	690.00	15.80
		30MHz	636.62	6.19	689.70	11.02
		25MHz	115.36	4.75	128.42	9.48
		16MHz	115.35	3.26	128.79	8.07
		8MHz	115.38	1.97	127.76	6.71
		4MHz	115.36	1.33	127.73	6.04
		2MHz	115.34	1.02	127.74	5.70

Note:

(1) The data are obtained from a comprehensive evaluation and are not tested in production.

(2) The external clock is 4MHz, and when f_{HCLK}>25MHz, turn on PLL, otherwise, turn off PLL.

(3) When the analog peripherals such as ADC, DAC, HSECLK, LSECLK, HSICLK and LSICLK are turned on, extra power consideration needs to be considered.

5.7.3 Power consumption in sleep mode

Table 38 Power Consumption in Sleep Mode when the Program is Executed in Flash (ART is turned off)

Parameter	Conditions	f _{HCLK}	Typical value ⁽¹⁾		Maximum value ⁽¹⁾	
			T _A =25°C, V _{DD} =3.3V		T _A =105°C, V _{DD} =3.6V	
			I _{DDA} (μA)	I _{DD} (mA)	I _{DDA} (μA)	I _{DD} (mA)
Power consumption in sleep mode	HSECLK bypass ⁽²⁾ , enabling all peripherals	168MHz	751.34	54.18	802.1	60.33
		144MHz	693.26	42.25	745.00	47.12
		120MHz	637.24	35.75	689.80	40.53
		90MHz	780.60	27.69	831.20	32.539
		60MHz	636.72	19.33	689.20	24.149
		30MHz	636.46	11.02	689.20	15.8
		25MHz	115.356	8.96	127.77	13.7
		16MHz	115.34	5.99	127.71	10.68
		8MHz	115.334	3.33	127.78	8.01
		4MHz	115.332	2.00	127.84	6.669
		2MHz	115.352	1.34	127.82	6.017
Power consumption in sleep mode	HSECLK bypass ⁽²⁾ , disabling all peripherals	168MHz	750.52	13.91	801.00	19.86
		144MHz	692.58	10.82	743.90	15.64
		120MHz	636.46	9.20	689.00	13.99
		90MHz	780.24	7.44	830.60	12.21
		60MHz	636.42	5.33	689.00	10.07
		30MHz	636.36	3.38	688.80	8.10
		25MHz	115.37	2.41	127.84	7.08
		16MHz	115.35	1.79	127.74	6.46
		8MHz	115.35	1.23	127.83	5.91
		4MHz	115.36	0.96	127.86	5.63
		2MHz	115.42	0.83	127.84	5.54

Note:

(1) The data are obtained from a comprehensive evaluation and are not tested in production.

(2) The external clock is 4MHz; when f_{HCLK}>25MHz, turn on PLL; otherwise, turn off PLL.

5.7.4 Power consumption in stop mode

Table 39 Power Consumption in Stop Mode

Conditions		Typical value ⁽¹⁾ , ($T_A=25^\circ C$)						Maximum value ⁽¹⁾ , ($V_{DD}=3.6V$)	
		$V_{DD}=2.4V$		$V_{DD}=3.3V$		$V_{DD}=3.6V$		$T_A=105^\circ C$	
		I_{DDA} (μA)	I_{DD} (mA)	I_{DDA} (μA)	I_{DD} (mA)	I_{DDA} (μA)	I_{DD} (mA)	I_{DDA} (μA)	I_{DD} (mA)
The regulator is in run mode, and all oscillators are in off state	Flash is in stop mode, and RC internal oscillator and high-speed oscillator are turned off (with no independent watchdog)	9.28	0.69	9.80	0.70	10.05	0.71	12.36	20.00
	Flash is in power-down mode, and RC internal oscillator and high-speed oscillator are turned off (with no independent watchdog)	9.23	0.69	9.72	0.70	10.00	0.70	12.35	20.00
The regulator is in low-power mode, and all oscillators are in off state	Flash is in stop mode, and RC internal oscillator and high-speed oscillator are turned off (with no independent watchdog)	4.18	0.21	4.65	0.21	4.87	0.21	5.91	15.00
	Flash is in power-down mode, and RC internal oscillator and high-speed oscillator are turned off (with no independent watchdog)	4.19	0.20	4.64	0.20	4.86	0.20	5.86	15.00

5.7.5 Power consumption in standby mode

Table 40 Power Consumption in Standby Mode

Conditions		Typical value ⁽¹⁾ , ($T_A=25^\circ C$)						Maximum value ⁽¹⁾ , ($V_{DD}=3.6V$)	
		$V_{DD}=2.4V$		$V_{DD}=3.3V$		$V_{DD}=3.6V$		$T_A=105^\circ C$	
		I_{DDA} (μA)	I_{DD} (μA)	I_{DDA} (μA)	I_{DD} (μA)	I_{DDA} (μA)	I_{DD} (μA)	I_{DDA} (μA)	I_{DD} (μA)
Power supply current in standby mode	The backup SRAM is turned on, and the low-speed oscillator and RTC are turned on	2.15	8.38	2.56	9.73	2.83	10.19	3.76	59.39
	The backup SRAM is turned off, and the low-speed oscillator and RTC are turned on	2.15	3.52	2.62	4.46	2.81	5.11	3.48	32.00

Conditions	Typical value ⁽¹⁾ , ($T_A=25^\circ C$)						Maximum value ⁽¹⁾ , ($V_{DD}=3.6V$)	
	$V_{DD}=2.4V$		$V_{DD}=3.3V$		$V_{DD}=3.6V$		$T_A=105^\circ C$	
	I_{DDA} (μA)	I_{DD} (μA)	I_{DDA} (μA)	I_{DD} (μA)	I_{DDA} (μA)	I_{DD} (μA)	I_{DDA} (μA)	I_{DD} (μA)
The backup SRAM is turned on, and the RTC is turned off	2.13	7.33	2.62	8.24	2.81	8.64	3.45	58.24
The backup SRAM is turned off, and the RTC is turned off	2.13	2.51	2.61	3.31	2.78	3.68	3.45	19.2

Note: (1) The data are obtained from a comprehensive evaluation and are not tested in production.

5.7.6 Peripheral power consumption

Peripheral power consumption = current that enables the peripheral clock-current that disables the peripheral clock.

Table 41 Peripheral Power Consumption

Parameter	Peripheral	Typical value ⁽¹⁾ $T_A=25^\circ C$, $V_{DD}=3.3V$		Unit
		168MHz	144MHz	
AHB1 (up to 168MHz)	DMA1	5.4	4.21	$\mu A/MHz$
	DMA2	5.56	4.3	
	ETH	3	2.35	
	OTG_HS	4.21	3.26	
	GPIOA	0.32	0.25	
	GPIOB	0.31	0.24	
	GPIOC	0.32	0.24	
	GPIOD	0.3	0.23	
	GPIOE	0.31	0.25	
	GPIOF	0.33	0.26	
	GPIOG	0.3	0.24	
	GPIOH	0.3	0.24	
	GPIOI	0.3	0.24	
AHB2 (up to 168MHz)	CRC	0.03	0.03	
	BAKPR	0.07	0.05	
	OTG_FS	3.12	2.41	
	DCI	0.79	0.61	
	RNG	0.16	0.12	
	HASH	1.3	1	

Parameter	Peripheral	Typical value ⁽¹⁾ T _A =25°C, V _{DD} =3.3V		Unit
		168MHz	144MHz	
		CRYP	0.25	0.19
AHB3 (up to 168MHz)	EMMC	1.68	1.3	
APB1 (up to 42MHz)	TMR2	0.46	0.36	
	TMR3	0.35	0.27	
	TMR4	0.34	0.27	
	TMR5	0.46	0.35	
	TMR6	0.08	0.07	
	TMR7	0.08	0.06	
	TMR12	0.19	0.15	
	TMR13	0.14	0.11	
	TMR14	0.14	0.1	
	WWDT	0.02	0.02	
	SPI2/I2S2	0.12	0.1	
	SPI3/I2S3	0.12	0.1	
	USART2	0.11	0.09	
	USART3	0.12	0.09	
	UART4	0.11	0.08	
	UART5	0.11	0.08	
	I2C1	0.12	0.09	
	I2C2	0.12	0.09	
	I2C3	0.12	0.1	
APB2 (up to 84MHz)	CAN1	0.18	0.14	
	CAN2	0.16	0.13	
	PMU	0.01	0.01	
	DAC	0.08	0.06	
	SDIO	0.41	0.32	
	TMR1	0.99	0.77	
	TMR8	0.97	0.77	

Parameter	Peripheral	Typical value ⁽¹⁾ T _A =25°C, V _{DD} =3.3V		Unit
		168MHz	144MHz	
	ADC2	0.27	0.22	
	ADC3	0.28	0.23	
	SPI1	0.12	0.11	
	USART1	0.22	0.18	
	USART6	0.21	0.18	
	SYSCFG	0.05	0.05	

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.7.7 Backup Domain Power Consumption

Table 42 V_{BAT} Power Consumption

Symbol	Parameter	Conditions	Typical value ⁽¹⁾ , T _A =25°C		Maximum value ⁽¹⁾ , V _{BAT} =3.6V		Unit
			V _{BAT} =2.4V	V _{BAT} =3.3V	T _A =85°C	T _A =105°C	
I _{DD_VBAT}	LSECLK and RTC are in ON state	The backup SRAM is turned on, and the low-speed oscillator and RTC are turned on	1.894	2.262	6	11	μA
		The backup SRAM is turned off, and the low-speed oscillator and RTC are turned on	1.08	1.412	3	5	
		The backup SRAM is turned on, and the RTC is turned off	0.926	1.116	5	10	
		The backup SRAM is turned off, and the RTC is turned off	0.02	0.128	2	4	

Note: (1) The data are obtained from a comprehensive evaluation and are not tested in production.

5.8 Wake-up time in low-power mode

The measurement of wake-up time in low-power mode is from the start of wake-up event to the time when the user program reads the first instruction, in which V_{DD}=V_{DDA}.

Table 43 Wake-up Time in Low-power Mode

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
t _{WUSLEEP}	Wake-up from sleep mode	-	39.00	59	61.20	ns

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
tWUSTOP	Wake up from the stop mode	The regulator is in run mode, and Flash is in stop state	12.51	13.602	14.99	μs
		The regulator is in low-power mode, and Flash is in stop state	15.51	19.552	22.93	
		The regulator is in run mode, and Flash is in deep power-down mode	125.63	133.156	135.16	
		The regulator is in low-power mode, and Flash is in deep power-down mode	133.52	136.956	139.60	
tWUSTDBY	Wake up from standby mode	-	173.03	214.056	227.96	

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.9 I/O port characteristics

Table 44 DC Characteristics ($T_A=-40^{\circ}\text{C}-105^{\circ}\text{C}$, $V_{DD}=2\text{~}3.6\text{V}$)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V _{IL}	Low-level input voltage	STD and STDA I/O	-	-	0.3V _{DD} -0.04	V
		5T and 5Tf I/O	-	-	0.3V _{DD}	
		Boot0 pin	-	-	0.1 _{DD} +0.1	
V _{IH}	High-level input voltage	STD and STDA I/O	0.45V _{DD} +0.3	-	-	V
		5T and 5Tf I/O	0.7V _{DD}	-	-	
		Boot0 pin	0.17V _{DD} +0.7	-	-	
V _{hys}	Schmidt trigger hysteresis	STD, STDA and 5T, 5Tf I/O	10% V _{DD}	-	-	mV
		Boot0 pin	0.1	-	-	
I _{lk}	Input leakage current	STDA in digital mode, $V_{DDIOx} \leq V_{IN} \leq V_{DDA}$	-	-	±1	μA
		5T and 5Tf I/O, $V_{DDIOx} \leq V_{IN} \leq 5\text{V}$	-	-	3	
R _{PU}	Weak pull-up equivalent resistance	Except PA10 and PB12, $V_{IN}=V_{SS}$	30	40	50	kΩ
		PA10 and PB12	7	10	14	
R _{PD}	Weak pull-down equivalent resistance	Except PA10 and PB12, $V_{IN}=V_{DD}$	30	40	50	
		PA10 and PB12	7	10	14	
C _{io}	I/O pin capacitance	-	-	5	-	pF

Table 45 AC Characteristics ($T_A=25^\circ C$)

SPEED[1:0]	Symbol	Parameter	Conditions	Min	Max	Unit
00	$f_{max(IO)out}$	Maximum frequency	CL=50pF, $V_{DD}>2.7V$	-	4	MHz
			CL=50pF, $V_{DD}>1.8V$	-	2	
			CL=10pF, $V_{DD}>2.7V$	-	8	
			CL=10pF, $V_{DD}>1.8V$	-	4	
	$t_{f(IO)out}/t_{r(IO)out}$	Fall time of output from high to low level and rise time of output from low to high level	$C_L=50 \text{ pF}, V_{DD}=1.8 \text{ V}-3.6\text{V}$	-	100	ns
			CL=50pF, $V_{DD}>2.7V$	-	25	
			CL=50pF, $V_{DD}>1.8V$	-	12.5	
			CL=10pF, $V_{DD}>2.7V$	-	50	
01	$f_{max(IO)out}$	Maximum frequency	CL=10pF, $V_{DD}>1.8V$	-	20	MHz
			CL=30pF, $V_{DD}>2.7V$	-	10	
			CL=30pF, $V_{DD}>1.8V$	-	20	
			CL=10pF, $V_{DD}>2.7V$	-	6	
	$t_{f(IO)out}/t_{r(IO)out}$	Fall time of output from high to low level and rise time of output from low to high level	CL=10pF, $V_{DD}>1.8V$	-	10	ns
			CL=30pF, $V_{DD}>2.7V$	-	50	
			CL=30pF, $V_{DD}>1.8V$	-	25	
			CL=10pF, $V_{DD}>2.7V$	-	100	
10	$f_{max(IO)out}$	Maximum frequency	CL=10pF, $V_{DD}>1.8V$	-	50	MHz
			CL=30pF, $V_{DD}>2.7V$	-	6	
			CL=30pF, $V_{DD}>1.8V$	-	10	
			CL=10pF, $V_{DD}>2.7V$	-	4	
	$t_{f(IO)out}/t_{r(IO)out}$	Fall time of output from high to low level and rise time of output from low to high level	CL=10pF, $V_{DD}>1.8V$	-	6	ns
			CL=30pF, $V_{DD}>2.7V$	-	100	
			CL=30pF, $V_{DD}>1.8V$	-	50	
			CL=10pF, $V_{DD}>2.7V$	-	180	
11	$f_{max(IO)out}$	Maximum frequency	CL=10pF, $V_{DD}>1.8V$	-	100	MHz
			CL=30pF, $V_{DD}>2.7V$	-	4	
			CL=30pF, $V_{DD}>1.8V$	-	6	
			CL=10pF, $V_{DD}>2.7V$	-	2.5	
	$t_{f(IO)out}/t_{r(IO)out}$	Fall time of output from high to low level and rise time of output from low to high level	CL=30pF, $V_{DD}>2.7V$	-	4	ns
			CL=30pF, $V_{DD}>1.8V$	-	6	
			CL=10pF, $V_{DD}>2.7V$	-	2.5	

SPEED[1:0]	Symbol	Parameter	Conditions	Min	Max	Unit
			CL=10pF, V _{DD} >1.8V	-	4	
-	t _{EINTipw}	Pulse width of external signal detected by EINT controller	-	10	-	

Figure 12 I/O AC Characteristics Definition

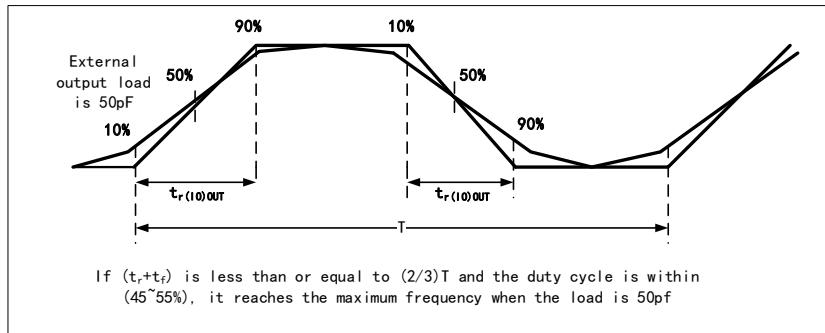


Table 46 Output Drive Voltage Characteristics ($T_A=25^\circ C$)

Symbol	Parameter	Conditions	Min	Max	Unit
V _{OL}	I/O pin outputs low voltage	CMOS port, I _{IO} =8mA, 2.7 V < V _{DD} < 3.6 V	-	0.4	V
V _{OH}	I/O pin outputs high voltage		V _{DD} -0.4	-	
V _{OL}	I/O pin outputs low voltage	TTL port, I _{IO} =20mA, 2.7 V < V _{DD} < 3.6 V	-	0.4	V
V _{OH}	I/O pin outputs high voltage		2.4	-	
V _{OL}	I/O pin outputs low voltage	I _{IO} =20mA, 2.7 V < V _{DD} < 3.6 V	-	1.3	V
V _{OH}	I/O pin outputs high voltage		V _{DD} -1.3	-	
V _{OL}	I/O pin outputs low voltage	I _{IO} =6mA, 2.7 V < V _{DD} < 3.6 V	-	0.4	V
V _{OH}	I/O pin outputs high voltage		V _{DD} -0.4	-	

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.10 NRST pin characteristics

The NRST pin input drive adopts CMOS process, which is connected with a permanent pull-up resistor RPU.

Table 47 NRST Pin Characteristics ($T_A=-40\sim105^\circ C$, $V_{DD}=2\sim3.6V$)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V _{IL(NRST)}	NRST low-level input voltage	TTL port, 2.7V≤V _{DD} ≤3.6V	-	-	0.8	V
V _{IH(NRST)}	NRST high-level input voltage		2	-	-	
V _{IL(NRST)}	NRST low-level input voltage	CMOS port,	-	-	0.3V _{DD}	

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{IH(NRST)}$	NRST high-level input voltage	$1.8V \leq V_{DD} \leq 3.6V$	$0.7V_{DD}$	-	-	
$V_{hys(NRST)}$	NRST Schmidt trigger voltage hysteresis	-	-	200	-	mV
R_{PU}	Weak pull-up equivalent resistance	$V_{IN}=V_{SS}$	30	40	50	kΩ
$V_{F(NRST)}$	NRST input filter pulse	-	-	-	100	ns
$V_{NF(NRST)}$	NRST input unfiltered pulse	$V_{DD} > 2.7V$	300	-	-	
T_{NRST_OUT}	Generated reset pulse duration	Reset internal source	20	-	-	μs

5.11 Communication peripherals

5.11.1 I2C peripheral characteristics

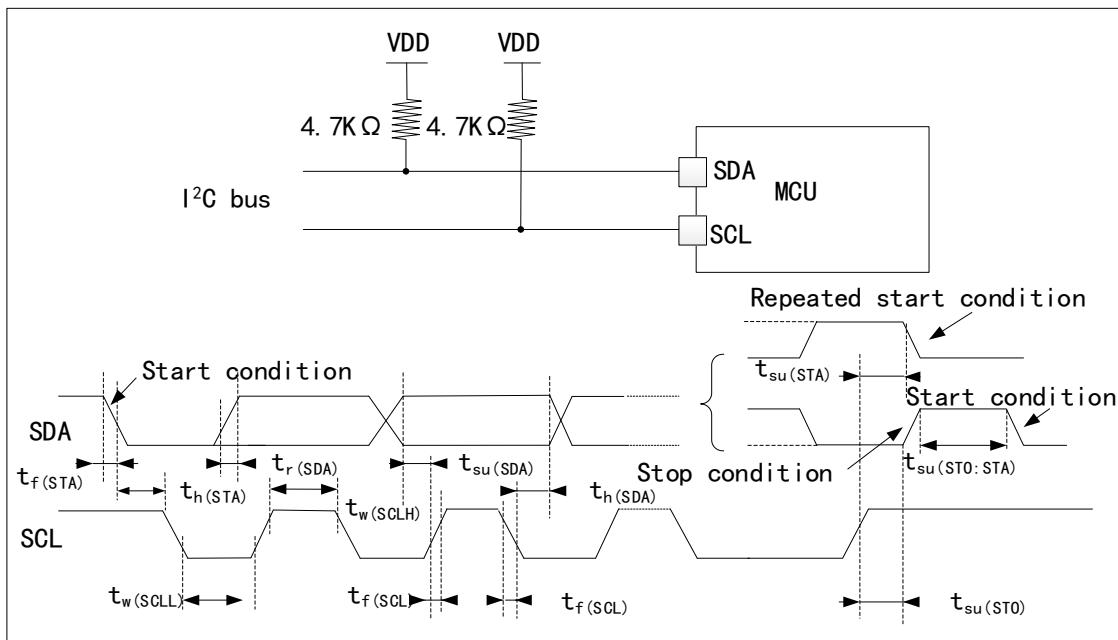
To achieve maximum frequency of I2C in standard mode, f_{PCLK1} must be greater than 2MHz. To achieve maximum frequency of I2C in fast mode, f_{PCLK1} must be greater than 4MHz.

Table 48 I2C Interface Characteristics ($T_A=25^\circ C$, $V_{DD}=3.3V$)

Symbol	Parameter	Standard I2C		Fast I2C		Unit
		Min	Max	Min	Max	
$t_w(SCLL)$	SCL clock low time	4.7	-	1.3	-	μs
$t_w(SCLH)$	SCL clock high time	4.0	-	0.6	-	
$t_{su}(SDA)$	SDA setup time	250	-	100	-	ns
$t_h(SDA)$	SDA data hold time	0	-	0	900	
$t_r(SDA)/t_f(SCL)$	SDA and SCL rise time	-	1000	$20+0.1C_b$	300	
$t_f(SDA)/t_r(SCL)$	SDA and SCL fall time	-	300	-	300	
$t_h(STA)$	Start condition hold time	4.0	-	0.6	-	μs
$t_{su}(STA)$	Setup time of repeated start condition	4.7	-	0.6	-	
$t_{su}(STO)$	Setup time of stop condition	4.0	-	0.6	-	
$t_w(STO:STA)$	Time from stop condition to start condition (the bus is idle)	4.7	-	1.3	-	
C_b	Capacitive load of each bus	-	400	-	400	pF

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

Figure 13 Bus AC Waveform and Measurement Circuit



Note: The measuring points are set at CMOS levels: 0.3V_{DD} and 0.7V_{DD}.

5.11.2 SPI peripheral characteristics

Table 49 SPI Characteristics ($T_A=25^\circ\text{C}$, $V_{DD}=3.3\text{V}$)

Symbol	Parameter	Conditions	Min	Max	Unit
f_{SCK} $1/t_{c(SCK)}$	SPI clock frequency	Master mode	-	18	MHz
		Slave mode	-	18	
$t_{r(SCK)}$ $t_{f(SCK)}$	SI clock rise and fall time	Load capacitance: C=15pF	-	6	
$t_{su(NSS)}$	NSS setup time	Slave mode	$4T_{PCLK}$	-	
$t_h(NSS)$	NSS hold time	Slave mode	$2T_{PCLK} + 10$	-	
$t_w(SCKH)$ $t_w(SCKL)$	SCK high and low time	Master mode, $f_{PCLK}=36\text{MHz}$, Prescaler factor=4	$T_{PCLK}/2-2$	$T_{PCLK}/2+1$	
$t_{su(MI)}$ $t_{su(SI)}$	Data input setup time	Master mode	4	-	ns
		Slave mode	5	-	
$t_h(MI)$ $t_h(SI)$	Data input hold time	Master mode	4	-	
		Slave mode	5	-	
$t_a(SO)$	Data output access time	Slave mode, $f_{PCLK}=20\text{MHz}$	0	$3T_{PCLK}$	
$t_{dis(SO)}$	Disable time of data output	Slave mode	0	18	
$t_v(SO)$	Effective time of data output	Slave mode (after enabling the edge)	-	22.5	

Symbol	Parameter	Conditions	Min	Max	Unit
$t_{v(MO)}$	Effective time of data output	Master mode (after enabling the edge)	-	6.97	
$t_{h(SO)}$	Data output hold time	Slave mode (after enabling the edge)	11.5	-	
		Master mode (after enabling the edge)	1	-	
DuCy(sck)	SPI clock frequency duty cycle	Slave mode	25	75	%

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

Figure 14 SPI Timing Diagram - Slave Mode and CPHA=0

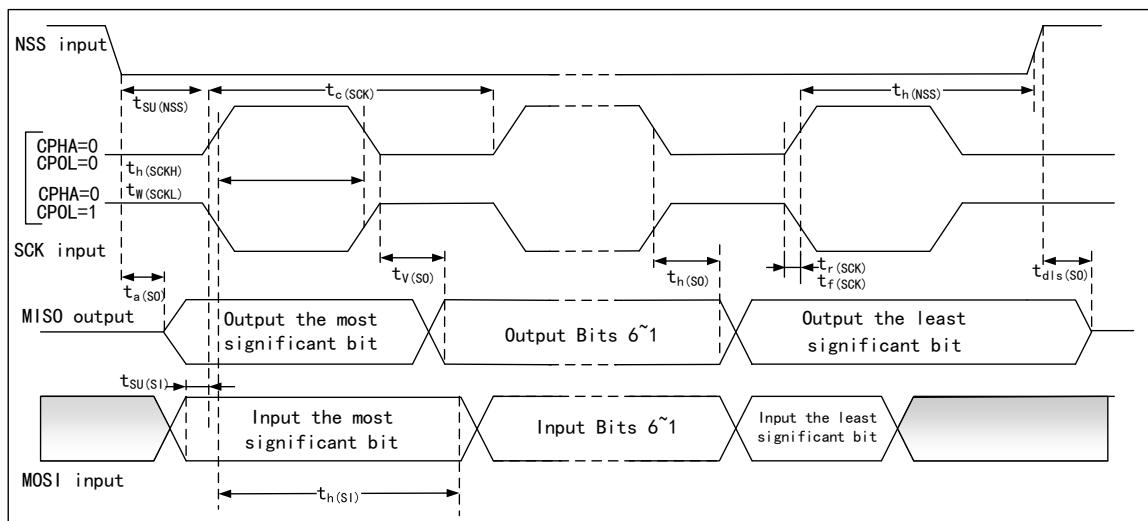
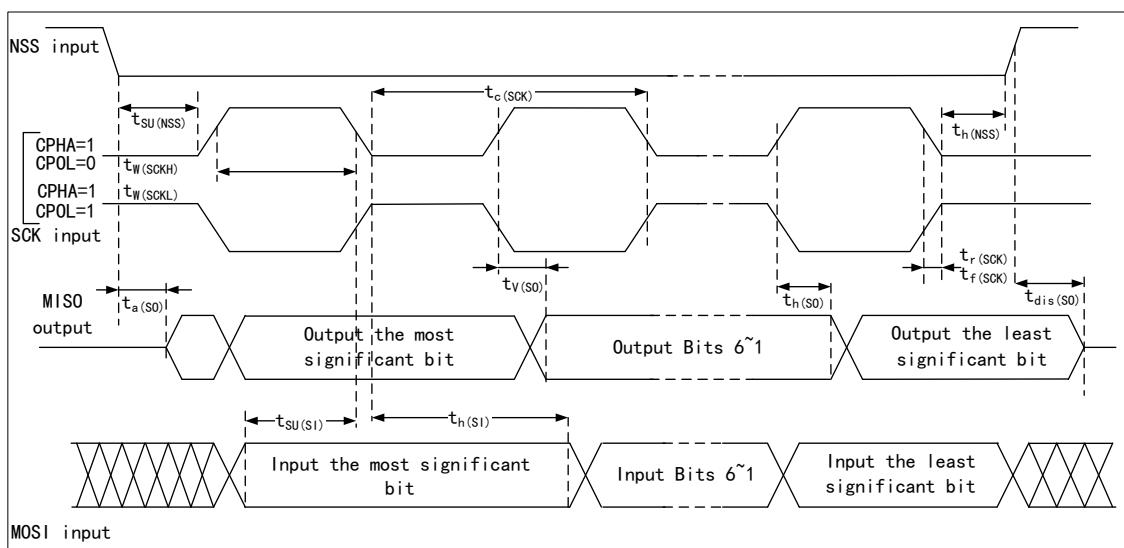
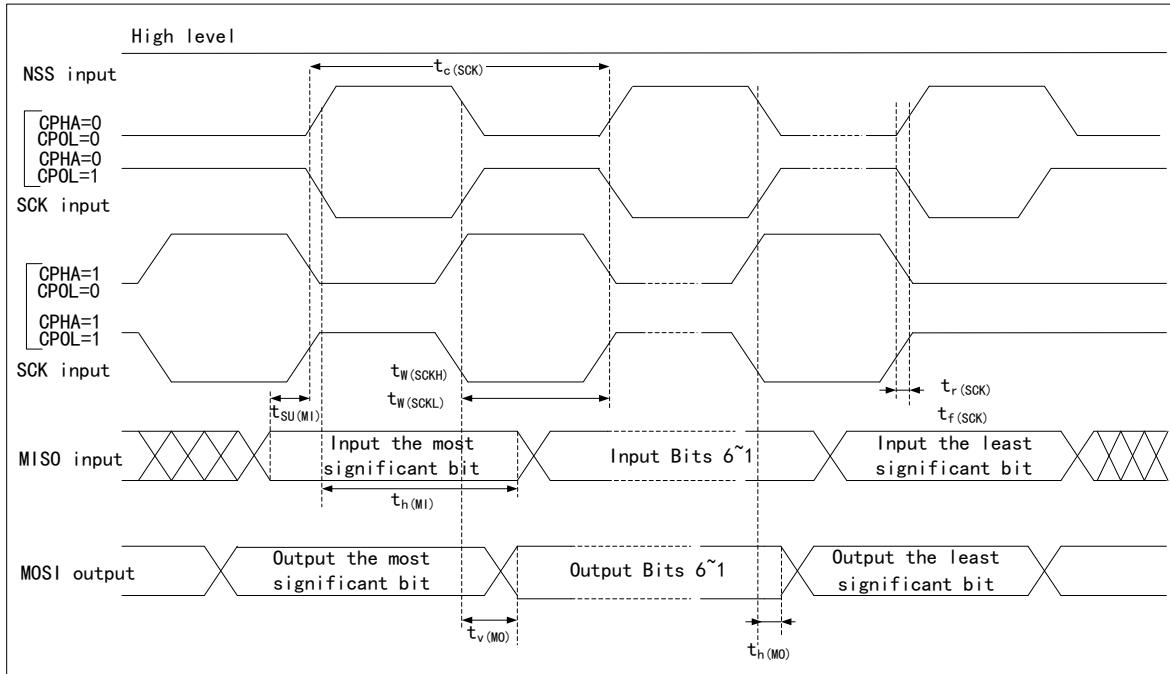


Figure 15 SPI Timing Diagram - Slave Mode and CPHA=1



Note: The measuring points are set at CMOS levels: $0.3V_{DD}$ and $0.7V_{DD}$.

Figure 16 SPI Timing Diagram - Master Mode



Note: The measuring points are set at CMOS levels: $0.3V_{DD}$ and $0.7V_{DD}$.

5.12 Analog peripherals

5.12.1 ADC

Test parameter description:

- Sampling rate: the number of conversion of analog quantity to digital quantity by ADC per second
- Sample rate=ADC clock/(number of sampling periods + number of conversion periods)

5.12.1.1 12-bit ADC characteristics

Table 50 12-bit ADC Characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DDA}	Power supply voltage	-	1.8	-	3.6	V
I_{DDA}	ADC power consumption	-	-	1.6	1.8	mA
f_{ADC}	ADC frequency	$V_{DDA}=1.8\sim2.4V$	0.6	15	18	MHz
		$V_{DDA}=2.4\sim3.6V$	0.6	30	36	
C_{ADC}	Internal sampling and holding capacitance	-	-	4	-	pF
R_{ADC}	Sampling resistor	-	-	-	6000	Ω
t_s	Sampling time	$f_{ADC}=30MHz$	0.1		16	μs

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
		-	3		480	1/f _{ADC}
T _{CONV}	Sampling and conversion time	f _{ADC} =30MHz 12-bit resolution	0.50	-	16.40	μs
		f _{ADC} =30MHz 10-bit resolution	0.43	-	16.34	μs
		f _{ADC} =30MHz 8-bit resolution	0.37	-	16.27	μs
		f _{ADC} =30MHz 6-bit resolution	0.30	-	16.20	μs

Table 51 12-bit ADC Accuracy

Symbol	Parameter	Conditions	Typ	Max	Unit
E _T	Composite error	f _{PCLK} =56MHz, f _{ADC} =14MHz, V _{DDA} =2.4V-3.6V T _A =-40°C~105°C	±2	±5	LSB
E _O	Offset error		±1.5	±2.5	
E _G	Gain error		±1.5	±3	
E _D	Differential linear error		±1	±2	
E _L	Integral linear error		±1.5	±3	

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.12.1.2 Test of Built-in Reference Voltage Characteristics

Table 52 Built-in Reference Voltage Characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V _{REFINT}	Built-in Reference Voltage	-40°C < T _A < +105°C	1.19	1.20	1.20	V
T _{S_vrefint}	Sampling time of ADC when reading out internal reference voltage	-	10	-	-	μs
V _{RERINT}	Built-in reference voltage extends to temperature range	V _{DD} =3V	-	3	5	mV
T _{coeff}	Temperature coefficient	-	-	30	50	ppm/°C

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.12.2 DAC

Test parameter description:

- DNL differential non-linear error: the deviation between two consecutive codes is - 1LSB
- INL integral non-linear error: the difference between the measured value at code i and the value at code i on the connection between code 0 and the last code 4095

Table 53 DAC Characteristics

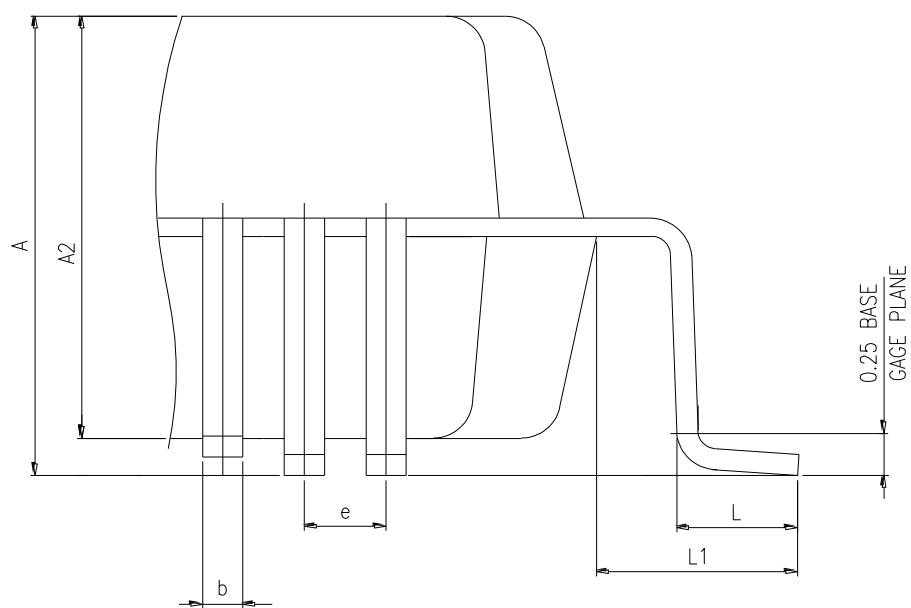
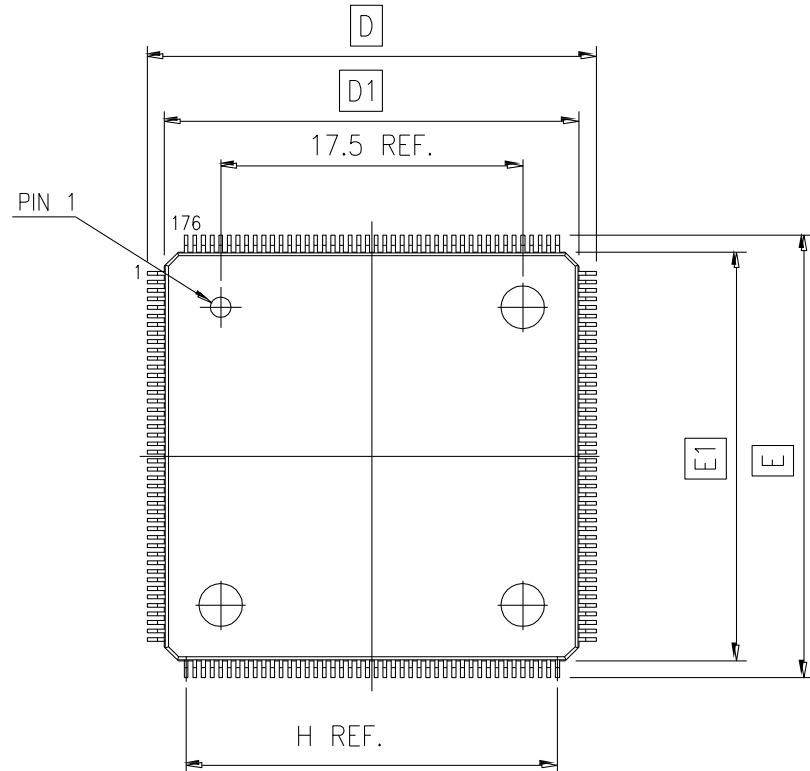
Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V _{DDA}	Analog power supply voltage	-	1.8	-	3.6	V
R _{LOAD}	Resistive load	The buffer is turned on	5	-	-	kΩ
R _O	Output impedance	The resistive load between DAC_OUT and V _{SS} is 1.5MΩ with buffer off	-	-	15	kΩ
C _{LOAD}	Capacitive load	Maximum capacitive load at DAC_OUT pin with buffer on	-	-	50	pF
DAC_OUT min	Low DAC_OUT voltage with buffer	Maximum output offset of DAC, (0x0E0) corresponding to 12-bit input code to V _{REF+} = (0xF1C) at 3.6V and V _{REF+} = (0x1C7) at 1.8V and (0xE38)	0.2	-	-	V
DAC_OUT max	Higher DAC_OUT voltage with buffer		-	-	V _{DDA} -0.2	V
DAC_OUT min	Low DAC_OUT voltage without buffer	Maximum output offset of DAC	-	0.5	-	mV
DAC_OUT max	Higher DAC_OUT voltage without buffer		-	-	V _{REF+-1LSB}	V
DNL	Differential non-linear error	Configured with 12-bit DAC	-	-	±2	LSB
INL	Integral non-linear error	Configured with 12-bit DAC	-	-	±4	LSB
Offset	Offset error	V _{REF+} =3.6V, configuring 12-bit DAC	-	-	±12	LSB
Gain error	Gain error	Configured with 12-bit DAC	-	-	±0.5	%

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

6 Package Information

6.1 LQFP176 package information

Figure 17 LQFP176 Package Diagram



- (1) The figure is not drawn to scale.
- (2) All pins should be soldered to the PCB.

Table 54 LQFP176 Package Data

S/N	SYM	DIMENSIONS	REMARKS
1	A	MAX. 1.600	OVERALL HEIGHT
2	A2	1.400±0.050	PKG THICKNESS
3	D	26.000±0.200	LEAD TIP TO TIP
4	D1	24.000±0.100	PKG LENGTH
5	E	26.000±0.200	LEAD TIP TO TIP
6	E1	24.000±0.100	PKG WDTH
7	L	0.600±0.150	FOOT LENGTH
8	L1	1.000 REF	LEAD LENGTH
9	e	0.500 BASE	LEAD PITCH
10	H (REF)	(21.50)	CUM LEAD PITCH
11	b	0.22±0.050	LEAD WIDTH

Note: Dimensions are marked in millimeters.

Figure 18 LQFP176 -176 Pins, 24 x24mm Welding Layout Recommendations

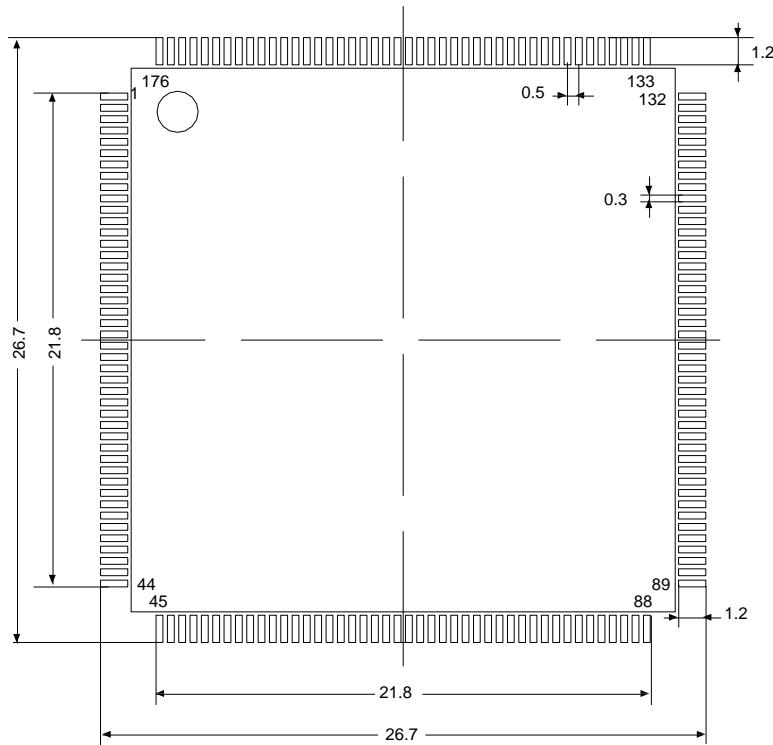
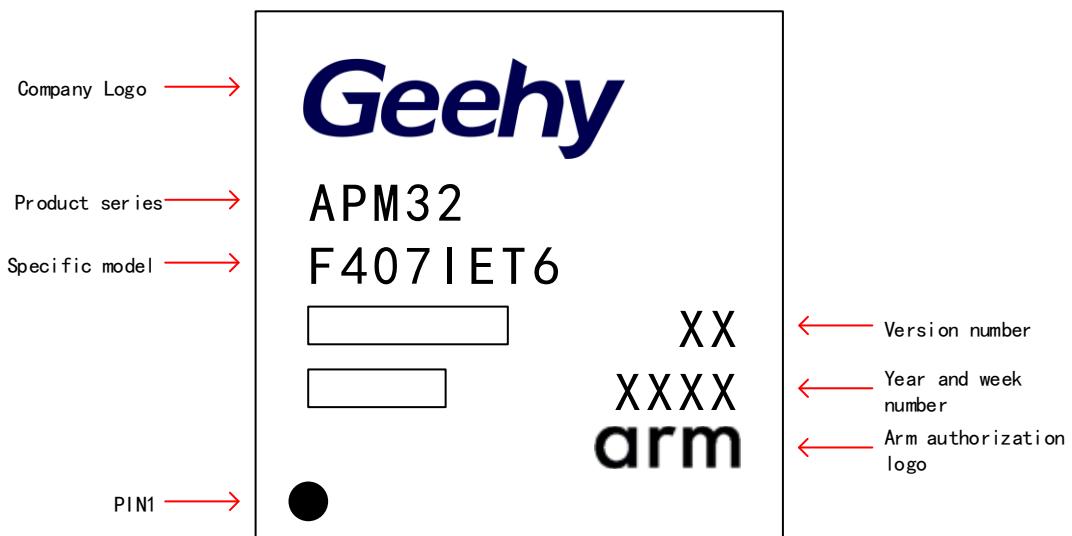
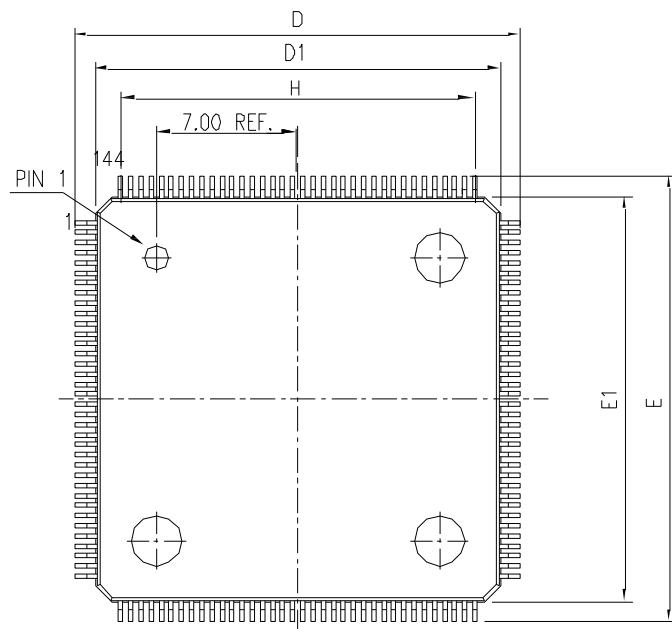


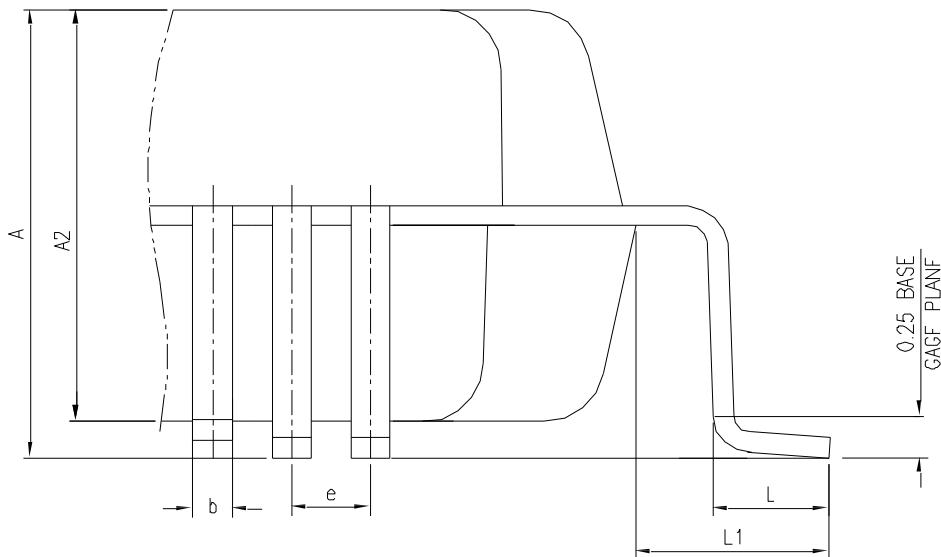
Figure 19 LQFP176 -176 Pins, 24 x24mm Schematic Diagram



6.2 LQFP144 package information

Figure 20 LQFP144 Package Diagram





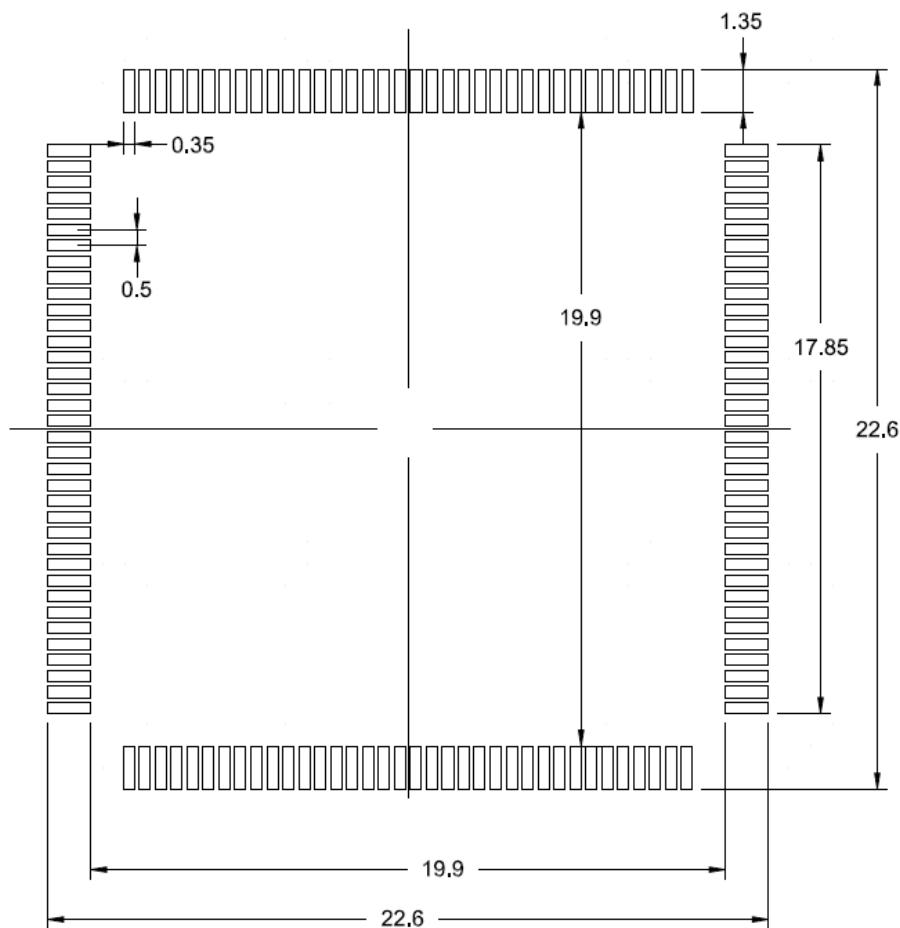
- (1) The figure is not drawn to scale.
- (2) All pins should be soldered to the PCB.

Table 55 LQFP144 Package Data

S/N	SYM	DIMENSIONS	REMARKS
1	A	MAX. 1.600	OVERALL HEIGHT
2	A2	1.400 ± 0.050	PKG THICKNESS
3	D	22.000 ± 0.200	LEAD TIP TO TIP
4	D1	20.000 ± 0.100	PKG LENGTH
5	E	22.000 ± 0.200	LEAD TIP TO TIP
6	E1	20.000 ± 0.100	PKG WDTH
7	L	0.600 ± 0.150	FOOT LENGTH
8	L1	1.000 REF	LEAD LENGTH
9	e	0.500 BASE	LEAD PITCH
10	H (REF)	(17.50)	CUM LEAD PITCH
11	b	0.22 ± 0.050	LEAD WIDTH

Note: Dimensions are marked in millimeters.

Figure 21 LQFP144-144 Pins, 20 x 20mm Welding Layout Recommendations



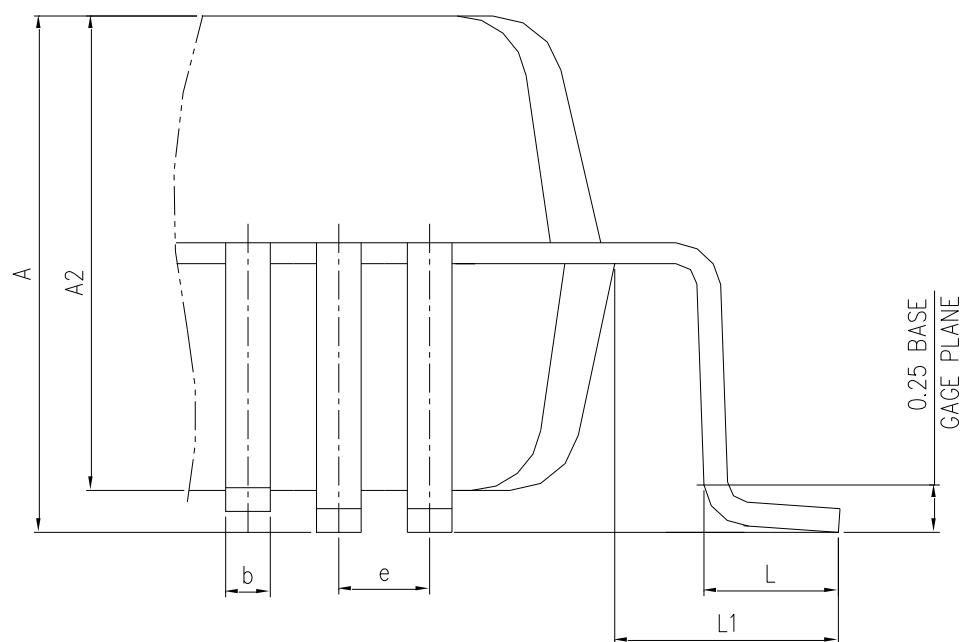
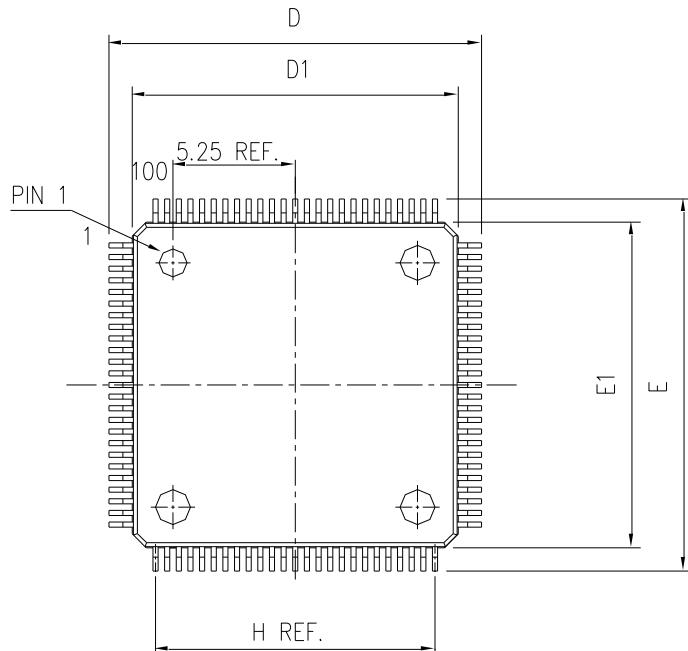
Note: Dimensions are marked in millimeters.

Figure 22 LQFP144 -144 Pins, 20 x20mm Schematic Diagram



6.3 LQFP100 package information

Figure 23 LQFP100 Package Diagram



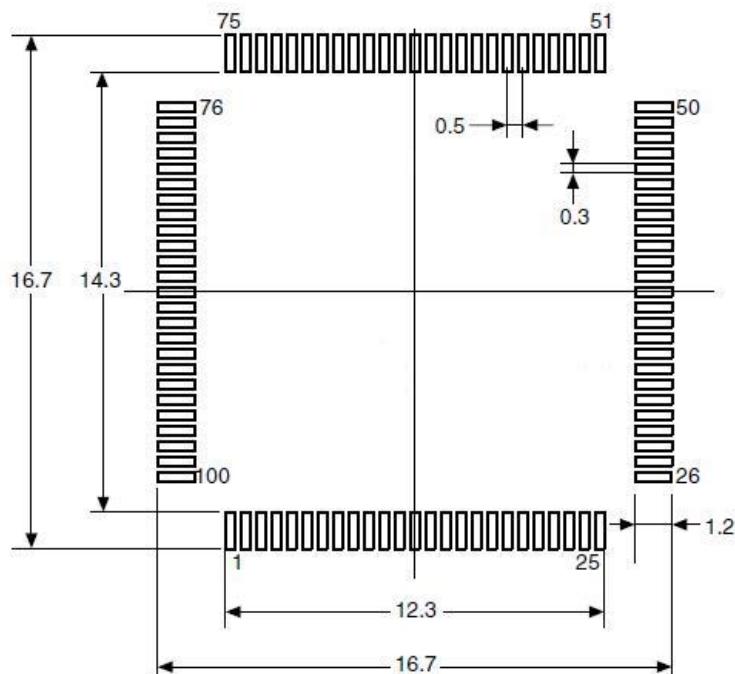
- (1) The figure is not drawn to scale.
- (2) All pins should be soldered to the PCB.

Table 56 LQFP100 Package Data

DIMENSION LIST (FOOTPRINT: 2.00)			
S/N	SYM	DIMENSIONS	REMARKS
1	A	MAX. 1.600	OVERALL HEIGHT
2	A2	1.400±0.050	PKG THICKNESS
3	D	16.000±0.200	LEAD TIP TO TIP
4	D1	14.000±0.100	PKG LENGTH
5	E	16.000±0.200	LEAD TIP TO TIP
6	E1	14.000±0.100	PKG WDTH
7	L	0.600±0.150	FOOT LENGTH
8	L1	1.000 REF	LEAD LENGTH
9	e	0.500 BASE	LEAD PITCH
10	H (REF)	(12.00)	CUM LEAD PITCH
11	b	0.22±0.050	LEAD WIDTH

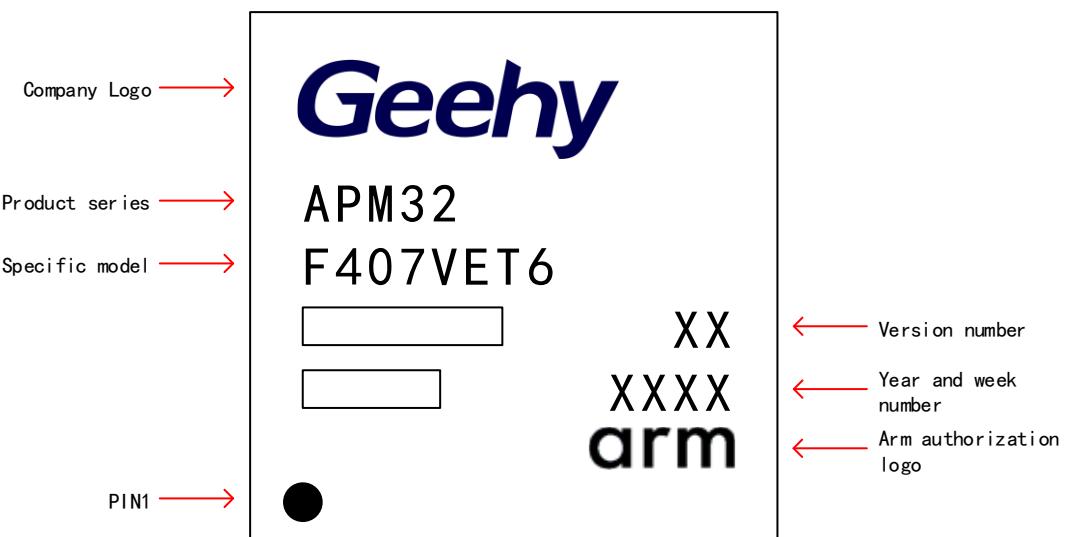
Note: Dimensions are marked in millimeters.

Figure 24 LQFP100 - 100 Pins, 14 x 14mm Welding Layout Recommendations



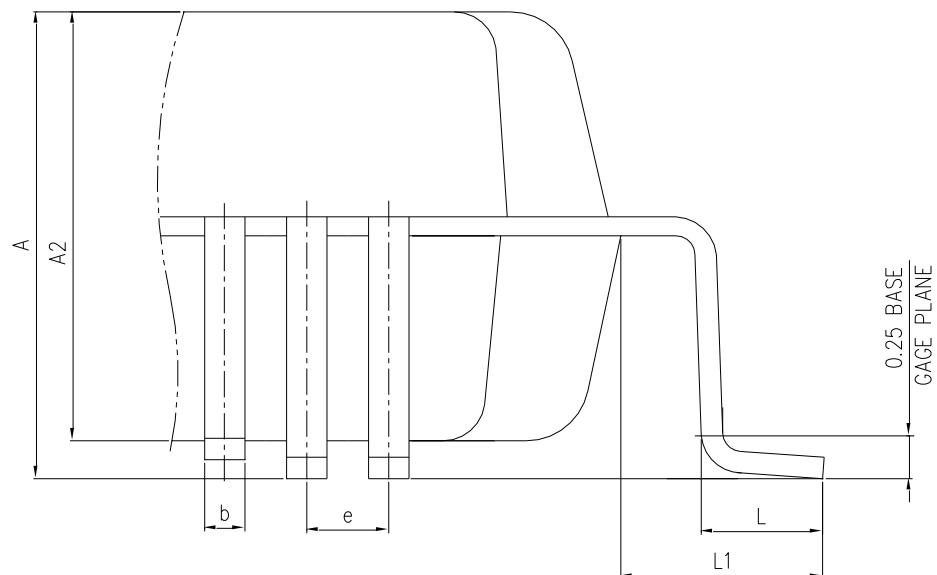
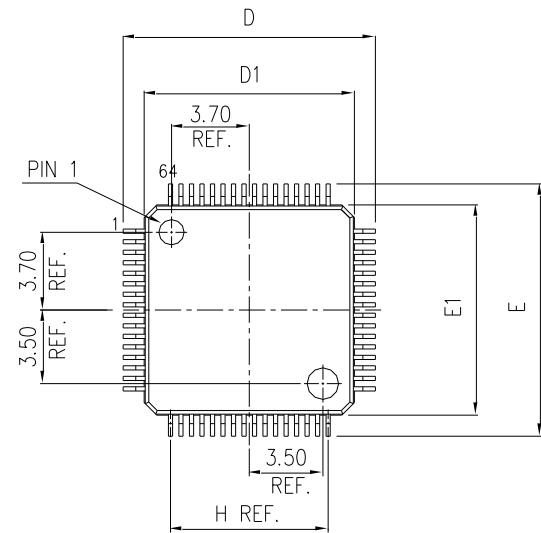
Note: Dimensions are marked in millimeters.

Figure 25 LQFP100 - 100 Pins, 14 x 14mm Package Schematic Diagram



6.4 LQFP64 package information

Figure 26 LQFP64 Package Diagram



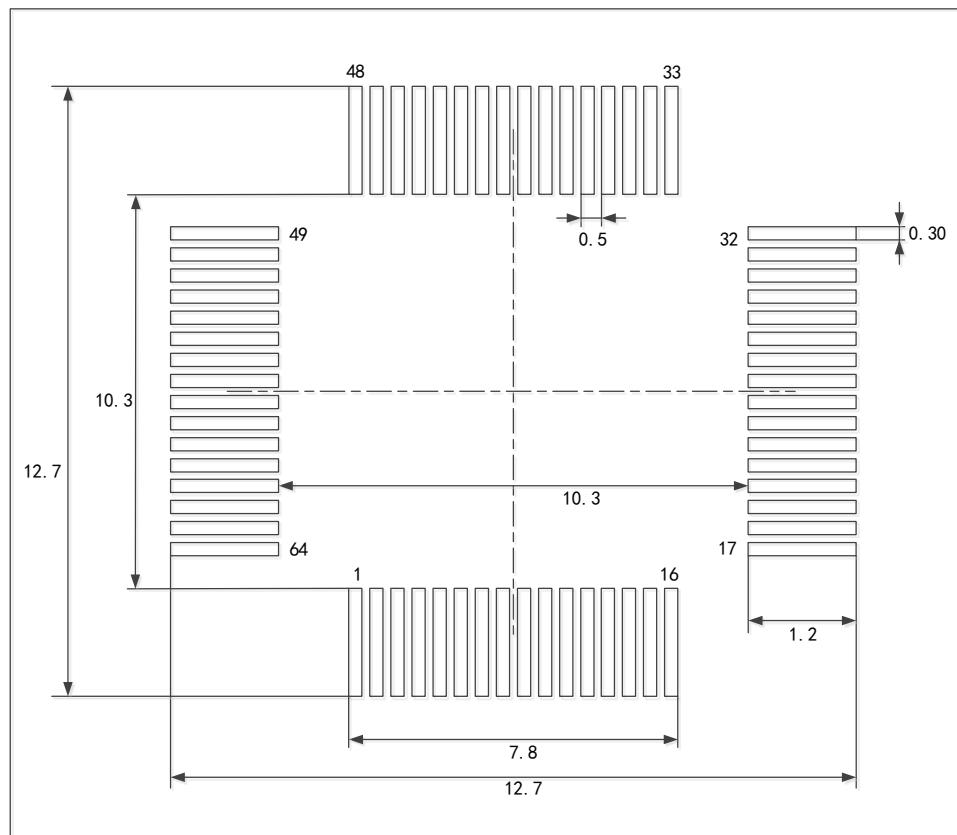
- (1) The figure is not drawn to scale.
- (2) All pins should be soldered to the PCB.

Table 57 LQFP64 Package Data

S/N	SYM	DIMENSIONS	REMARKS
1	A	MAX.1.600	OVERALLHEIGHT
2	A2	1.400±0.050	PKGTHICKNESS
3	D	12.000±0.200	LEADTIPTOTIP
4	D1	10.000±0.100	PKGLENGTH
5	E	12.000±0.200	LEADTIPTOTIP
6	E1	10.000±0.100	PKGWIDTH
7	L	0.600±0.150	FOOTLENGTH
8	L1	1.000REF.	LEADLENGTH
9	e	0.500BASE	LEADPITCH
10	H(REF.)	(7.500)	GUM.LEADPITCH
11	b	0.220±0.050	LEADWIDTH

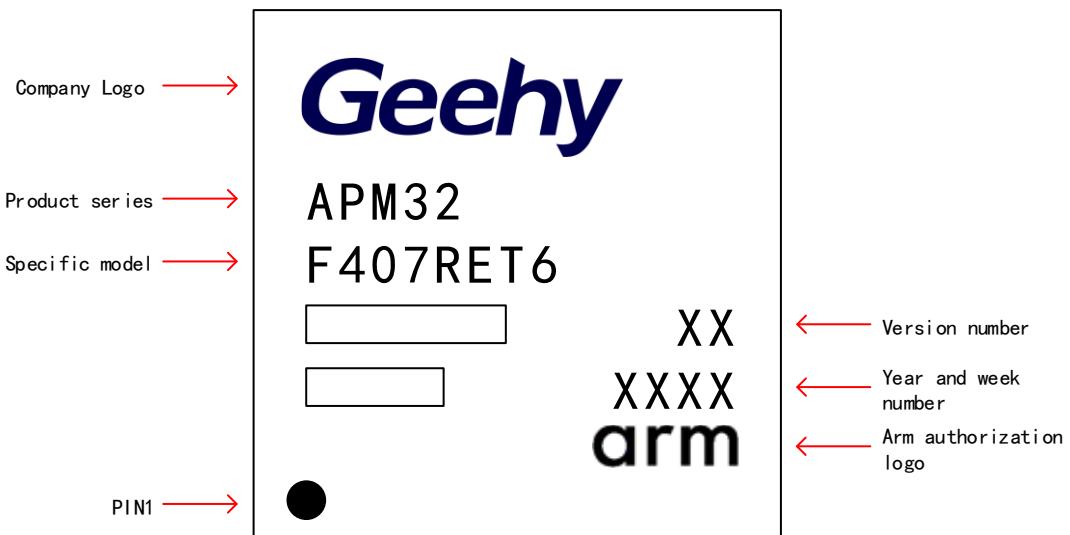
Note: Dimensions are marked in millimeters.

Figure 27 LQFP64 Welding Layout Recommendations



Note: Dimensions are marked in millimeters.

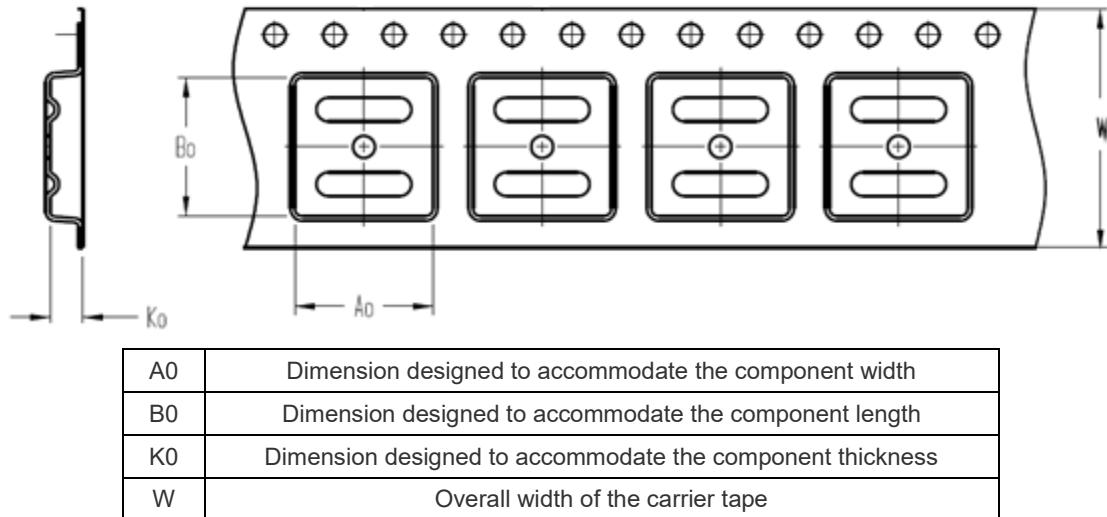
Figure 28 LQFP64 - 64 Pins, 10 x 10mm Package Schematic Diagram



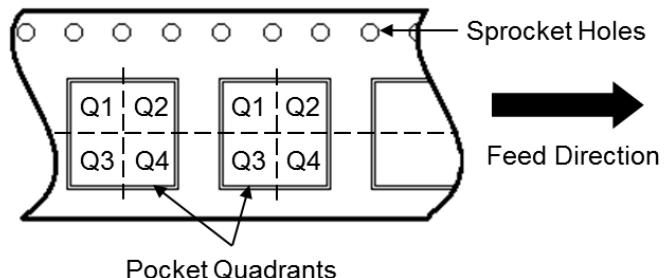
7 Packaging Information

7.1 Reel packaging

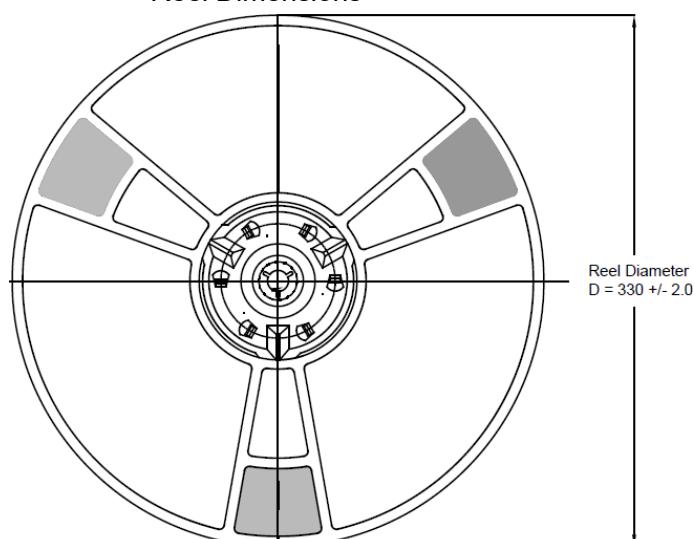
Figure 29 Specification Drawing of Reel Packaging



Quadrant Assignments for PIN1 Orientation in Tape



Reel Dimensions



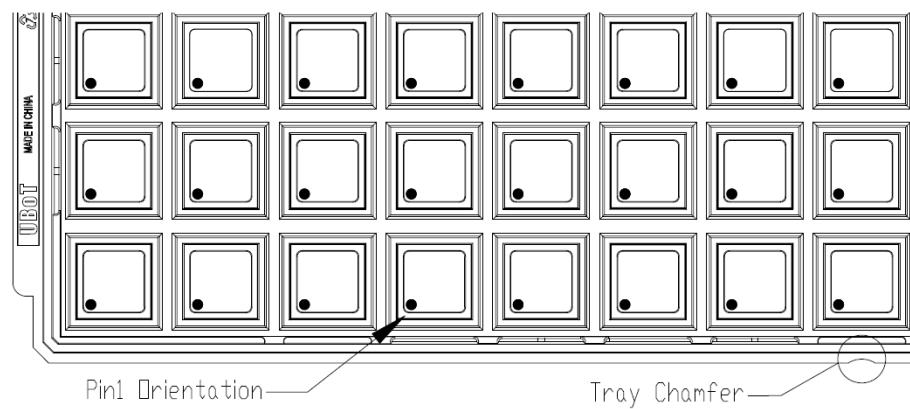
All photos are for reference only, and the appearance is subject to the product.

Table 58 Reel Packaging Parameter Specification Table

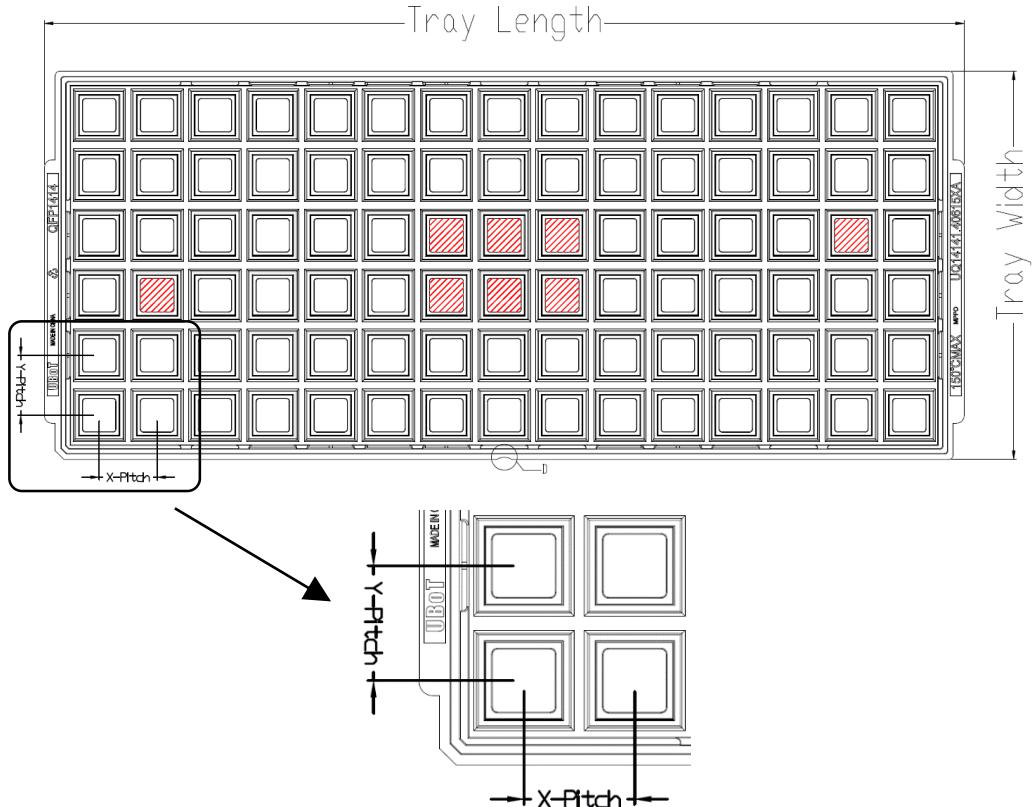
Device	Package Type	Pins	SPQ	Reel Diameter (mm)	A0 (mm)	B0 (mm)	K0 (mm)	W (mm)	Pin1 Quadrant
APM32F407RET6	LQFP	64	1000	330	12.35	12.35	2.2	24	Q1
APM32F407RGT6	LQFP	64	1000	330	12.35	12.35	2.2	24	Q1
APM32F405RGT6	LQFP	64	1000	330	12.35	12.35	2.2	24	Q1

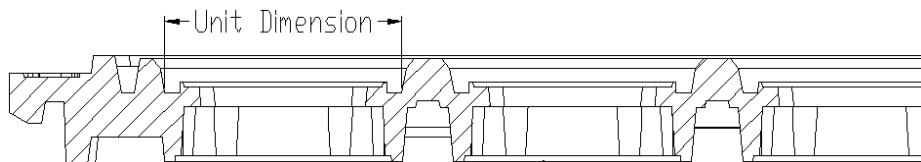
7.2 Tray packaging

Figure 30 Tray Packaging Diagram



Tray Dimensions





All photos are for reference only, and the appearance is subject to the product

Table 59 Tray Packaging Parameter Specification Table

Device	Package Type	Pins	SPQ	X-Dimension (mm)	Y-Dimension (mm)	X-Pitch (mm)	Y-Pitch (mm)	Tray Length (mm)	Tray Width (mm)
APM32F407IET6	LQFP	176	400	27	27	30.4	31.5	322.6	135.9
APM32F407IGT6	LQFP	176	400	27	27	30.4	31.5	322.6	135.9
APM32F407ZET6	LQFP	144	600	22.06	22.06	25.4	25.2	322.6	135.9
APM32F407ZGT6	LQFP	144	600	22.06	22.06	25.4	25.2	322.6	135.9
APM32F407VET6	LQFP	100	900	16.6	16.6	20.3	21	322.6	135.9
APM32F407VGT6	LQFP	100	900	16.6	16.6	20.3	21	322.6	135.9
APM32F407RET6	LQFP	64	1600	12.3	12.3	15.2	15.7	322.6	135.9
APM32F407RGT6	LQFP	64	1600	12.3	12.3	15.2	15.7	322.6	135.9
APM32F405ZGT6	LQFP	144	600	22.06	22.06	25.4	25.2	322.6	135.9
APM32F405VGT6	LQFP	100	900	16.6	16.6	20.3	21	322.6	135.9
APM32F405RGT6	LQFP	64	1600	12.3	12.3	15.2	15.7	322.6	135.9

8 Ordering Information

Figure 31 APM32F405xG 407xExG Series Ordering Information Diagram

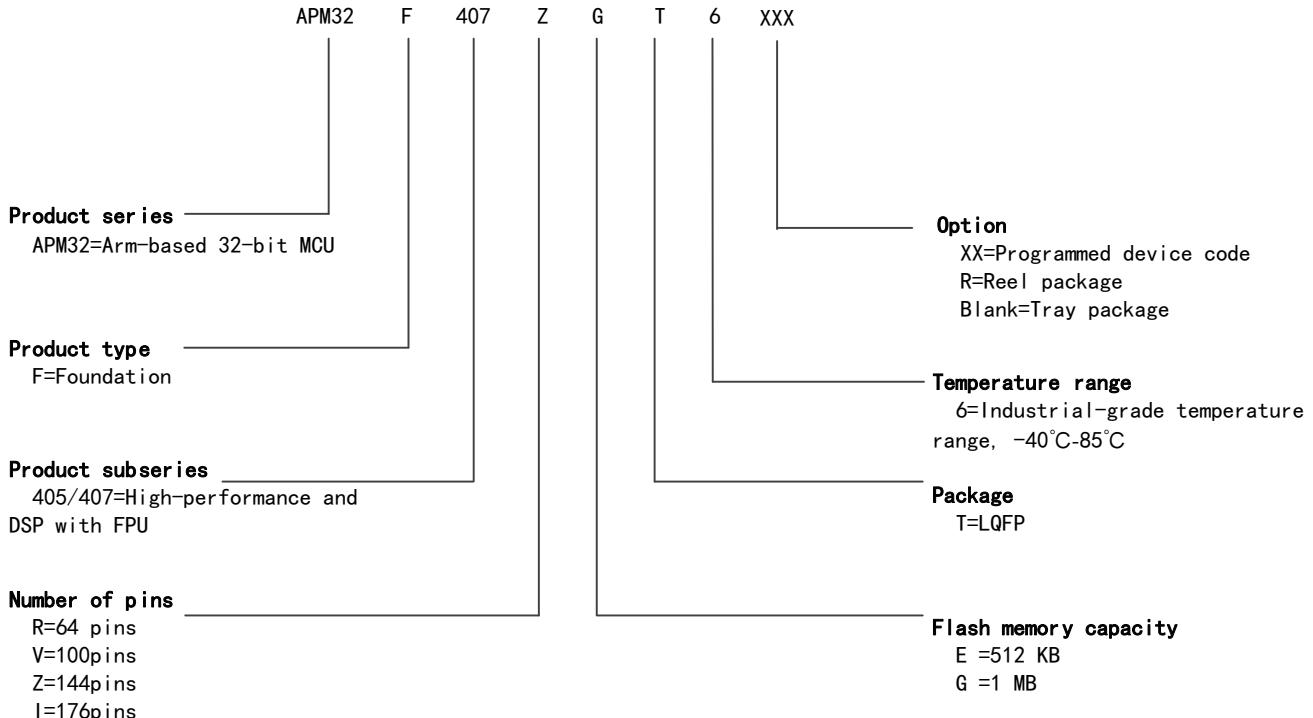


Table 60 Ordering Information Table

Order code	FLASH (KB)	SRAM (KB)	Package	SPQ	Range of temperature
APM32F407IGT6	1024	192+4	LQFP176	400	Industrial grade -40°C~85°C
APM32F407IET6	512	192+4	LQFP176	400	Industrial grade -40°C~85°C
APM32F407ZGT6	1024	192+4	LQFP144	600	Industrial grade -40°C~85°C
APM32F407ZET6	512	192+4	LQFP144	600	Industrial grade -40°C~85°C
APM32F407VGT6	1024	192+4	LQFP100	900	Industrial grade -40°C~85°C
APM32F407VET6	512	192+4	LQFP100	900	Industrial grade -40°C~85°C
APM32F407RGT6	1024	192+4	LQFP64	1600	Industrial grade -40°C~85°C
APM32F407RET6	512	192+4	LQFP64	1600	Industrial grade -40°C~85°C
APM32F407RGT6-R	1024	192+4	LQFP64	1000	Industrial grade -40°C~85°C
APM32F407RET6-R	512	192+4	LQFP64	1000	Industrial grade -40°C~85°C
APM32F405ZGT6	1024	192+4	LQFP144	600	Industrial grade -40°C~85°C
APM32F405VGT6	1024	192+4	LQFP100	900	Industrial grade -40°C~85°C
APM32F407RGT6	1024	192+4	LQFP64	1600	Industrial grade -40°C~85°C
APM32F405RGT6-R	1024	192+4	LQFP64	1000	Industrial grade -40°C~85°C

9 Commonly Used Function Module Denomination

Table 61 Commonly Used Function Module Denomination

Chinese description	Abbreviations
Reset management unit	RMU
Clock management unit	CMU
Reset and clock management	RCM
External interrupt	EINT
General-purpose IO	GPIO
Multiplexing IO	AFIO
Wake-up controller	WUPT
Buzzer	BUZZER
Independent watchdog timer	IWDT
Window watchdog timer	WWDT
Timer	TMR
CRC controller	CRC
Power Management Unit	PMU
DMA controller	DMA
Analog-to-digital converter	ADC
Real-time clock	RTC
External memory controller	EMMC
Controller local area network	CAN
I2C Interface	I2C
Serial peripheral interface	SPI
Universal asynchronous transmitter receiver	UART
Universal synchronous and asynchronous transmitter receiver	USART
Flash interface control unit	FMC

10 Version History

Table 62 Document Version History

Date	Version	Change History
2021.10	1.0	New creation
2022.4.1	1.1	(1) Modify pin definitions (2) The APM32F405xG model is added
2022.7.12	1.2	(1) Add 3.3 GPIO Multiplexing Function Configuration (2) Modify the Arm trademark (3) Add the statement (4) Add DMC pin description

Statement

This document is formulated and published by Geehy Semiconductor Co., Ltd. (hereinafter referred to as "Geehy"). The contents in this document are protected by laws and regulations of trademark, copyright and software copyright. Geehy reserves the right to make corrections and modifications to this document at any time. Please read this document carefully before using Geehy products. Once you use the Geehy product, it means that you (hereinafter referred to as the "users") have known and accepted all the contents of this document. Users shall use the Geehy product in accordance with relevant laws and regulations and the requirements of this document.

1. Ownership

This document can only be used in connection with the corresponding chip products or software products provided by Geehy. Without the prior permission of Geehy, no unit or individual may copy, transcribe, modify, edit or disseminate all or part of the contents of this document for any reason or in any form.

The "极海" or "Geehy" words or graphics with "®" or "™" in this document are trademarks of Geehy. Other product or service names displayed on Geehy products are the property of their respective owners.

2. No Intellectual Property License

Geehy owns all rights, ownership and intellectual property rights involved in this document.

Geehy shall not be deemed to grant the license or right of any intellectual property to users explicitly or implicitly due to the sale or distribution of Geehy products or this document.

If any third party's products, services or intellectual property are involved in this document, it shall not be deemed that Geehy authorizes users to use the aforesaid third party's products, services or intellectual property, unless otherwise agreed in sales order or sales contract.

3. Version Update

Users can obtain the latest document of the corresponding models when ordering Geehy products.

If the contents in this document are inconsistent with Geehy products, the agreement in the sales order or the sales contract shall prevail.

4. Information Reliability

The relevant data in this document are obtained from batch test by Geehy Laboratory or cooperative third-party testing organization. However, clerical errors in correction or errors caused by differences in testing environment may occur inevitably. Therefore, users should understand that Geehy does not bear any responsibility for such errors that may occur in this document. The relevant data in this document are only used to guide users as performance

parameter reference and do not constitute Geehy's guarantee for any product performance.

Users shall select appropriate Geehy products according to their own needs, and effectively verify and test the applicability of Geehy products to confirm that Geehy products meet their own needs, corresponding standards, safety or other reliability requirements. If losses are caused to users due to the user's failure to fully verify and test Geehy products, Geehy will not bear any responsibility.

5. Legality

USERS SHALL ABIDE BY ALL APPLICABLE LOCAL LAWS AND REGULATIONS WHEN USING THIS DOCUMENT AND THE MATCHING GEEHY PRODUCTS. USERS SHALL UNDERSTAND THAT THE PRODUCTS MAY BE RESTRICTED BY THE EXPORT, RE-EXPORT OR OTHER LAWS OF THE COUNTRIES OF THE PRODUCTS SUPPLIERS, GEEHY, GEEHY DISTRIBUTORS AND USERS. USERS (ON BEHALF OR ITSELF, SUBSIDIARIES AND AFFILIATED ENTERPRISES) SHALL AGREE AND PROMISE TO ABIDE BY ALL APPLICABLE LAWS AND REGULATIONS ON THE EXPORT AND RE-EXPORT OF GEEHY PRODUCTS AND/OR TECHNOLOGIES AND DIRECT PRODUCTS.

6. Disclaimer of Warranty

THIS DOCUMENT IS PROVIDED BY GEEHY "AS IS" AND THERE IS NO WARRANTY OF ANY KIND, EITHER EXPRESSED OR IMPLIED, INCLUDING, BUT NOT LIMITED TO, THE WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE, TO THE EXTENT PERMITTED BY APPLICABLE LAW.

GEEHY WILL BEAR NO RESPONSIBILITY FOR ANY DISPUTES ARISING FROM THE SUBSEQUENT DESIGN OR USE BY USERS.

7. Limitation of Liability

IN NO EVENT UNLESS REQUIRED BY APPLICABLE LAW OR AGREED TO IN WRITING WILL GEEHY OR ANY OTHER PARTY WHO PROVIDE THE DOCUMENT "AS IS", BE LIABLE FOR DAMAGES, INCLUDING ANY GENERAL, SPECIAL, DIRECT, INCIDENTAL OR CONSEQUENTIAL DAMAGES ARISING OUT OF THE USE OR INABILITY TO USE THE DOCUMENT (INCLUDING BUT NOT LIMITED TO LOSS OF DATA OR DATA BEING RENDERED INACCURATE OR LOSSES SUSTAINED BY USERS OR THIRD PARTIES).

8. Scope of Application

The information in this document replaces the information provided in all previous versions of the document.

© 2021-2022 Geehy Semiconductor Co., Ltd. - All Rights Reserved